Convergence of MCMC and Loopy BP in the Tree Uniqueness Region for the Hard-Core Model

Charis Efthymiou efthymiou@gmail.com

University of Frankfurt

joint work with: T. Hayes, D. Štefankovič, E. Vigoda, Y. Yin

Workshop on Random Instances and Phase Transitions Simons Institute 2-6 May 2016

◆□> <@> < E> < E> < E</p>

C.Efthymiou (Frankfurt)

2

イロト イ団ト イヨト イヨト

2

- 4 3 6 4 3 6

Image: A matrix

Given a graph G = (V, E) and fugacity $\lambda > 0$, for each independent set σ we have

$$\mu(\sigma) = \lambda^{|\sigma|} / Z,$$

3

ヨト イヨト

Given a graph G = (V, E) and fugacity $\lambda > 0$, for each independent set σ we have

$$\mu(\sigma) = \lambda^{|\sigma|} / Z,$$

where

$$Z = \sum_{\sigma} \lambda^{|\sigma|}$$

3

Given a graph G = (V, E) and fugacity $\lambda > 0$, for each independent set σ we have

$$\mu(\sigma) = \lambda^{|\sigma|}/Z,$$

where

$$Z = \sum_{\sigma} \lambda^{|\sigma|}$$

 $Z = Z(G, \lambda)$ is the partition function.

C.Efthymiou (Frankfurt)

2

イロト イ団ト イヨト イヨト

Given a graph G = (V, E) and *fugacity* $\lambda > 0$, *compute* the partition function

$$Z(G,\lambda) = \sum_{\sigma} \lambda^{|\sigma|}$$

3 1 4 3 1

Given a graph G = (V, E) and *fugacity* $\lambda > 0$, *compute* the partition function

$$Z(G,\lambda) = \sum_{\sigma} \lambda^{|\sigma|}$$

• computationally hard problem

ヨト イヨト

Given a graph G = (V, E) and *fugacity* $\lambda > 0$, *compute* the partition function

$$Z(G,\lambda) = \sum_{\sigma} \lambda^{|\sigma|}$$

- computationally hard problem
 - #P-complete [Valiant 1979]

Given a graph G = (V, E) and *fugacity* $\lambda > 0$, *compute* the partition function

$$Z(G,\lambda) = \sum_{\sigma} \lambda^{|\sigma|}$$

- computationally hard problem
 - #P-complete [Valiant 1979]
- focus on the approximation algorithms

Approximation Algorithms' Approach

2

- 4 週 ト - 4 三 ト - 4 三 ト

Compute estimates of the Gibbs distribution

(日) (同) (三) (三)

Compute estimates of the Gibbs distribution

Deterministic

э

(日) (同) (三) (三)

Compute estimates of the Gibbs distribution

Deterministic

Randomized

(日) (同) (三) (三)

Compute estimates of the Gibbs distribution

- Deterministic
 - Compute numerically (estimations of) the probability of a configuration

Randomized

∃ → (∃ →

Compute estimates of the Gibbs distribution

- Deterministic
 - Compute numerically (estimations of) the probability of a configuration

- Randomized
 - Generate Samples (approximately) Gibbs distributed

Compute estimates of the Gibbs distribution

Deterministic

- Compute numerically (estimations of) the probability of a configuration
- Fully Polynomial Time Approximation Scheme (FPTAS)

- Randomized
 - Generate Samples (approximately) Gibbs distributed
 - Fully Polynomial Time Randomized Approximation Scheme (FPRAS)

Compute estimates of the Gibbs distribution

- Deterministic
 - Compute numerically (estimations of) the probability of a configuration
 - Fully Polynomial Time Approximation Scheme (FPTAS)
 - in time $\operatorname{poly}(n)$ and $\operatorname{poly}(\epsilon^{-1})$

$$\hat{Z} \in (1 \pm \epsilon) Z(G, \lambda)$$

Randomized

- Generate Samples (approximately) Gibbs distributed
- Fully Polynomial Time Randomized Approximation Scheme (FPRAS)

• in time poly(n), $poly(\epsilon^{-1})$ and $poly(log(\delta^{-1}))$

$$\Pr[\hat{Z} \in (1 \pm \epsilon)Z(G, \lambda)] > 1 - \delta$$

(日) (周) (三) (三)

C.Efthymiou (Frankfurt)

2

くほと くほと くほと

Hardness of approximation [Sly 2010]

For triangle-free Δ -regular graphs, where $\Delta \geq 3$, and for all $\lambda > \lambda_c(\Delta)$, it is NP-hard to approximate the partition function within factor $2^{\gamma n}$.

Hardness of approximation [Sly 2010]

For triangle-free Δ -regular graphs, where $\Delta \geq 3$, and for all $\lambda > \lambda_c(\Delta)$, it is NP-hard to approximate the partition function within factor $2^{\gamma n}$.

- Galanis, Ge, Stefankovic, Vigoda, Yang (2011)
- Sly, Sun (2012)
- Galanis, Stefankovic, Vigoda (2012)

Hardness of approximation [Sly 2010]

For triangle-free Δ -regular graphs, where $\Delta \geq 3$, and for all $\lambda > \lambda_c(\Delta)$, it is NP-hard to approximate the partition function within factor $2^{\gamma n}$.

What is $\lambda_c(\Delta)$? [Kelly 1985]

Critical point for "uniqueness/non-uniqueness" phase transition of the hard-core model on \varDelta regular trees

$$\lambda_{\mathsf{c}}(\varDelta) := rac{(\varDelta-1)^{\varDelta-1}}{(\varDelta-2)^{\varDelta}} \sim rac{e}{\varDelta}$$

C.Efthymiou (Frankfurt)

2

イロト イヨト イヨト イヨト

Δ -regular tree T of height h

イロト イヨト イヨト イヨト

æ

Gibbs Uniqueness



 Δ -regular tree T of height h

æ

.∋...>

-



Gibbs Uniqueness



 Δ -regular tree T of height hTake two *extreme* configurations on L(h)

Gibbs Uniqueness



 Δ -regular tree T of height hTake two *extreme* configurations on L(h)



For every λ consider



For every λ consider

 $||\mu(\cdot|L(h) \text{ occupied}) - \mu(\cdot|L(h) \text{ unoccupied})||_{\{r\}}$



