

# Active Nearest Neighbors in Changing Environments

**Ruth Urner**



MAX-PLANCK-GESELLSCHAFT

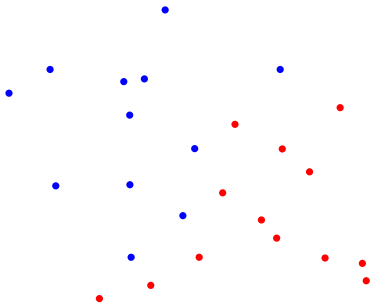
MPI for Intelligent Systems, Tübingen

February 16, 2017

# Active Learning for Domain Adaptation

## Phenomenon:

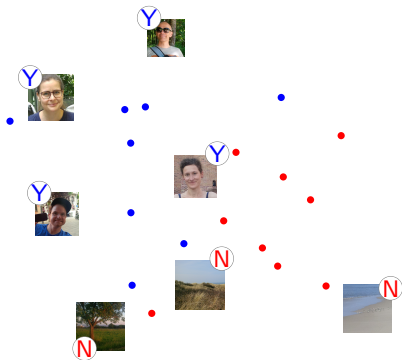
Data generation may change



# Active Learning for Domain Adaptation

## Phenomenon:

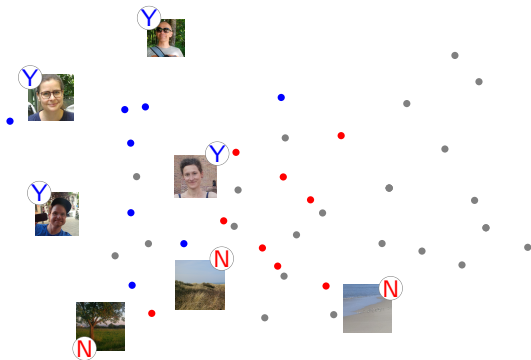
Data generation may change



# Active Learning for Domain Adaptation

## Phenomenon:

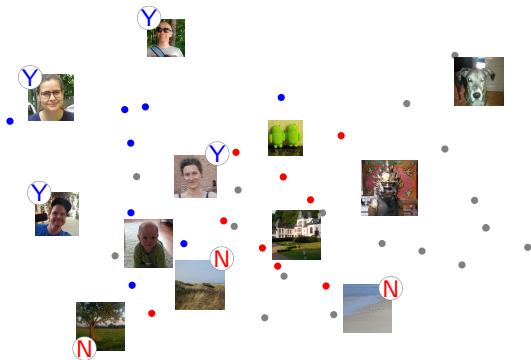
Data generation may change



# Active Learning for Domain Adaptation

## Phenomenon:

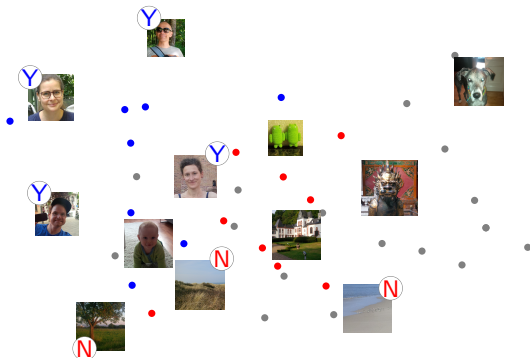
Data generation may change



# Active Learning for Domain Adaptation

## Phenomenon:

Data generation may change



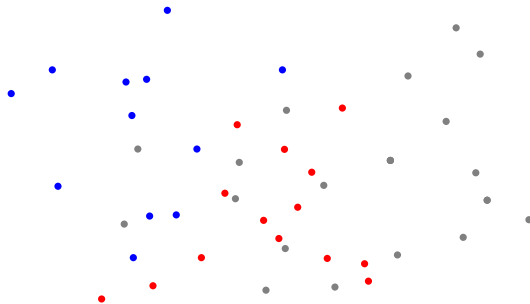
## Berlind, U., ICML '15:

- Developed new learning method ANDA
- **Idea:** use active learning to adapt to distributional shift
- Error bounds on shifted task
- Bounds on number of label queries

# Active Nearest Neighbors in Changing Environments

Algorithm **ANDA**:

Nearest Neighbor query rule + Nearest Neighbor prediction

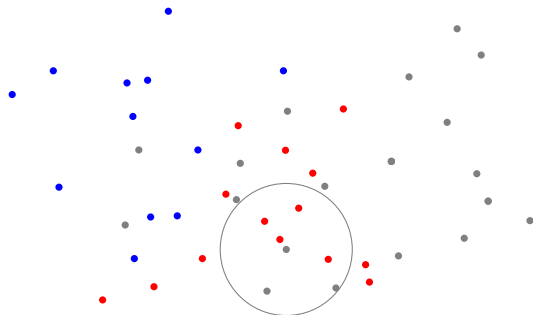


**Input:** Labeled source data and unlabeled target data

# Active Nearest Neighbors in Changing Environments

Algorithm **ANDA**:

