

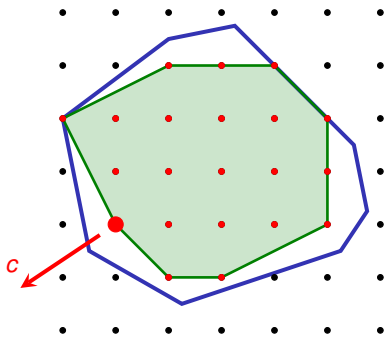
A Strongly Polynomial Algorithm for Bimodular Integer Programming

Rico Zenklusen

ETH Zurich

joint work with Stephan Artmann and Robert Weismantel

Toward general classes of efficiently solvable ILPs

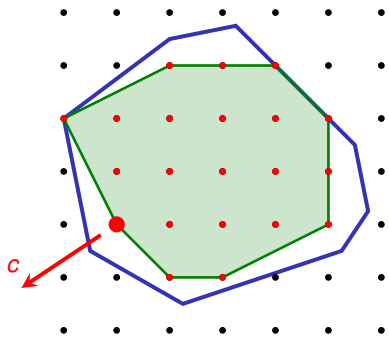


Integer Linear Program (ILP)

$$\max\{c^T x \mid Ax \leq b, x \in \mathbb{Z}^n\},$$

where $A \in \mathbb{Z}^{m \times n}$, $b \in \mathbb{Z}^m$, $c \in \mathbb{Z}^n$.

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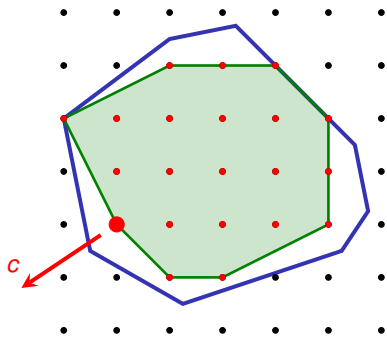
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Two classes of efficiently solvable ILPs

- ▶ If $n = O(1)$ or $m = O(1)$
→ Lenstra's Algorithm. (Lenstra [1983])
- ▶ If A is totally unimodular (TU)
→ Relaxation is naturally integral.

Toward general classes of efficiently solvable ILPs



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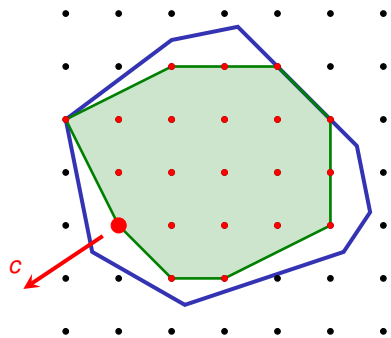
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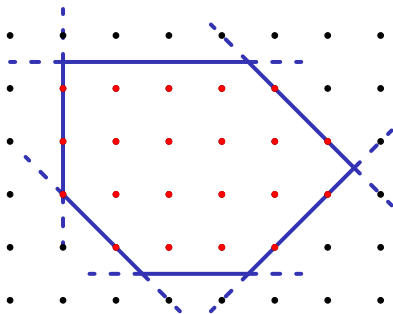
- ▶ One can show that for any $\epsilon > 0$, if minors are of order n^ϵ , then ILP gets NP-hard.
(see, e.g., Burch et al. [2003], Chestnut, Z. [2016])

Beyond TU-ness: Bimodular integer programs

Definition: Bimodular Integer Program (BIP)

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- (i) All $n \times n$ minors of A are $\in \{-2, -1, 0, 1, 2\}$.
- (ii) $\text{rank}(A) = n$.



$$\begin{pmatrix} 0 & -2 \\ 1 & -1 \\ 1 & 1 \\ 0 & 2 \\ -1 & 0 \\ -1 & -1 \end{pmatrix} \cdot \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \leq \begin{pmatrix} -1 \\ 4 \\ 9 \\ 9 \\ -1 \\ -3 \end{pmatrix}$$

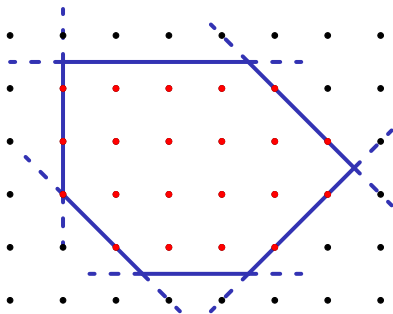
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Any ILPs s.t. all minors of A are $\in \{-2, -1, 0, 1, 2\}$ can easily be reduced to BIP.