For every λ consider

```
\lim_{h \to \infty} ||\mu(\cdot|L(h) \text{ occupied}) - \mu(\cdot|L(h) \text{ unoccupied})||_{\{r\}}
```



For every λ consider

 $\lim_{h\to\infty} ||\mu(\cdot|L(h) \text{ occupied}) - \mu(\cdot|L(h) \text{ unoccupied})||_{\{r\}} = \left\{ \left| \frac{1}{2} \left(\frac{1}{2} \right) - \frac{1}{2} \left(\frac{1}{2} \right) \right|_{\{r\}} \right\} = \left\{ \left| \frac{1}{2} \right|_{r} \left(\frac{1}{2} \right) - \frac{1}{2} \left(\frac{1}{2} \right) - \frac{1}{2} \left(\frac{1}{2} \right) \right) \right|_{r} \left(\frac{1}{2} \right) - \frac{1}{2} \left(\frac{1}{2} \right) -$



For every λ consider

 $\lim_{h\to\infty} ||\mu(\cdot|L(h) \text{ occupied}) - \mu(\cdot|L(h) \text{ unoccupied})||_{\{r\}} = \begin{cases} 0 \\ 0 \end{cases}$



For every λ consider

 $\lim_{h\to\infty} ||\mu(\cdot|L(h) \text{ occupied}) - \mu(\cdot|L(h) \text{ unoccupied})||_{\{r\}} = \begin{cases} 0\\ \delta \end{cases}$



For every λ consider

 $\lim_{h \to \infty} ||\mu(\cdot | L(h) \text{ occupied}) - \mu(\cdot | L(h) \text{ unoccupied})||_{\{r\}} = \begin{cases} 0 & \text{Unique} \\ \delta & \text{non-Unique} \end{cases}$


 Δ -regular tree T of height hTake two *extreme* configurations on L(h)

For every λ consider

 $\lim_{h \to \infty} ||\mu(\cdot|L(h) \text{ occupied}) - \mu(\cdot|L(h) \text{ unoccupied})||_{\{r\}} = \begin{cases} 0 & \text{Unique} \\ \delta & \text{non-Unique} \end{cases}$

 $\lambda < \lambda_c(\Delta) \Leftrightarrow$ Gibbs measure is Unique



 Δ -regular tree T of height hTake two *extreme* configurations on L(h)

For every λ we compare

 $\lim_{h \to \infty} ||\mu(\cdot|L(h) \text{ occupied}) - \mu(\cdot|L(h) \text{ unoccupied})||_{\{r\}} = \begin{cases} 0 & \text{Unique} \\ \delta & \text{non-Unique} \end{cases}$

 $\lambda < \lambda_c(\Delta) \Leftrightarrow$ we have spatial mixing

Deterministic Algorithms

C.Efthymiou (Frankfurt)

3

- 本間 と 本語 と 本語 と

Deterministic Algorithms

Weitz's approach [Weitz 2006]

Given G and $\lambda < \lambda_c$,

C.Efthymiou (Frankfurt)

B ▶ < B ▶

Given G and $\lambda < \lambda_c$,

• uses tree of self avoiding walks, to organize the computations

- uses tree of self avoiding walks, to organize the computations
 - reduces to dynamic programming.

- uses tree of self avoiding walks, to organize the computations
 - reduces to dynamic programming.
- the size of computations depends on the size of the tree

- uses tree of self avoiding walks, to organize the computations
 - reduces to dynamic programming.
- the size of computations depends on the size of the tree
 - in the worst case the tree is exponentially large

- uses tree of self avoiding walks, to organize the computations
 - reduces to dynamic programming.
- the size of computations depends on the size of the tree
 - in the worst case the tree is exponentially large
- (strong) spatial mixing allows to "prune" the tree and still be accurate.

- uses tree of self avoiding walks, to organize the computations
 - reduces to dynamic programming.
- the size of computations depends on the size of the tree
 - in the worst case the tree is exponentially large
- (strong) spatial mixing allows to "prune" the tree and still be accurate.
 - this step requires $\lambda < \lambda_c(\varDelta)$

- uses tree of self avoiding walks, to organize the computations
 - reduces to dynamic programming.
- the size of computations depends on the size of the tree
 - in the worst case the tree is exponentially large
- (strong) spatial mixing allows to "prune" the tree and still be accurate.
 - this step requires $\lambda < \lambda_c(\varDelta)$
- L. Li, P. Lu, and Y. Yin (2012), (2013)
- Restrepo, Shin, Tetali, Vigoda, and Yang (2013)
- A. Sinclair, P. Srivastava, and Y. Yin (2013)

Approximation guarantees

For all $\delta > 0$, there exists constant $C = C(\delta) > 0$, for all Δ all G of maximum degree Δ , all $\lambda < (1 - \delta)\lambda_c(\Delta)$ all $\epsilon > 0$ Weitz's algorithm returns an estimation \hat{Z} of the partition function $Z(G, \lambda)$ such that

$$(1-\epsilon)Z(G,\lambda) \leq \hat{Z} \leq (1+\epsilon)Z(G,\lambda)$$

in time $O((n/\epsilon)^{C \log \Delta})$.

Randomized Algorithm

æ

イロト イ団ト イヨト イヨト

3

.∋...>

-

Given G and $\lambda > 0$,

3. 3

Given G and $\lambda > 0$,

• set up an ergodic Markov Chain over the independent sets

Given G and $\lambda > 0$,

- set up an ergodic Markov Chain over the independent sets
- the equilibrium distribution is the hard-core model with fugacity λ

Given G and $\lambda > 0$,

- set up an ergodic Markov Chain over the independent sets
- the equilibrium distribution is the hard-core model with fugacity λ
- the algorithm simulates the Markov chain

Given G and $\lambda > 0$,

- set up an ergodic Markov Chain over the independent sets
- the equilibrium distribution is the hard-core model with fugacity λ
- the algorithm simulates the Markov chain
- outputs the configuration of the chain after "sufficiently many" steps

Given G and $\lambda > 0$,

- set up an ergodic Markov Chain over the independent sets
- the equilibrium distribution is the hard-core model with fugacity λ
- the algorithm simulates the Markov chain
- outputs the configuration of the chain after "sufficiently many" steps

the output should be close to the equilibrium distribution

Given G and $\lambda > 0$,

- set up an ergodic Markov Chain over the independent sets
- the equilibrium distribution is the hard-core model with fugacity λ
- the algorithm simulates the Markov chain
- outputs the configuration of the chain after "sufficiently many" steps

the output should be close to the equilibrium distribution it is desirable that the chain mixes "fast"

C.Efthymiou (Frankfurt)

æ

・ロト ・ 日 ト ・ ヨ ト ・ ヨ ト

C.Efthymiou (Frankfurt)

æ

(日) (同) (三) (三)

 $X_t \rightarrow X_{t+1}$ is defined as follows:

æ

イロト イポト イヨト イヨト

- $X_t \rightarrow X_{t+1}$ is defined as follows:
 - Choose v uniformly at random from V.