Nearest Neighbor query rule + Nearest Neighbor prediction



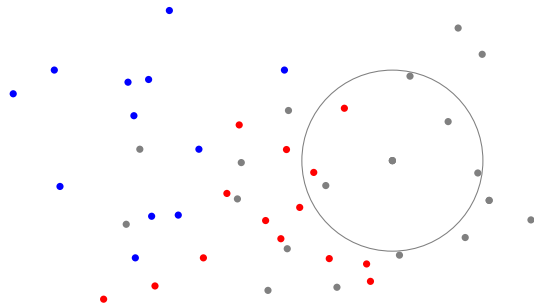
**$(k, k')$ -query rule:** don't query!



# Active Nearest Neighbors in Changing Environments

Algorithm **ANDA**:

Nearest Neighbor query rule + Nearest Neighbor prediction



$(k, k')$ -query rule: query!

## $(k, k')$ -Nearest Neighbor Cover

$T \subseteq \mathcal{X}$ ,  $T$  finite

$k, k' \in \mathbb{N}$  with  $k \leq k'$

A set  $R$  is a  $(k, k')$ -NN-cover for  $T$ , if for every  $x \in T$ , either  $x \in R$  or there are  $k$  elements from  $R$  among the  $k'$  nearest neighbors of  $x$  in  $T \cup R$ , that is  $|k'(x, T \cup R) \cap R| \geq k$ .

**input:** Labeled set  $S$ , unlabeled set  $T$ , parameters  $k, k'$

- Find  $T' \subseteq T$  s.t.  $S \cup T'$  is a  $(k, k')$ -NN-cover of  $T$
- **Query** the labels of points in  $T'$

**output:**  $h_{S \cup T'}^k$ , the  $k$ -NN classifier on  $S \cup T'$

## Lemma

Let  $T$  be a finite set of points in a metric space  $(\mathcal{X}, \rho)$  and let  $R$  be a  $(k, k')$ -NN-cover for  $T$ . Then, for all  $x \in \mathcal{X}$  we have

$$\rho(x, x_k(x, R)) \leq 3\rho(x, x_{k'+1}(x, T))$$

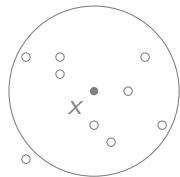
$\Rightarrow$  For every  $x$ : the distance to the  $k$  nearest labels is at most 3 times the distance to the  $k' + 1$  nearest target points!

## Proof of Lemma

For every  $x$ : the distance to the  $k$  nearest labels is at most 3 times the distance to the  $k' + 1$  nearest target points.

# Proof of Lemma

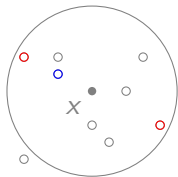
For every  $x$ : the distance to the  $k$  nearest labels is at most 3 times the distance to the  $k' + 1$  nearest target points.



- Let  $x \in \mathcal{X}$
- Consider  $k'$  nearest neighbors in  $T$

# Proof of Lemma

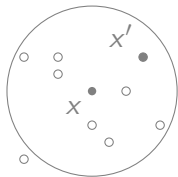
For every  $x$ : the distance to the  $k$  nearest labels is at most 3 times the distance to the  $k' + 1$  nearest target points.



- Let  $x \in \mathcal{X}$
- Consider  $k'$  nearest neighbors in  $\mathcal{T}$
- If they contain  $k$  labels  $\Rightarrow$  done!

# Proof of Lemma

For every  $x$ : the distance to the  $k$  nearest labels is at most 3 times the distance to the  $k' + 1$  nearest target points.

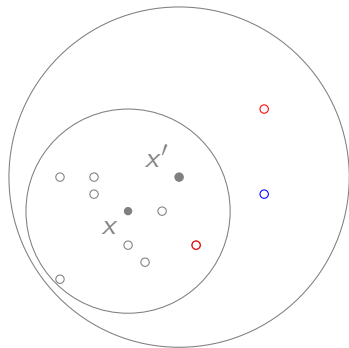


- Let  $x \in \mathcal{X}$
- Consider  $k'$  nearest neighbors in  $\mathcal{T}$
- If they contain  $k$  labels  $\Rightarrow$  done!
- Else let  $x'$  be unlabeled



# Proof of Lemma

For every  $x$ : the distance to the  $k$  nearest labels is at most 3 times the distance to the  $k' + 1$  nearest target points.



- Let  $x \in \mathcal{X}$
- Consider  $k'$  nearest neighbors in  $T$
- If they contain  $k$  labels  $\Rightarrow$  done!
- Else let  $x'$  be unlabeled
- Since  $x'$  in  $T$ ,  $x'$  has to be covered!