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Theorem

AWZ [2017]

There is a strongly polynomial algorithm to solve BIP.

Some comments and gained insights

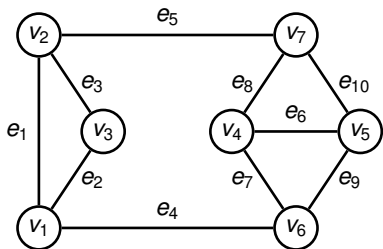
- ▶ BIP is equivalent to “parity-constrained TU ILPs”.
- ▶ We heavily use Seymour’s TU decomposition.
- ▶ Crucial role play parity-constrained combinatorial problems, like the T -cut problem.

A useful tool: parity-constrained submodular minimization

(Grötschel, Lovász, Schrijver [1981], Goemans and Ramakrishnan [1995]):

$$\min\{f(S) \mid S \subseteq N, |S| \text{ odd}\} .$$

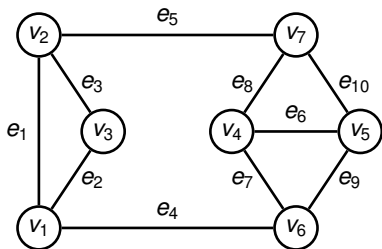
↑
submodular set function



$$M = \begin{matrix} & e_1 & e_2 & e_3 & e_4 & e_5 & e_6 & e_7 & e_8 & e_9 & e_{10} \\ \begin{matrix} v_1 \\ v_2 \\ v_3 \\ v_4 \\ v_5 \\ v_6 \\ v_7 \end{matrix} & \begin{pmatrix} 1 & 1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 & 1 \end{pmatrix} \end{matrix}$$

Largest minor of M in abs. value = $2^{\text{ocp}(G)}$, where $\text{ocp}(G)$ is odd cycle packing number.

If $\text{ocp}(G) = 1$, then M is tot. bimodular \rightarrow can efficiently find max weight stable set through BIP.



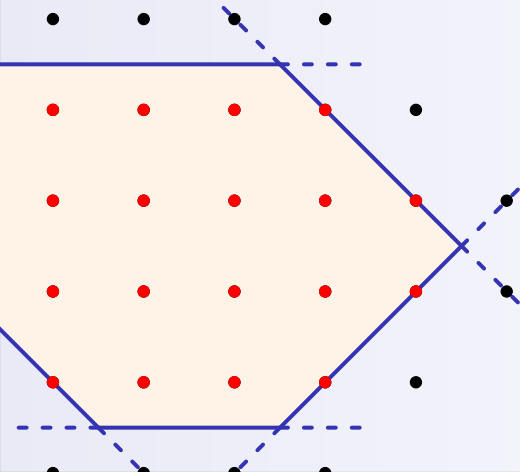
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Some optimization questions studied in context of minors

- ▶ Odd cycle packing number. Kawarabayashi & Reed [2010], Bock, Faenza, Moldenhauer & Ruiz-Vargas [2010]
- ▶ Diameter of polyhedra and efficient simplex-type algorithms. Bonifas, Di Summa, Eisenbrand, Hähnle & Niemeier [2014], Eisenbrand & Vempala [2017]
- ▶ Computing largest minor. Summa, Eisenbrand, Faenza & Moldenhauer [2015], Nikolov [2015]
- ▶ Efficient minimization of separable convex functions. Hochbaum & Shanthikumar [1990]