3. 3

 $X_t \rightarrow X_{t+1}$ is defined as follows:

• Choose v uniformly at random from V.

$$X' = egin{cases} X_t \cup \{v\} & ext{ with probability } \lambda/(1+\lambda) \ X_t \setminus \{v\} & ext{ with probability } 1/(1+\lambda) \end{cases}$$

3

 $X_t \rightarrow X_{t+1}$ is defined as follows:

• Choose v uniformly at random from V.

$$X' = egin{cases} X_t \cup \{v\} & ext{ with probability } \lambda/(1+\lambda) \ X_t \setminus \{v\} & ext{ with probability } 1/(1+\lambda) \end{cases}$$

2 If X' is independent set, then $X_{t+1} = X'$, otherwise $X_{t+1} = X_t$

 $X_t \rightarrow X_{t+1}$ is defined as follows:

• Choose v uniformly at random from V.

$$X' = egin{cases} X_t \cup \{v\} & ext{ with probability } \lambda/(1+\lambda) \ X_t \setminus \{v\} & ext{ with probability } 1/(1+\lambda) \end{cases}$$

2 If X' is independent set, then $X_{t+1} = X'$, otherwise $X_{t+1} = X_t$

The chain converges to the hard-core model with fugacity λ .

Our Results

3

イロト イ団ト イヨト イヨト

For all $\delta > 0$, there exists $\Delta_0 = \Delta_0(\delta)$ for all graphs G = (V, E) of maximum degree $\Delta \ge \Delta_0$ and girth ≥ 7 , all $\lambda < (1 - \delta)\lambda_c(\Delta)$, the mixing time of the Glauber dynamics satisfies

 $T_{mix} = O\left(n\log(n)\right).$

For all $\delta > 0$, there exists $\Delta_0 = \Delta_0(\delta)$ for all graphs G = (V, E) of maximum degree $\Delta \ge \Delta_0$ and girth ≥ 7 , all $\lambda < (1 - \delta)\lambda_c(\Delta)$, the mixing time of the Glauber dynamics satisfies

$$T_{mix} = O\left(n\log(n)\right).$$

Mixing Time ...

$$T_{mix} = \min\{t : \text{ for all } X_0, d_{tv}(X_t, \mu) \le 1/4\},\$$

For all $\delta > 0$, there exists $\Delta_0 = \Delta_0(\delta)$ for all graphs G = (V, E) of maximum degree $\Delta \ge \Delta_0$ and girth ≥ 7 , all $\lambda < (1 - \delta)\lambda_c(\Delta)$, the mixing time of the Glauber dynamics satisfies

$$T_{mix} = O\left(n\log(n)\right).$$

Corollary

The above sampling result yields an FPRAS for estimating the partition function Z. The running time is $O^*(n^2)$.

For all $\delta > 0$, there exists $\Delta_0 = \Delta_0(\delta)$ for all graphs G = (V, E) of maximum degree $\Delta \ge \Delta_0$ and girth ≥ 7 , all $\lambda < (1 - \delta)\lambda_c(\Delta)$, the mixing time of the Glauber dynamics satisfies

$$T_{mix} = O\left(n\log(n)\right).$$

Previous work

 $T_{mix} = O(n \log(n))$ for Glauber dynamics on G of maximum degree Δ and $\lambda < 2/(\Delta - 2)$

• Dyer Greenhill, Luby, Vigoda

$O(n \log n)$ mixing for Random Graphs

3

イロト イヨト イヨト イヨト

Relaxation for girth

" # short cycles in the neighborhood of its vertex in G are not too many"

Relaxation for girth

" # short cycles in the neighborhood of its vertex in G are not too many"

Corollary

 $\mathcal{T}_{mix} = O(n \log n)$ for Glauber dynamics with $\lambda \leq (1 - \delta)\lambda_c(\Delta)$ for

伺下 イヨト イヨト
Relaxation for girth

" # short cycles in the neighborhood of its vertex in G are not too many"

Corollary

 $\mathcal{T}_{\textit{mix}} = O(n \log n)$ for Glauber dynamics with $\lambda \leq (1 - \delta) \lambda_c(\Delta)$ for

• random Δ -regular graph

Relaxation for girth

" # short cycles in the neighborhood of its vertex in G are not too many"

Corollary

 $\mathcal{T}_{\textit{mix}} = O(n \log n)$ for Glauber dynamics with $\lambda \leq (1 - \delta) \lambda_c(\Delta)$ for

- random Δ -regular graph
- random Δ -regular bipartite graph

Relaxation for girth

" # short cycles in the neighborhood of its vertex in G are not too many"

Corollary

 $\mathcal{T}_{\textit{mix}} = O(n \log n)$ for Glauber dynamics with $\lambda \leq (1 - \delta)\lambda_c(\Delta)$ for

- random Δ -regular graph
- random Δ -regular bipartite graph

Mossel, Weitz, Wormald (2009)