## Error bound

Let  $(\mathcal{X}, \rho)$  be a metric space and let  $P_T$  be a (target) distribution over  $\mathcal{X} \times \{0, 1\}$  with  $\lambda$ -Lipschitz regression function  $\eta$ . Then for all  $k' \geq k \geq 10$ , all  $\epsilon > 0$ , and any unlabeled sample size  $m_T$  and labeled sequence  $S = ((x_1, y_1), \dots, (x_{m_S}, y_{m_S}))$  with labels  $y_i$  generated by  $\eta$ ,

$$\begin{aligned} & \mathbb{E}_{T \sim P_T^{m_T}} [\mathcal{L}_T(\text{ANDA}(S, T, k, k'))] \\ & \leq \left(1 + \sqrt{\frac{8}{k}}\right) \mathcal{L}_T(h^*) + 9\lambda\epsilon + \frac{2N_\epsilon(\mathcal{X}, \rho) k'}{m_T}. \end{aligned}$$

**Correctness** of ANDA does not depend on relatedness assumptions  
of source and target marginals

However, the **number of queries** ANDA makes does depend on a local relatedness measure.

However, the **number of queries** ANDA makes does depend on a local relatedness measure.

Define weight ratio of  $B \subseteq \mathcal{X}$ :

$$\beta(B) := D_S(B)/D_T(B)$$

## Query bound

Let  $\delta > 0$ ,  $w > 0$  and  $C > 1$ . Let  $m_T$  be some target sample size with  $m_T > k' = (C + 1)k$  for some  $k$  that satisfies  $k \geq 9(\text{VC}(\mathcal{B}) \ln(2m_T) + \ln(6/\delta))$ . Let the source sample size satisfy

$$m_S \geq \frac{36 \ln(6/\delta) m_T}{C w} \ln \left( \frac{9 m_T}{C w} \right)$$

Then, with probability at least  $1 - 2\delta$  over samples  $S$  of size  $m_S$  (*i.i.d.* from  $P_S$ ) and  $T$  of size  $m_T$  (*i.i.d.* from  $D_T$ ), **ANDA-S** on input  $S, T, k, k'$  will not query any points  $x \in T$  with  $\beta(B_{Ck, T}(x)) > w$ .

Query bound provides fall-back guarantee for the lucky case:  
If source and target are the same (or very similar/have bounded weight ratio) ANDA will not query at all.

## Query consistency

For a fixed target sample size, we show that in the limit of large source samples, ANDA **will not make any queries** in the support of the source distribution.



## Lower bound

- **Error bound** in terms of Lipschitzness  $\lambda$  and covering numbers  $N_{1/\lambda}$
- **Query guarantee** no queries in source covered area  $\mathcal{X}_S \cap \mathcal{X}_T$

Define **source coverage** of task:  $\nu = D_T(\mathcal{X}_S \cap \mathcal{X}_T)$

$\mathcal{C}_\lambda^\nu$ : DA tasks with source coverage  $\nu$  and Lipschitzness  $\lambda$

## Lower bound

Let  $(\mathcal{X}, \rho)$  be a metric space,  $\nu \in [0, 1]$ , and  $\lambda > 0$ . Then for every DA learning algorithm  $\mathcal{A}$ , every source sample size  $m_S$  and target sample size  $m_T$ , if  $\mathcal{A}$  is restricted to making fewer than

$$q = \frac{\lfloor (1 - \nu) Q_{\frac{1}{\lambda}}(\mathcal{X}, \rho) \rfloor}{2}$$

label queries, then there exists a pair of distribution  $(P_S, P_T) \in \mathcal{C}_\lambda^\nu$  such that

$$\mathbb{E}_{S \sim P_S^{m_S}, T \sim D_T^{m_T}} [\mathcal{L}_T(\mathcal{A}(S, T))] \geq \frac{1}{4} D_T(\mathcal{X}_T \setminus \mathcal{X}_S)$$

# Active learning is beneficial to Domain Adaptation

## **Corollary**

No DA learner with a fixed query budget, in particular no passive DA learner, is consistent on the class  $\mathcal{C}_\infty^0$ .

