Phase Transitions in Semidefinite Relaxations (a fast & robust algorithm for community detection)

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# Outline of the talk

- Hidden partition model (a.k.a. community detection pb.)
  - Spectral vs. optimization methods (ML & SDP)
  - Optimality vs. robustness
- Community detection algorithm based on SDP
  - It is simple, fast and robust
- Phase transitions in SDP
  - Statistical physics approach -> phase transitions
  - (Quasi-)optimality of SDP for (sparse) dense graphs

## Communities detection problem

- Detecting communities/partitions/clusters in graphs is a widespread problem in many different disciplines
- Examples of applications: social networks mining, recommendation systems improvement, images segmentation and classification, and many more in biology...
- We need fast (linear and scalable) algorithms
  - robust (real datasets are very noisy and not random)
  - optimal (on random ensemble benchmarks)

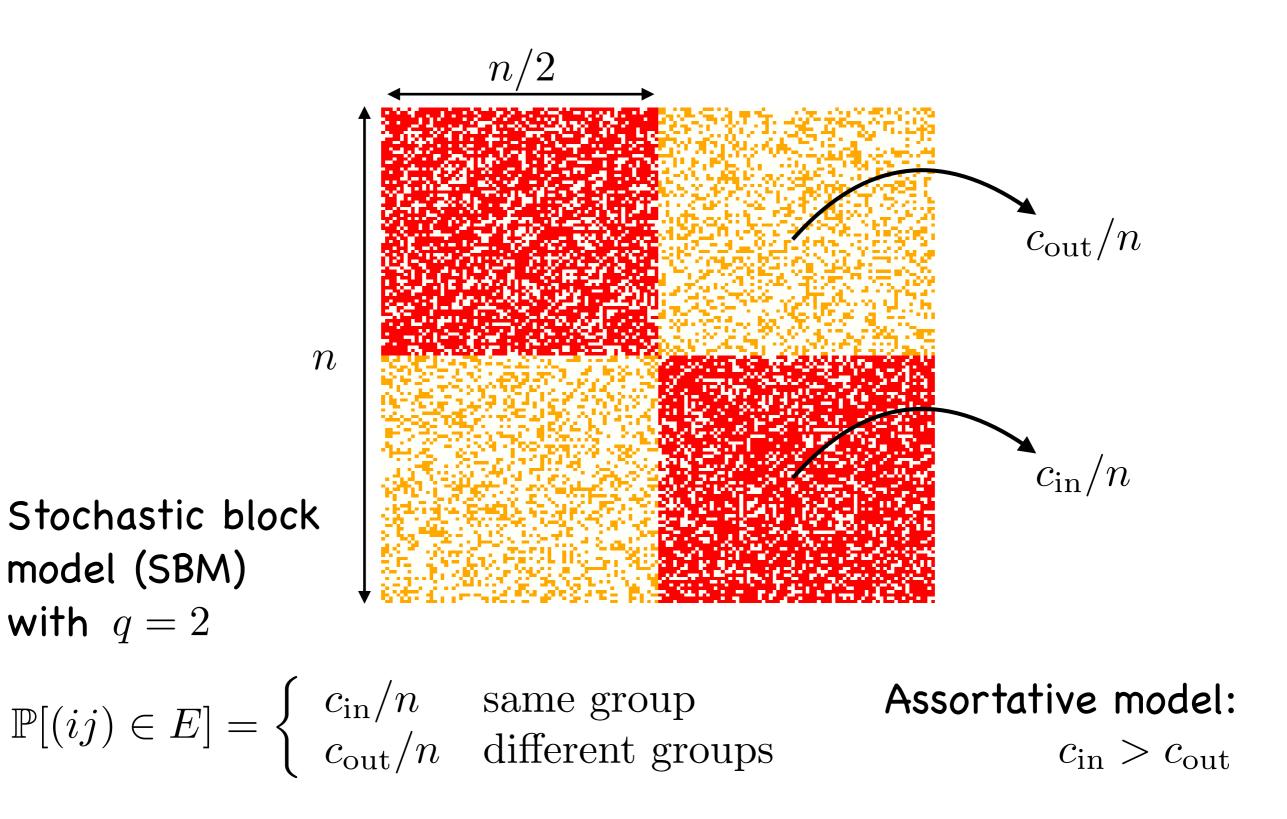
# Benchmark for community detection

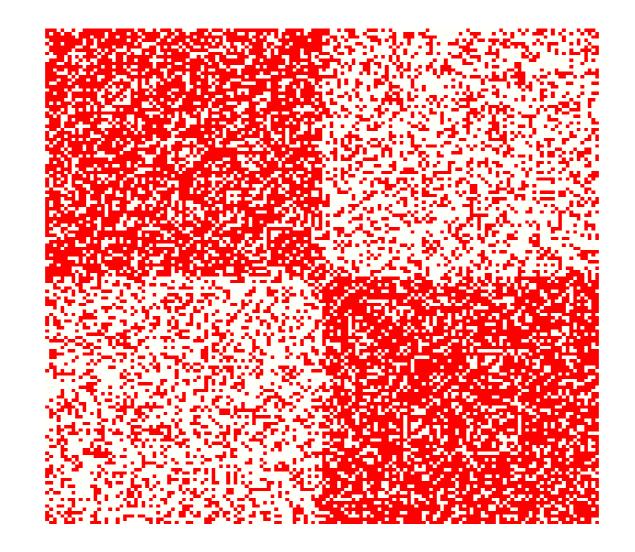
Hidden partition model or stochastic block model (SBM)

- Generate a partition of n nodes: e.g. q groups of size n/q
- Add independently edges between any pair of nodes according to the following probability

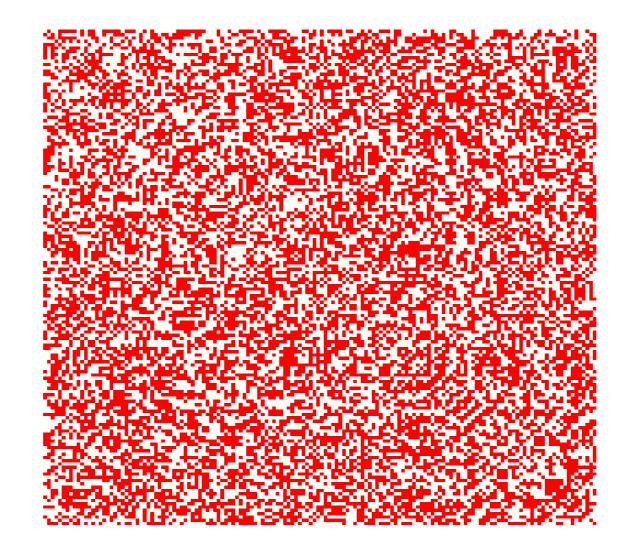
 $\mathbb{P}[(ij) \in E] = \begin{cases} c_{\rm in}/n & \text{same group} \\ c_{\rm out}/n & \text{different groups} \end{cases}$ 

• Assortative model  $c_{in} > c_{out}$ Disassortative model  $c_{in} < c_{out}$ 

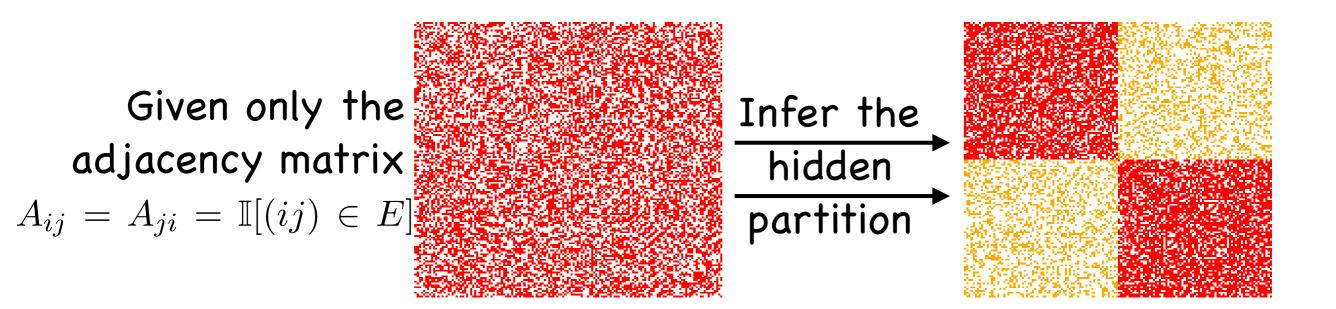




Colors are not provided !