æ

- 4 週 ト - 4 三 ト - 4 三 ト

For T and λ compute $\mu(v \text{ occupied}|w \text{ unoccupied})$

- 一司

B ▶ < B ▶

For T and λ compute $\mu(v \text{ occupied}|w \text{ unoccupied})$



э

For T and λ compute $\mu(v \text{ occupied}|w \text{ unoccupied})$



For T and λ compute $\mu(v \text{ occupied}|w \text{ unoccupied})$



For *T* and λ compute $\mu(v \text{ occupied}|w \text{ unoccupied})$

$$R_{v\to w} = \frac{q_w(v)}{1-q_w(v)}$$



For *T* and λ compute $\mu(v \text{ occupied}|w \text{ unoccupied})$

$$R_{v\to w} = \frac{q_w(v)}{1-q_w(v)}$$



For T and λ compute $\mu(v \text{ occupied}|w \text{ unoccupied})$





For T and λ compute $\mu(v \text{ occupied}|w \text{ unoccupied})$





For *T* and λ compute $\mu(v \text{ occupied}|w \text{ unoccupied})$

 $q_w(v) = \mu(v \text{ occupied}|w \text{ unoccupied})$

$$R_{v \to w} = \frac{q_w(v)}{1 - q_w(v)}$$
$$R_{v \to w} = \lambda \prod_{z \in N(v) \setminus \{w\}} \frac{1}{1 + R_{z \to v}}$$

BP starts from arbitrary $R_{v \to w}^0 s$, iterates like

$$R_{\nu \to w}^{i} = \lambda \prod_{z \in N(\nu) \setminus \{w\}} \frac{1}{1 + R_{z \to \nu}^{i-1}}$$





C.Efthymiou (Frankfurt)

2

・ロト ・ 日 ト ・ ヨ ト ・ ヨ ト

Convergence on trees

There exists i_0 such that for every $i \ge i_0$ and every $(R^0_{\nu \to w})_{\{\nu,w\} \in E}$ we have

$$R^i_{v o w} = R^*_{v o w}$$

In turn

$$\mu(v \text{ occupied}|w \text{ unoccupied}) = q^* = \frac{R^*_{v \to w}}{1 + R^*_{v \to w}}$$

э

Convergence on trees

There exists i_0 such that for every $i \ge i_0$ and every $(R^0_{v \to w})_{\{v,w\} \in E}$ we have

$$R^i_{v o w} = R^*_{v o w}$$

In turn

$$\mu(v \text{ occupied} | w \text{ unoccupied}) = q^* = \frac{R^*_{v \to w}}{1 + R^*_{v \to w}}$$

BP is an elaborate use of *Dynamic Programing* to compute marginal.

- ∢ ∃ ▶

(Loopy) Belief Propagation

2

イロト イヨト イヨト イヨト

• We do not know whether it converges

э

B ▶ < B ▶

- We do not know whether it converges
- ... if does, we do not know where exactly it converges

æ

イロト イ団ト イヨト イヨト

$$R_{\nu \to w}^{i} = \lambda \prod_{z \in N(\nu) \setminus \{w\}} \frac{1}{1 + R_{z \to \nu}^{i-1}}$$

æ

イロト イ団ト イヨト イヨト

$$R^i_{\nu \to w} = \lambda \prod_{z \in \mathcal{N}(\nu) \setminus \{w\}} \frac{1}{1 + R^{i-1}_{z \to \nu}} \quad \text{and} \quad q^i_w(\nu) = \frac{R^i_{\nu \to w}}{1 + R^i_{\nu \to w}}$$

æ

イロト イヨト イヨト イヨト

$$R_{\nu \to w}^{i} = \lambda \prod_{z \in \mathcal{N}(\nu) \setminus \{w\}} \frac{1}{1 + R_{z \to \nu}^{i-1}} \quad \text{and} \quad q_{w}^{i}(\nu) = \frac{R_{\nu \to w}^{i}}{1 + R_{\nu \to w}^{i}}$$

Theorem

For G = (V, E) of maximum degree $\Delta \ge \Delta_0$ and girth ≥ 6 , all $\lambda < (1-\delta)\lambda_c(\Delta)$, the following holds: for $i \ge C$, for all $v \in V$, $w \in N(v)$,

$$\left|rac{q_w^i(m{v})}{\mu(m{v} \,\, is \,\, occupied \,|\,\, w \,\, is \,\, unoccupied)} - 1
ight| \leq \epsilon$$

$$R_{\nu \to w}^{i} = \lambda \prod_{z \in \mathcal{N}(\nu) \setminus \{w\}} \frac{1}{1 + R_{z \to \nu}^{i-1}} \quad \text{and} \quad q_{w}^{i}(\nu) = \frac{R_{\nu \to w}^{i}}{1 + R_{\nu \to w}^{i}}$$

Theorem

For G = (V, E) of maximum degree $\Delta \ge \Delta_0$ and girth ≥ 6 , all $\lambda < (1-\delta)\lambda_c(\Delta)$, the following holds: for $i \ge C$, for all $v \in V$, $w \in N(v)$,

$$\left|rac{q_w^i(m{v})}{\mu(m{v} ~is~occupied \mid w~is~unoccupied)}-1
ight| \leq \epsilon$$

we also have convergence for the BP estimate of $\mu(v \text{ is occupied})$

Path Coupling for Rapid Mixing



æ

イロト イヨト イヨト イヨト

Path Coupling for Rapid Mixing

Path Coupling [Bubley and Dyer 1997]



• • = • • =

Consider copies $(X_s), (Y_s)$ such that $X_t \oplus Y_t = \{v\}$

Consider copies $(X_s), (Y_s)$ such that $X_t \oplus Y_t = \{v\}$



C.Efthymiou (Frankfurt)

Consider copies $(X_s), (Y_s)$ such that $X_t \oplus Y_t = \{v\}$

$$\mathbb{E}\left[\Phi(X_{t+1},Y_{t+1})|X_t,Y_t\right] \leq (1-\gamma)\Phi(X_t,Y_t).$$



C.Efthymiou (Frankfurt)

Consider copies $(X_s), (Y_s)$ such that $X_t \oplus Y_t = \{v\}$

$$\mathbb{E}\left[\Phi(X_{t+1}, Y_{t+1}) | X_t, Y_t\right] \leq (1 - \gamma) \Phi(X_t, Y_t).$$

 $\Phi: \Omega \times \Omega \to \mathbb{R}_{\geq 1}$ is a "distance metric"



Consider copies $(X_s), (Y_s)$ such that $X_t \oplus Y_t = \{v\}$

$$\mathbb{E}\left[\Phi(X_{t+1},Y_{t+1})|X_t,Y_t\right] \leq (1-\gamma)\Phi(X_t,Y_t).$$

 $\Phi: \Omega \times \Omega \to \mathbb{R}_{\geq 1}$ is a "distance metric"

$$\Phi(X,Y) = \sum_{u \in X \oplus Y} \Phi(u)$$



Key Results

3

・ロト ・ 日 ト ・ ヨ ト ・ ヨ ト

• We don't know a Φ that gives contraction for worst-case X_t, Y_t .