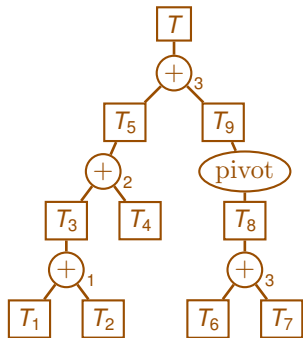
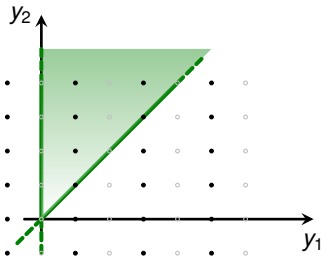
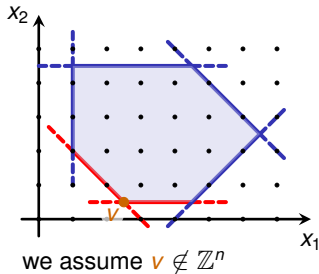
Our approach

Our approach on a high level

BIP

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where A is bimodular.



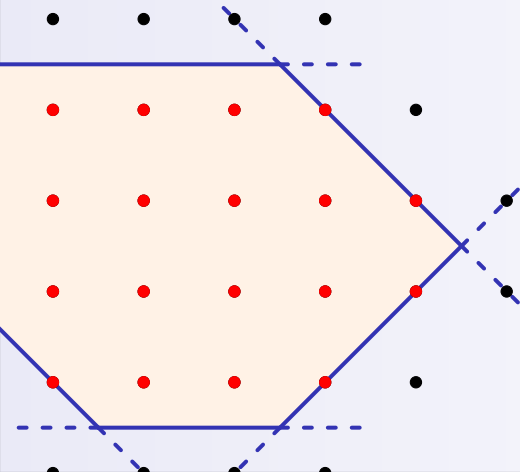
Conic parity TU problem (CPTU)

$$\max\{\tilde{c}^T y \mid Ty \leq 0, y \in \mathbb{Z}_{\geq 0}^n, y(S) \text{ odd}\},$$

where T is TU, and $S \subseteq [n]$.

Seymour's TU decomposition

- ▶ Decompose T into base blocks (leaves).
- ▶ Solve CPTU by solving CPTUs on base blocks and propagating solutions up.



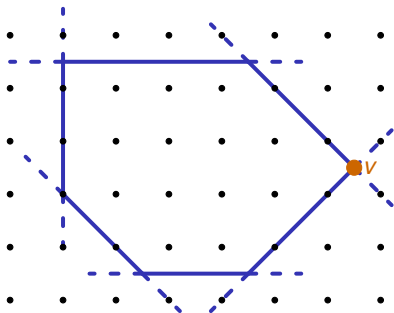
From BIP to CPTU

Theorem

Veselov and Chirkov [2009]

Let $\max\{c^T x \mid Ax \leq b, x \in \mathbb{Z}^n\}$ be a BIP, $P = \{x \in \mathbb{R}^n \mid Ax \leq b\}$, $v \in \text{vertices}(P)$, and let $\bar{A}x \leq \bar{b}$ be the v -tight subsystem of $Ax \leq b$.

Then each vertex of $C = \text{conv}(\{x \in \mathbb{Z}^n \mid \bar{A}x \leq \bar{b}\})$ lies on an edge of P .