But ANDA is :)

# Summary

- **New method** for learning under data shift
- **Finite sample bounds** on target generalization error

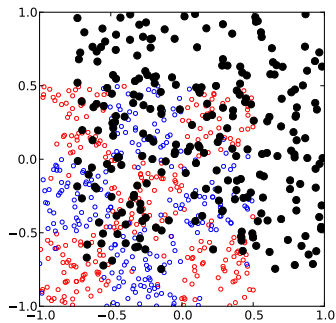
$$\mathbb{E}_{T \sim P_T^{m_T}} [\mathcal{L}_T(\text{ANDA}(S, T, k, k'))] \leq \left(1 + \sqrt{\frac{8}{k}}\right) \mathcal{L}_T(h^*) + 9\lambda\epsilon + \frac{2N_\epsilon(\mathcal{X}, \rho) k'}{m_T}.$$

(**independent** of source/target **relatedness**)

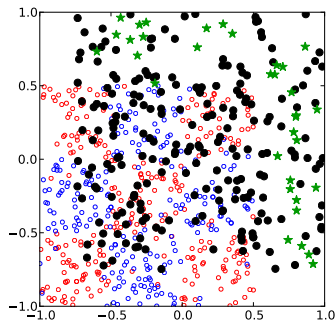
- Adaptability with **no prior knowledge of relatedness**
- Consistency even when **target not supported by the source**
- **No queries at all** when source/target are the same (or similar)

Thank you!

# Experiments

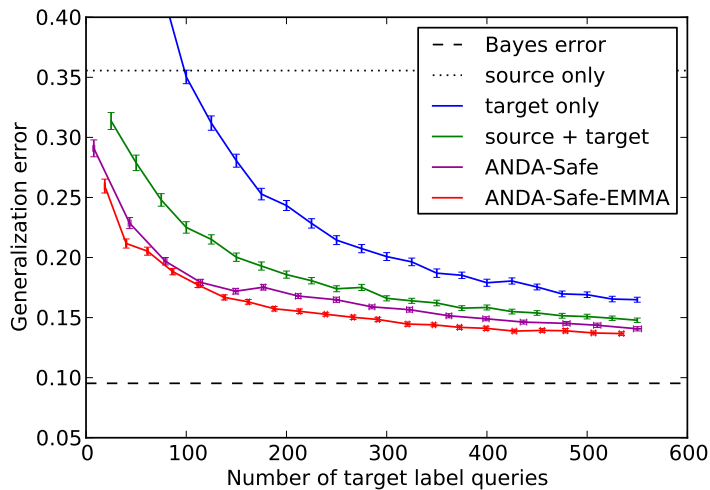


Unlabeled target



Queries made

# Experiments



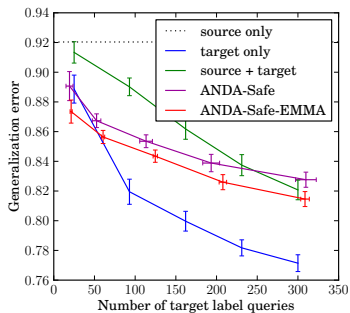


Figure: Imagenet  $\rightarrow$  Caltech256

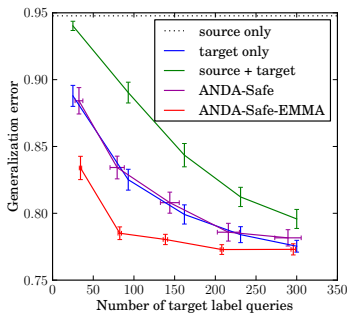


Figure: Bing  $\rightarrow$  Caltech256



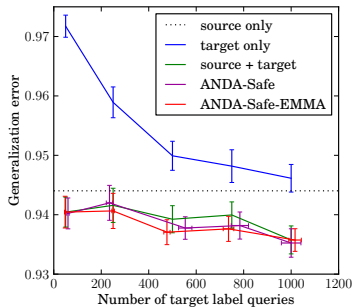


Figure: Caltech256 → Bing

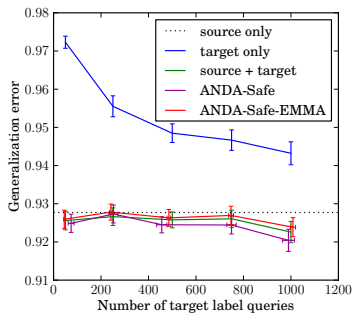


Figure: Imagenet → Bing

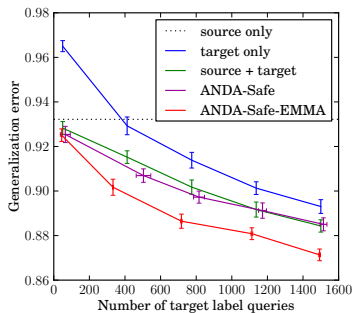


Figure: Bing  $\rightarrow$  Imagenet

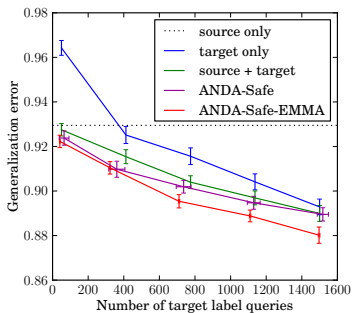


Figure: Caltech256  $\rightarrow$  Imagenet