æ

(日) (周) (三) (三)

- We don't know a Φ that gives contraction for worst-case X_t, Y_t .
- can find Φ when locally X_t, Y_t "behave" like R^*

3

ヨト イヨト

- We don't know a Φ that gives contraction for worst-case X_t, Y_t .
- can find Φ when locally X_t, Y_t "behave" like R^*
- Glauber dynamics converges locally to R^*

- We don't know a Φ that gives contraction for worst-case X_t, Y_t .
- can find Φ when locally X_t, Y_t "behave" like R^*
- Glauber dynamics converges locally to R*
- ${\ensuremath{\,\circ}}$ Given \varPhi and convergence of Glauber dynamics we show rapid mixing
Path Coupling Example

C.Efthymiou (Frankfurt)

2

イロト イヨト イヨト イヨト

Path Coupling Example



2

イロト イヨト イヨト イヨト

$$\mathbb{E}\left[\Phi(X_{t+1}, Y_{t+1}) | X_t, Y_t\right] = \left(1 - \frac{1}{n}\right) \Phi(v) + \frac{1}{n} \sum_{z_i} \Pr[z_i \in Y_{t+1}] \cdot \Phi(z_i)$$



æ

$$\mathbb{E}\left[\Phi(X_{t+1}, Y_{t+1}) | X_t, Y_t\right] = \left(1 - \frac{1}{n}\right) \Phi(v) + \frac{1}{n} \sum_{z_i} \Pr[z_i \in Y_{t+1}] \cdot \Phi(z_i)$$



æ

$$\mathbb{E}\left[\Phi(X_{t+1}, Y_{t+1}) | X_t, Y_t\right] = \left(1 - \frac{1}{n}\right) \Phi(v) + \frac{1}{n} \sum_{z_i} \Pr[z_i \in Y_{t+1}] \cdot \Phi(z_i)$$



æ

$$\mathbb{E}\left[\Phi(X_{t+1}, Y_{t+1}) | X_t, Y_t\right] = \left(1 - \frac{1}{n}\right) \Phi(v) + \frac{1}{n} \sum_{z_i} \mathbf{1}\{z_i \text{ unblocked}\} \frac{\lambda \Phi(z_i)}{1 + \lambda}$$

Blocked



æ

Path coupling condition

$$\Phi(\mathbf{v}) > rac{\lambda}{1+\lambda} \sum_{z_i} \mathbf{1}\{z_i \text{ unblocked in } Y_t\} \cdot \Phi(z_i)$$



æ

ም.

.

- We don't know a Φ that gives contraction for worst-case X_t, Y_t .
- can find Φ when locally X_t, Y_t "behave" like R^*
- Glauber dynamics converges locally to R^*
- Given Φ and convergence of Glauber dynamics we show rapid mixing

æ

ヨト イヨト

$$\omega_z^i = \prod_{y \sim z} \frac{1}{1 + \lambda \cdot \omega_y^{i-1}}$$

21 / 35

æ

- 4 @ ▶ 4 @ ▶ 4 @ ▶

$$\omega_z^i = \prod_{y \sim z} \frac{1}{1 + \lambda \cdot \omega_y^{i-1}}$$

• $\omega^i(z)$ is the loopy BP estimate of z to be unblocked

표 문 문

$$\omega_z^i = \prod_{y \sim z} \frac{1}{1 + \lambda \cdot \omega_y^{i-1}}$$

ωⁱ(z) is the loopy BP estimate of z to be unblocked
converges to a unique fixed point ω*

$$\omega_z^i = \prod_{y \sim z} \frac{1}{1 + \lambda \cdot \omega_y^{i-1}}$$

- ωⁱ(z) is the loopy BP estimate of z to be unblocked
 converges to a unique fixed point ω*
- $\omega^*(z) \approx \mu(z \text{ is unblocked})$



2

イロト イヨト イヨト イヨト



C.Efthymiou (Frankfurt)

Rapid Mixing from Loopy BP

22 / 35

2

E ► < E ►

worst case condition

$$arPsi_i(\mathbf{v}) > rac{\lambda}{1+\lambda}\sum_{\mathbf{z}_i} \mathbf{1}\{z_i ext{ unblocked}\} \cdot \varPhi(z_i)$$



C.Efthymiou (Frankfurt)

22 / 35

2

- ∢ ≣ →

worst case condition

$$arPsi_i(oldsymbol{v}) > rac{\lambda}{1+\lambda}\sum_{z_i} \mathbf{1}\{z_i ext{ unblocked}\} \cdot \varPhi(z_i)$$

when X_t, Y_t "behave" like ω^*

$$arPsi_i(m{v}) > rac{\lambda}{1+\lambda}\sum_{z_i}\omega^*(z_i)\cdot arPsi(z_i)$$



문 > 문

22 / 35



2

・ロト ・ 日 ト ・ ヨ ト ・ ヨ ト



Reformulation

C.Efthymiou (Frankfurt)

2

イロト イ団ト イヨト イヨト

Reformulation

For $\rho = 1 - \delta$, there is Φ such that

$$ho \cdot \Phi(\mathbf{v}) \geq \sum_{z_i} rac{\lambda \omega^*(z_i)}{1 + \lambda \omega^*(z_i)} \cdot \Phi(z_i)$$

æ

イロト イヨト イヨト イヨト

Reformulation

For $\rho = 1 - \delta$, there is Φ such that

$$\rho \cdot \Phi(\mathbf{v}) \geq \sum_{z_i} \frac{\lambda \omega^*(z_i)}{1 + \lambda \omega^*(z_i)} \cdot \Phi(z_i)$$

 $n \times n$ matrix C

$$\mathcal{C}(v,z) = \begin{cases} \frac{\lambda \omega^*(z)}{1 + \lambda \omega^*(z)} & \text{if } z \in \mathcal{N}(v) \\ 0 & \text{otherwise} \end{cases}$$