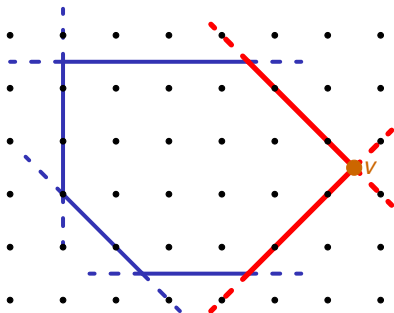
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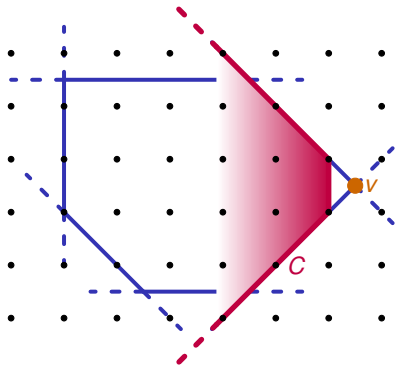
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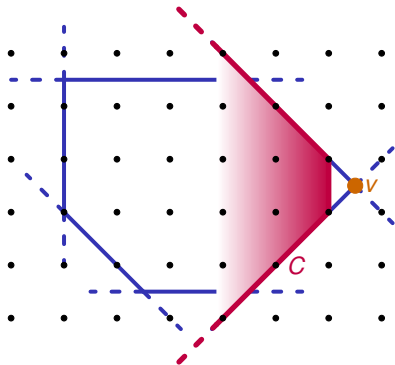
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- All vertices of C are feasible for BIP.
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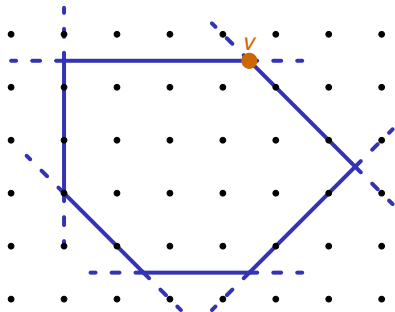
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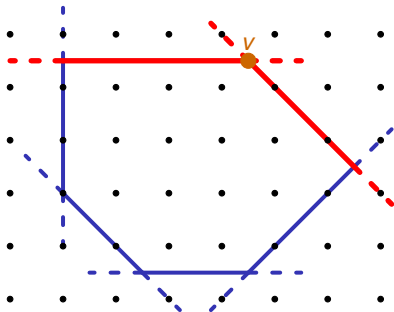
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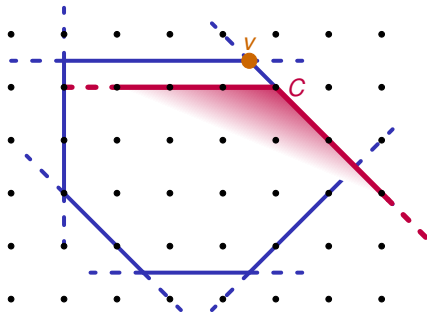
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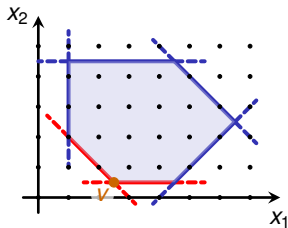
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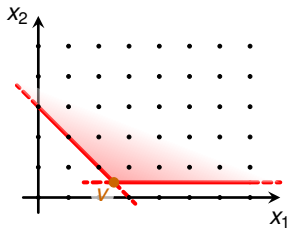
$$y = Q \cdot (x - v)$$

$$\max\{c^T x \mid Ax \leq b, x \in \mathbb{Z}^n\} = \max\{c^T Q^{-1} y \mid \bar{A}Q^{-1} y \leq 0, Q^{-1}(b_Q + y) \in \mathbb{Z}^n\}$$



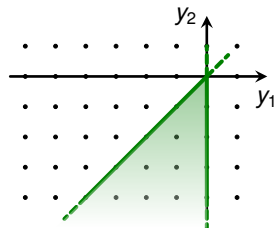
$$\underbrace{\begin{pmatrix} \boxed{\bar{A}} \end{pmatrix}}_A \cdot x \leq \underbrace{\begin{pmatrix} \boxed{\bar{b}} \end{pmatrix}}_b$$

tight constraints
 $\bar{A} \cdot v = \bar{b}$



$$\underbrace{\begin{pmatrix} \boxed{Q} \end{pmatrix}}_{\bar{A}} \cdot x \leq \underbrace{\begin{pmatrix} \boxed{b_Q} \end{pmatrix}}_{\bar{b}}$$

full-rank square submatrix Q



$$\underbrace{\begin{pmatrix} \boxed{\text{Id}} \end{pmatrix}}_{\bar{A}Q^{-1} =: T} \cdot y \leq 0$$

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$$\max\{\tilde{c}^T y \mid Ty \leq 0, Q^{-1}(b_Q + y) \in \mathbb{Z}^n\} = \max\{\tilde{c}^T y \mid Ty \leq 0, Q^{-1}(b_Q + y) \in \mathbb{Z}^n, y \in \mathbb{Z}^n\}$$

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Question

Given $w \in \mathbb{Z}^n$, when do we have $Q^{-1}w \in \mathbb{Z}^n$, where $Q \in \mathbb{Z}^{n \times n}$ with $\det Q \in \{-2, 2\}$?