The right ordering neither !!



Hidden (true) partition ->  $x_0 \in \{+1, -1\}^n$ Estimated partition ->  $\hat{x}(G) \in \{+1, -1\}^n$ Quality of inference via the overlap ->  $Q = \frac{1}{n} |\langle \hat{x}(G), x_0 \rangle|$ 

### Assortative SBM with 2 equal-size groups

Relevant parameters and threshold

• Mean degree  $d = \frac{c_{\text{in}} + c_{\text{out}}}{2}$ 

• Signal-to-noise ratio 
$$\lambda = rac{c_{
m in} - c_{
m out}}{2\sqrt{d}}$$

- Bayes optimal threshold  $\lambda_c = 1$ 
  - Impossible detection for  $\lambda < \lambda_c$
  - BP algorithm with Q>0 for  $\lambda>\lambda_c$

Very
 ingenious
 spectral
 methods

[Decelle, Krzakala, Moore, Zdeborova, 2011] [Massoulie, 2013] [Mossel, Neeman, Sly, 2013]

# Maximum Likelihood (ML)

 If no information on the generative model is given (apart being assortative and with 2 equal-size groups) a good choice is to <u>maximize the likelihood</u>

maximize 
$$\sum_{i,j} A_{i,j} x_i x_j$$

subject to 
$$x_i \in \{+1, -1\}$$
 and  $\sum_i x_i = 0$ 

• NP-hard problem

## Lagrangian formulation

• Maximize 
$$\sum_{i,j} A_{ij} x_i x_j - \eta \left(\sum_i x_i\right)^2$$
 over  $x \in \{+1, -1\}^n$ 

- A good choice is  $~\eta \geq d/n$
- For  $\eta = d/n$  the <u>centered</u> adjacency matrix appears

$$A_{ij}^{\rm cen} = A_{ij} - d/n$$

• Maximize  $\sum_{i,j} A_{ij}^{ ext{cen}} x_i x_j$  over  $oldsymbol{x} \in \{+1,-1\}^n$ 

# Spectral relaxation (PCA)

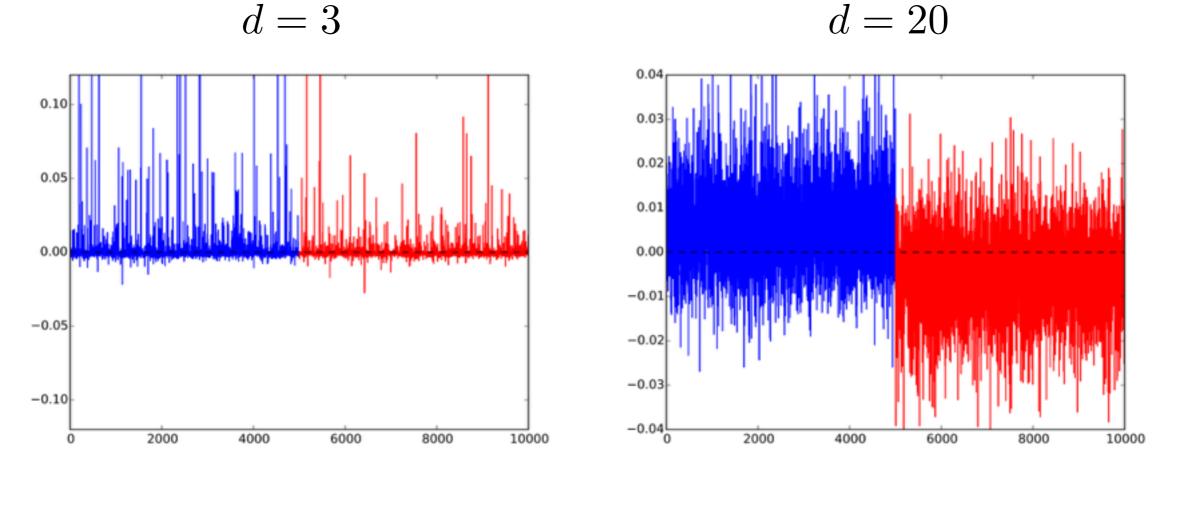
- PCA on  $A^{ ext{cen}}$  relaxes the constraint  $x \in \{+1, -1\}^n$ and maximizes  $\sum_{i,j} A^{ ext{cen}}_{ij} x_i x_j$  over  $x \in \mathbb{R}^n$
- Computes the eigenvector of the largest eigenvalue  $oldsymbol{v}_1(oldsymbol{A^{cen}})$
- Estimates the partition via a projection on  $oldsymbol{x} \in \{+1,-1\}^n$