æ

イロト イヨト イヨト イヨト

Reformulation

For $\rho = 1 - \delta$, there is Φ such that

$$\rho \cdot \Phi(\mathbf{v}) \geq \sum_{z_i} \frac{\lambda \omega^*(z_i)}{1 + \lambda \omega^*(z_i)} \cdot \Phi(z_i)$$

 $n \times n$ matrix C

$$\mathcal{C}(v,z) = \begin{cases} \frac{\lambda \omega^*(z)}{1+\lambda \omega^*(z)} & \text{if } z \in \mathcal{N}(v) \\ 0 & \text{otherwise} \end{cases}$$

There is a vector $\Phi \in \mathbb{R}_{\geq 1}^{V}$ such that

 $\mathcal{C}\Phi \le \rho \cdot \Phi.$

3

イロト イポト イヨト イヨト

Connections with Loopy BP

2

Connections with Loopy BP

Jacobian of Loopy BP

æ

э

BP Operator

$$F(\omega_z) = \prod_{y \in N(z)} \frac{1}{1 + \lambda \omega_y}.$$

æ

.∋...>

-

BP Operator

$$F(\omega_z) = \prod_{y \in N(z)} \frac{1}{1 + \lambda \omega_y}.$$

 $J^* = J|_{\omega = \omega^*}$ denote the Jacobian of F at the fixed point $\omega = \omega^*$.

æ

伺下 イヨト イヨト

BP Operator

$$F(\omega_z) = \prod_{y \in N(z)} \frac{1}{1 + \lambda \omega_y}.$$

 $J^* = J|_{\omega = \omega^*}$ denote the Jacobian of F at the fixed point $\omega = \omega^*$.

$$\hat{J} = D^{-1} J^* D,$$

where D is diagonal matrix, with $D(v, v) = \omega^*(v)$

- 4 緑 ト - 4 戸 ト - 4 戸 ト

BP Operator

$$F(\omega_z) = \prod_{y \in N(z)} \frac{1}{1 + \lambda \omega_y}.$$

 $J^* = J|_{\omega = \omega^*}$ denote the Jacobian of F at the fixed point $\omega = \omega^*$.

$$\hat{J}=D^{-1}J^*D,$$

where D is diagonal matrix, with $D(v, v) = \omega^*(v)$

Relation to Path Coupling

$$\hat{J} = C$$

æ

イロト イポト イヨト イヨト

2

イロト イヨト イヨト イヨト

Reduction to BP Spectral radius

For $\rho = 1 - \delta$, there is a vector $\Phi \in \mathbb{R}^V$ such that

 $\hat{J} \Phi \leq \rho \cdot \Phi$

Reduction to BP Spectral radius

For $\rho = 1 - \delta$, there is a vector $\Phi \in \mathbb{R}^V$ such that

$$\hat{J}\Phi \leq \rho \cdot \Phi$$

 \hat{J} has the same eigenvalues as the Jacobian of BP at the fixed point

Reduction to BP Spectral radius

For $\rho = 1 - \delta$, there is a vector $\Phi \in \mathbb{R}^V$ such that

$$\hat{J}\Phi \leq \rho \cdot \Phi$$

 \hat{J} has the same eigenvalues as the Jacobian of BP at the fixed point

Spectral radius of BP in uniqueness region

We should expect $\rho(\lambda, \Delta) < 1$, because the fixed point ω^* is attractive

Reduction to BP Spectral radius

For $\rho = 1 - \delta$, there is a vector $\Phi \in \mathbb{R}^V$ such that

$$\hat{J}\Phi \leq \rho \cdot \Phi$$

 \hat{J} has the same eigenvalues as the Jacobian of BP at the fixed point

Spectral radius of BP in uniqueness region

We should expect $ho(\lambda, \Delta) < 1$, because the fixed point ω^* is attractive

• $\Phi > 0$ from Perron-Frobenius

Reduction to BP Spectral radius

For $\rho = 1 - \delta$, there is a vector $\Phi \in \mathbb{R}^V$ such that

$$\hat{J}\Phi \leq \rho \cdot \Phi$$

 \widehat{J} has the same eigenvalues as the Jacobian of BP at the fixed point

Spectral radius of BP in uniqueness region

We should expect $ho(\lambda, \Delta) < 1$, because the fixed point ω^* is attractive

• $\Phi > 0$ from Perron-Frobenius

What is Φ

$$arPsi_{}(\mathbf{v})=\sqrt{rac{1+\lambda\omega^{*}(\mathbf{v})}{\omega^{*}(\mathbf{v})}}$$

C.Efthymiou (Frankfurt)

- We don't know a Φ that gives contraction for worst-case X_t, Y_t .
- can find Φ when locally X_t, Y_t "behave" like R^*
- Glauber dynamics converges locally to R^*
- Given Φ and convergence of Glauber dynamics we show rapid mixing

- We don't know a Φ that gives contraction for worst-case X_t, Y_t .
- can find Φ when locally X_t, Y_t "behave" like ω^*
- $\bullet\,$ Glauber dynamics converges locally to ω^*
- Given Φ and convergence of Glauber dynamics we show rapid mixing
- We don't know a Φ that gives contraction for worst-case X_t, Y_t .
- can find Φ when locally X_t, Y_t "behave" like ω^*
- $\bullet\,$ Glauber dynamics converges locally to ω^*
- ullet Given \varPhi and convergence of Glauber dynamics we show rapid mixing

Theorem

Let G be of girth ≥ 7 and maximum degree Δ , for $\Delta > \Delta_0$. Let (X_t) be the Glauber dynamics with $\lambda < (1 - \delta)\lambda_c(\Delta)$. For any vertex v, with probability $1 - \exp[-\Delta/C]$, it holds that

Unblocked Neighbors of
$$v$$
 in $X_t < \sum_{z \in N(v)} \omega^*(z) + \epsilon \varDelta$

where $t \geq Cn \log \Delta$.