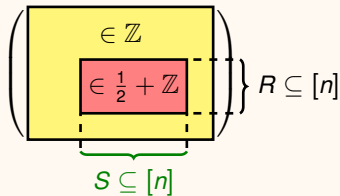
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Up to row and column permutations, Q^{-1} looks as follows: $Q^{-1} =$



$$\Rightarrow Q^{-1}w \in \mathbb{Z}^n \Leftrightarrow w(S) \text{ is even.}$$

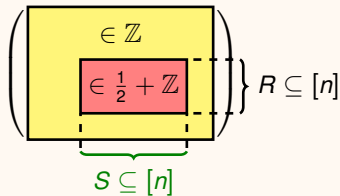
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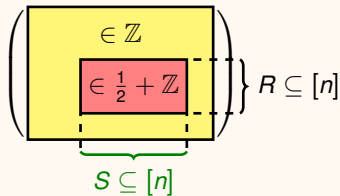
$$\begin{aligned} \max\{\tilde{c}^T y \mid Ty \leq 0, Q^{-1}(b_Q + y) \in \mathbb{Z}^n\} &= \max\{\tilde{c}^T y \mid Ty \leq 0, Q^{-1}(b_Q + y) \in \mathbb{Z}^n, y \in \mathbb{Z}^n\} \\ &= \max\{\tilde{c}^T y \mid Ty \leq 0, y(\mathbf{S}) \text{ odd}, y \in \mathbb{Z}^n\} \end{aligned}$$

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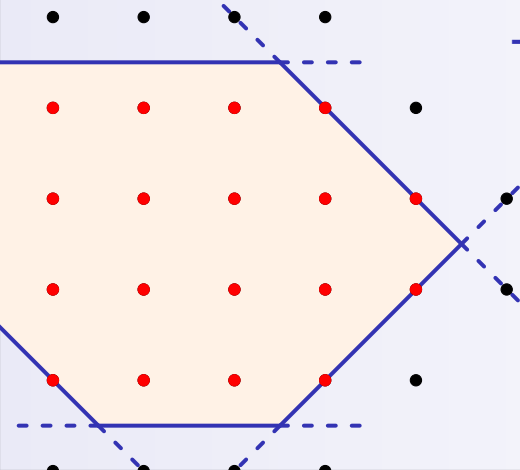
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Toward simpler combinatorial
problems via Seymour's
TU decomposition

Seymour's TU decomposition (I)

Any TU matrix can be constructed from 3 basic types of TU matrices:

- (i) Network matrices (gen. of incidence matrices),
- (ii) transposes of network matrices,
- (iii) the following two matrices:

$$\begin{pmatrix} 1 & -1 & 0 & 0 & -1 \\ -1 & 1 & -1 & 0 & 0 \\ 0 & -1 & 1 & -1 & 0 \\ 0 & 0 & -1 & 1 & -1 \\ -1 & 0 & 0 & -1 & 1 \end{pmatrix}, \begin{pmatrix} 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 1 & 0 \\ 1 & 0 & 0 & 1 & 1 \\ 1 & 1 & 0 & 0 & 1 \end{pmatrix}$$

using the following operations:

- ▶ 1-sum: $L \oplus_1 R = \begin{bmatrix} L & 0 \\ 0 & R \end{bmatrix}$,
- ▶ 2-sum: $\begin{bmatrix} L & a \end{bmatrix} \oplus_2 \begin{bmatrix} d^T \\ R \end{bmatrix} = \begin{bmatrix} L & ad^T \\ 0 & R \end{bmatrix}$, and
- ▶ 3-sum: $\begin{bmatrix} L & a & a \\ f^T & 0 & 1 \end{bmatrix} \oplus_3 \begin{bmatrix} 1 & 0 & d^T \\ g & g & R \end{bmatrix} = \begin{bmatrix} L & ad^T \\ gf^T & R \end{bmatrix}$,