- We don't know a Φ that gives contraction for worst-case X_t, Y_t .
- can find Φ when locally X_t, Y_t "behave" like ω^*
 - \varPhi is from the Jacobian of BP operator
- Glauber dynamics (approximately) converges locally to ω^*
 - locally Glauber dynamics behaves approximately like BP fixed points
- $\bullet\,$ Given $\varPhi\,$ and convergence of Glauber dynamics we show rapid mixing

æ

イロト イヨト イヨト イヨト



There is a single disagreement at v



Run the chains for $Cn \log \Delta$ steps, "burn-in"



Run the chains for $Cn \log \Delta$ steps, "burn-in"



The disagreements spread in the graph during burn-in



Typically the disagreements do not escape the ball



Typically the disagreements do not escape the ball



Typically the ball has uniformity.

3. 3



Interpolate and do path coupling for the pairs, ... the pairs now "behave" like ω^{\ast}



Interpolate and do path coupling for the pairs,

 \ldots the pairs now "behave" like ω^* and \varPhi gives convergence



 $\mathbb{E}\left[\left. \Phi(X_{C'n\log\Delta}, Y_{C'n\log\Delta}) \right| X_0, Y_0 \right] \leq (1-\gamma) \Phi(X_0, Y_0)$

< ロト < 同ト < ヨト < ヨト

- We don't know a Φ that gives contraction for worst-case X_t, Y_t .
- We can find Φ when $X, Y \sim \omega^*$
- $\bullet\,$ Glauber dynamics converges locally to ω^*
- Given Φ and convergence of Glauber dynamics we show rapid mixing

- We don't know a Φ that gives contraction for worst-case X_t, Y_t .
- We can find Φ when $X, Y \sim \omega^*$
- Glauber dynamics converges locally to ω^*
- Given Φ and convergence of Glauber dynamics we show rapid mixing

Local uniformity I

$$\mathbf{R}(\sigma, \mathbf{v}) = \prod_{w \sim \mathbf{v}} \left(1 - \frac{\lambda}{1+\lambda} \mathbf{1} \{ \text{w unblocked by its children} \} \right),$$

2

* ロ > * 個 > * 注 > * 注 >

Local uniformity I

$$\mathbf{R}(\sigma, \mathbf{v}) = \prod_{w \sim \mathbf{v}} \left(1 - \frac{\lambda}{1+\lambda} \mathbf{1} \{ \text{w unblocked by its children} \} \right),$$

2

* ロ > * 個 > * 注 > * 注 >

Local uniformity I

$$\mathbf{R}(\sigma, \mathbf{v}) = \prod_{w \sim \mathbf{v}} \left(1 - \frac{\lambda}{1+\lambda} \mathbf{1} \{ \text{w unblocked by its children} \} \right),$$



$$\mathbf{R}(\sigma, \mathbf{v}) = \Pr_{\mathbf{Y} \sim \mu} [\mathbf{v} \text{ is unblocked in } \mathbf{Y} | \mathbf{v} \notin \mathbf{Y}, \ \mathbf{Y}(S_2(\mathbf{v})) = \sigma(S_2(\mathbf{v}))]$$

2

・ロト ・ 日 ト ・ ヨ ト ・ ヨ ト

$$\mathbf{R}(\sigma, \mathbf{v}) = \prod_{w \sim \mathbf{v}} \left(1 - \frac{\lambda}{1+\lambda} \mathbf{1} \{ \text{w unblocked by its children} \} \right),$$

BP for Gibbs measure

Let G be of girth ≥ 6 and maximum degree $\Delta > \Delta_0$. Let X be distributed as in μ with $\lambda < (1 - \delta)\lambda_c(\Delta)$. Then for any vertex v with probability $\geq 1 - \exp(-\Delta/C)$ it holds that

$$\left| \mathbf{R}(X, v) - \prod_{z \sim v} \left(1 - \frac{\lambda}{1+\lambda} \mathbf{R}(X, z) \right) \right| < \gamma.$$

$$\mathbf{R}(\sigma, \mathbf{v}) = \prod_{\mathbf{w} \sim \mathbf{v}} \left(1 - \frac{\lambda}{1+\lambda} \mathbf{1} \{ \text{w unblocked by its children} \} \right),$$

BP for Glauber dynamics

Let G be of girth ≥ 7 and maximum degree $\Delta > \Delta_0$. Let (X_t) be the Glauber dynamics with $\lambda < (1 - \delta)\lambda_c(\Delta)$. Then for any vertex v and any $t > Cn \log \Delta$ with probability $\geq 1 - \exp(-\Delta/C)$ it holds that

$$\left| \mathbf{R}(X_t, \nu) - \prod_{z \sim \nu} \left(1 - \frac{\lambda}{1+\lambda} \mathbb{E}_{t_z} \left[\mathbf{R}(X_{t_z}, z) \right] \right) \right| < \gamma.$$

Local uniformity II

C.Efthymiou (Frankfurt)

æ

メロト メポト メヨト メヨト

Lemma

Let G be of girth ≥ 7 and maximum degree $\Delta > \Delta_0$. Let (X_t) be the Glauber dynamics with $\lambda < (1 - \delta)\lambda_c(\Delta)$. For all $\mathcal{I} = [t_0, t_1]$, where $t_0 = Cn \log \Delta$, for every $v \in V$ with probability $1 - (1 + |\mathcal{I}|/n) \exp(-\Delta/C)$, we have that

$$(\forall t \in \mathcal{I}) \quad |\mathbf{R}(X_t, v) - \omega^*(v)| \leq \epsilon.$$

Lemma

Let G be of girth ≥ 7 and maximum degree $\Delta > \Delta_0$. Let (X_t) be the Glauber dynamics with $\lambda < (1 - \delta)\lambda_c(\Delta)$. For all $\mathcal{I} = [t_0, t_1]$, where $t_0 = Cn \log \Delta$, for every $v \in V$ with probability $1 - (1 + |\mathcal{I}|/n) \exp(-\Delta/C)$, we have that

$$(\forall t \in \mathcal{I}) \quad |\mathbf{R}(X_t, v) - \omega^*(v)| \leq \epsilon.$$

• Hayes 2012

C.Efthymiou (Frankfurt)

2

イロト イヨト イヨト イヨト

Convergence with \varPsi

Potential function

$$\Psi(x) = (\lambda)^{-1} \operatorname{arcsinh}(\sqrt{\lambda x})$$

3 x 3

Convergence with \varPsi

Potential function

$$\Psi(x) = (\lambda)^{-1} \operatorname{arcsinh}(\sqrt{\lambda x})$$

 \mathcal{I}

3 x 3

Convergence with \varPsi

Potential function

$$\Psi(x) = (\lambda)^{-1} \operatorname{arcsinh}(\sqrt{\lambda x})$$



Convergence with Ψ

Potential function

$$\Psi(x) = (\lambda)^{-1} \operatorname{arcsinh}(\sqrt{\lambda x})$$

Provided

- t ∈ I' approximate BP equation hold in B(v, R)
- $\forall t \in \mathcal{I}_{i+1}, u \in B(v, i+1)$



Convergence with Ψ

Potential function

$$\Psi(x) = (\lambda)^{-1} \operatorname{arcsinh}(\sqrt{\lambda x})$$

Provided

- t ∈ I' approximate BP equation hold in B(v, R)
- $\forall t \in \mathcal{I}_{i+1}, u \in B(v, i+1)$



Convergence with Ψ

Potential function

$$\Psi(x) = (\lambda)^{-1} \operatorname{arcsinh}(\sqrt{\lambda x})$$

Provided

- t ∈ I' approximate BP equation hold in B(v, R)
- $\forall t \in \mathcal{I}_{i+1}, u \in B(v, i+1)$



Convergence with Ψ

Potential function

$$\Psi(x) = (\lambda)^{-1} \operatorname{arcsinh}(\sqrt{\lambda x})$$

Provided

- t ∈ *I*' approximate BP equation hold in B(v, R)
- $\forall t \in \mathcal{I}_{i+1}, u \in B(v, i+1)$



Convergence with Ψ

Potential function

$$\Psi(x) = (\lambda)^{-1} \operatorname{arcsinh}(\sqrt{\lambda x})$$

Provided

- t ∈ *I*' approximate BP equation hold in B(v, R)
- $\forall t \in \mathcal{I}_{i+1}, u \in B(v, i+1)$



Convergence with \varPsi

Potential function

$$\Psi(x) = (\lambda)^{-1} \operatorname{arcsinh}(\sqrt{\lambda x})$$

Provided

 t ∈ I' approximate BP equation hold in B(v, R)

•
$$\forall t \in \mathcal{I}_{i+1}, u \in B(v, i+1)$$

$$|\Psi(\mathsf{R}(X_t, u)) - \Psi(\omega^*(u))| \le \alpha_{i+1}$$

 $\forall t \in \mathcal{I}_i, u \in B(v, i)$

$$|\Psi(\mathsf{R}(X_t, u)) - \Psi(\omega^*(u))| \le (1 - \delta)\alpha_{i+1}$$



Convergence with \varPsi

Potential function

$$\Psi(x) = (\lambda)^{-1} \operatorname{arcsinh}(\sqrt{\lambda x})$$

Provided

 t ∈ I' approximate BP equation hold in B(v, R)

•
$$\forall t \in \mathcal{I}_{i+1}, u \in B(v, i+1)$$

$$|\Psi(\mathsf{R}(X_t, u)) - \Psi(\omega^*(u))| \le \alpha_{i+1}$$

 $\forall t \in \mathcal{I}_i, u \in B(v, i)$

$$|\Psi(\mathsf{R}(X_t,u)) - \Psi(\omega^*(u))| \le (1-\delta)\alpha_{i+1}$$



Concluding Remarks

C.Efthymiou (Frankfurt)

2

メロト メポト メヨト メヨト
- Rapid mixing for Glauber Dynamics
 - G max degree $\Delta > \Delta_0$ and girth ≥ 7
 - λ in uniqueness

< 🗇 🕨

- - E + - E +

• Rapid mixing for Glauber Dynamics

- G max degree $\varDelta > \varDelta_0$ and girth ≥ 7
- λ in uniqueness
- Approach

< A

э

• Rapid mixing for Glauber Dynamics

- G max degree $\varDelta > \varDelta_0$ and girth ≥ 7
- λ in uniqueness
- Approach
 - by establishing *uniformity*

-∢∃>

- Rapid mixing for Glauber Dynamics
 - G max degree $\varDelta > \varDelta_0$ and girth ≥ 7
 - λ in uniqueness
- Approach
 - by establishing uniformity
 - proposing "Hamming weights"

-∢ ∃ ▶

- Rapid mixing for Glauber Dynamics
 - G max degree $\varDelta > \varDelta_0$ and girth ≥ 7
 - λ in uniqueness
- Approach
 - by establishing uniformity
 - proposing "Hamming weights"
- Establish a novel connection between Path Coupling and Loopy BP
 - this is important for both uniformity and Hamming weights

- Rapid mixing for Glauber Dynamics
 - G max degree $\varDelta > \varDelta_0$ and girth ≥ 7
 - λ in uniqueness
- Approach
 - by establishing uniformity
 - proposing "Hamming weights"
- Establish a novel connection between Path Coupling and Loopy BP
 - this is important for both uniformity and Hamming weights
- Use experience from Glauber dynamics to analyze Loopy BP
 - ${\ensuremath{\, \bullet }}$ for graphs of girth ≥ 6 in the uniqueness region

- Rapid mixing for Glauber Dynamics
 - G max degree $\varDelta > \varDelta_0$ and girth ≥ 7
 - λ in uniqueness
- Approach
 - by establishing uniformity
 - proposing "Hamming weights"
- Establish a novel connection between Path Coupling and Loopy BP
 - this is important for both uniformity and Hamming weights
- Use experience from Glauber dynamics to analyze Loopy BP
 - $\bullet\,$ for graphs of girth ≥ 6 in the uniqueness region
- The connection between Glauber dynamics and Loopy BP is deep

- Rapid mixing for Glauber Dynamics
 - G max degree $\varDelta > \varDelta_0$ and girth ≥ 7
 - λ in uniqueness
- Approach
 - by establishing uniformity
 - proposing "Hamming weights"
- Establish a novel connection between Path Coupling and Loopy BP
 - this is important for both uniformity and Hamming weights
- Use experience from Glauber dynamics to analyze Loopy BP
 - $\bullet\,$ for graphs of girth ≥ 6 in the uniqueness region
- The connection between Glauber dynamics and Loopy BP is deep
 - Allows to establish uniformity and weights in a systematic way

THANK YOU!

2

メロト メポト メヨト メヨト