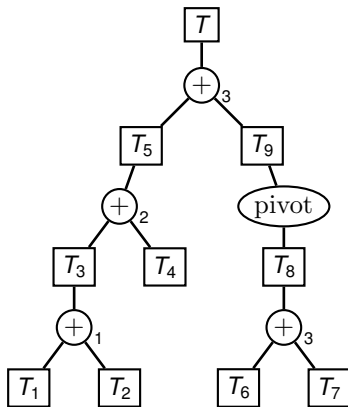
where $\text{rows}(L) + \text{cols}(L) \geq 4$ and $\text{rows}(R) + \text{cols}(R) \geq 4$.

- ▶ permuting rows/columns,
- ▶ adding a row/column with at most 1 nonzero entry,
- ▶ negating a row/column,
- ▶ doubling a row/column,
- ▶ pivoting (think of simplex pivoting).

Seymour's TU decomposition (II)

We slightly tweak Seymour's TU decomposition to get additional properties.

Key operations that have to be considered: 1-sums, 2-sums, 3-sums, and pivots.

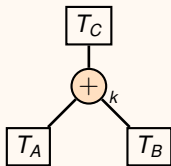


Using Seymour's decomposition to solve CPTU

CPTU problem: $\max\{c^T x \mid Tx \leq 0, x(S) \text{ odd}, x \in \mathbb{Z}_{\geq 0}^n\}$.

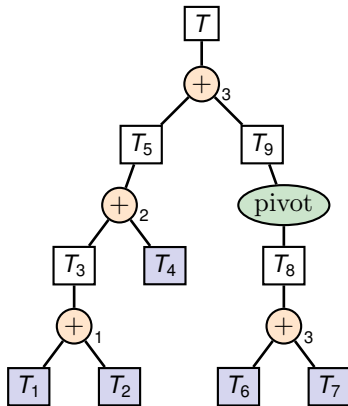
k-sums for $k \in \{1, 2, 3\}$

Efficient algo for CPTU wrt T_A, T_B implies efficient algo for CPTU wrt T_C .



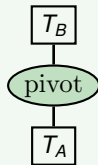
Base blocks

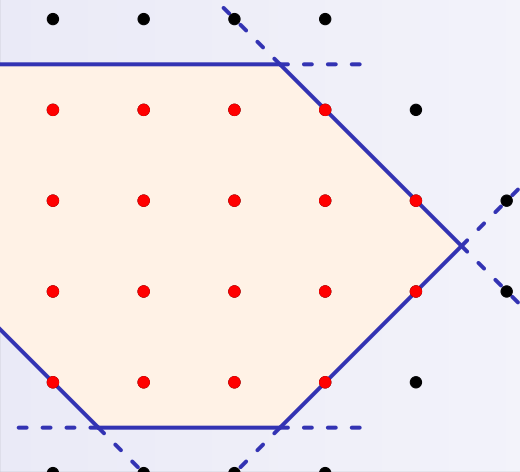
We can solve any CPTU for any base block matrix.



Pivots

Efficient algo for CPTU wrt T_A implies efficient algo for CPTU wrt T_B .





Propagation aspects on
the example of 2-sums

CPTU: $\max\{c^T x \mid Tx \leq 0, x(S) \text{ odd}, x \in \mathbb{Z}_{\geq 0}^n\}$

Assume T can be written as a 2-sum:

$$T = \begin{pmatrix} \underbrace{L}_{S_L} & ab^T \\ \hline \underbrace{0}_{S_L} & \underbrace{R}_{S_R} \end{pmatrix} = (L \ a) \oplus_2 \begin{pmatrix} b^T \\ R \end{pmatrix}$$

$S = S_L \dot{\cup} S_R$

Lemma

AWZ [2017]

\exists opt. sol. $x^* = \begin{pmatrix} x_L^* \\ x_R^* \end{pmatrix}$ to CPTU wrt T such that $b^T x_R^* \in \{-1, 0, 1\}$.

In what follows, assume $\text{rows}(R) \leq \text{rows}(L)$.

Assume you are given x_R^* with $b^T x_R^* \in \{-1, 0, 1\}$. All one has to know to determine x_L^* is:

- (i) value of $b^T x_R^* \in \{-1, 0, 1\}$, and
- (ii) parity of $x_R(S_R) \in \{\text{even}, \text{odd}\}$.

For each of the 6 combinations of (i) and (ii) we construct an optimal x_R^* .

$$T = \left(\begin{array}{c|c} L & ab^T \\ \hline 0 & R \end{array} \right) = (L \ a) \oplus_2 \left(\begin{array}{c} b^T \\ R \end{array} \right)$$

$S = S_L \dot{\cup} S_R$

For $\alpha \in \{-1, 0, 1\}$ and $\beta \in \{0, 1\}$, we compute:

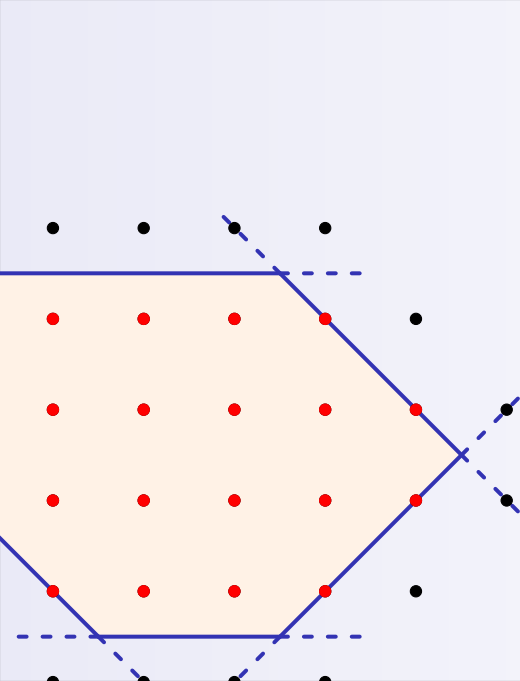
$$\rho(\gamma, \delta) := \max\{c_R^T x_R \mid R \cdot x_R \leq 0, b^T x_R = \alpha, x_R(S_R) \equiv \beta \pmod{2}, x_R \in \mathbb{Z}_{\geq 0}^{n_R}\}.$$

We incorporate these options into a problem involving L . We set:

J : components with $\beta = 1$

$$\begin{array}{l} (\alpha, \beta): \quad \quad \quad (-1, 0) \quad (0, 0) \quad (1, 0) \quad (-1, 1) \quad (0, 1) \quad (1, 1) \\ \bar{L} = \left[\begin{array}{c|ccc} L & -a & 0 & a \\ \hline c_L^T & \rho(-1, 0) & \rho(0, 0) & \rho(1, 0) \end{array} \right] \quad \left[\begin{array}{ccc} -a & 0 & a \\ \rho(-1, 1) & \rho(0, 1) & \rho(1, 1) \end{array} \right] \end{array}$$

Combined problem to find x_L^* : $\max\{\bar{c}^T x \mid \bar{L}x \leq 0, x \in \mathbb{Z}_{\geq 0}^{n_L+6}, x(S_L \cup J) \text{ odd}\}$



Conclusions

Our main result

- ▶ BIPs are efficiently solvable (even in strongly poly time).

Some natural open questions (...and things I am interested in)

- ▶ Recognition of bimodular matrices?
- ▶ Solve k -modular ILPs for $k = O(1)$, or even just determine feasibility?
- ▶ Reduction of k -modular ILP to modular optimization, e.g., TU problem with $x(S) \equiv 1 \pmod{k}$?
- ▶ Different approach to solve BIP not based on TU decomposition?
- ▶ Derive additional structural properties of k -modular matrices.