 $\hat{\boldsymbol{x}}^{\scriptscriptstyle ext{PCA}} = ext{sign}(\boldsymbol{v}_1(\boldsymbol{A^{ ext{cen}}}))$ 

- It is good as long as components of  $m{v}_1(A^{ ext{cen}})$  have similar moduli/intensities

### Spectral relaxation fails on sparse graphs

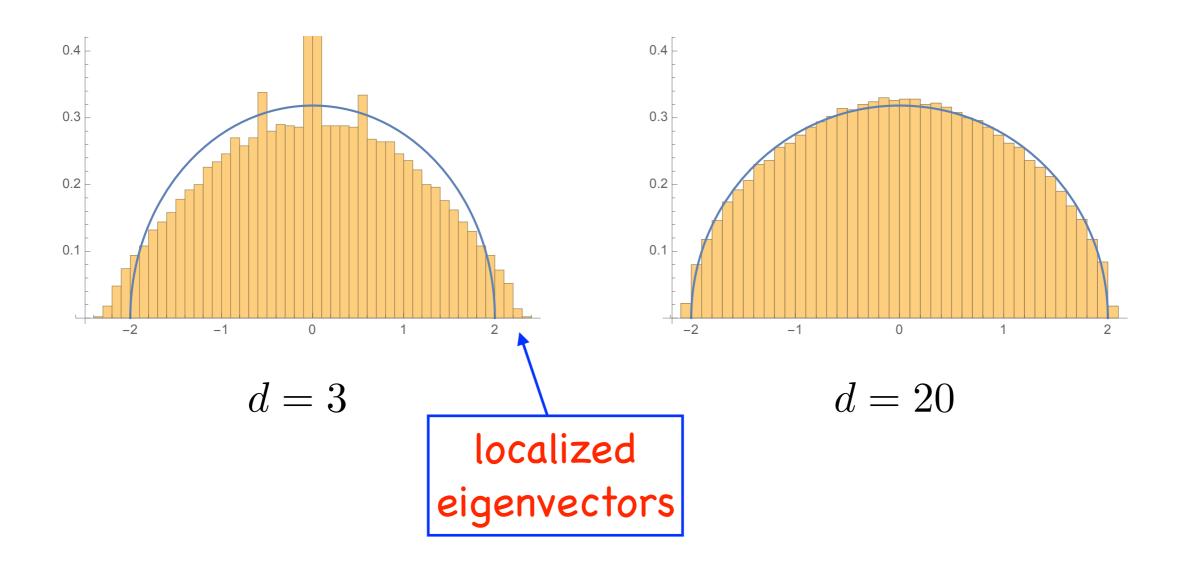
$$n = 10^4 \quad \lambda = 1.2$$



 $oldsymbol{v}_1(oldsymbol{A^{ extbf{cen}}})$ 

## Why PCA fails?

$$rac{1}{\sqrt{d}}A^{ ext{cen}} = rac{\lambda}{n} \, x_{0} x_{0}^{\mathsf{T}} + \, W$$



## Other spectral methods

- Compute eigenvalues and eigenvectors of some matrix related to the adjacency matrix A
- Fail for the same reason -> <u>eigenvectors localization</u>
- Laplacian L=D-A with D being the diagonal matrix of degrees
- Normalized Laplacian  $\mathcal{L} = D^{-1/2} L D^{-1/2}$
- Shown to be sub-optimal in the sparse regime
  [Kawamoto, Kabashima, 2015]

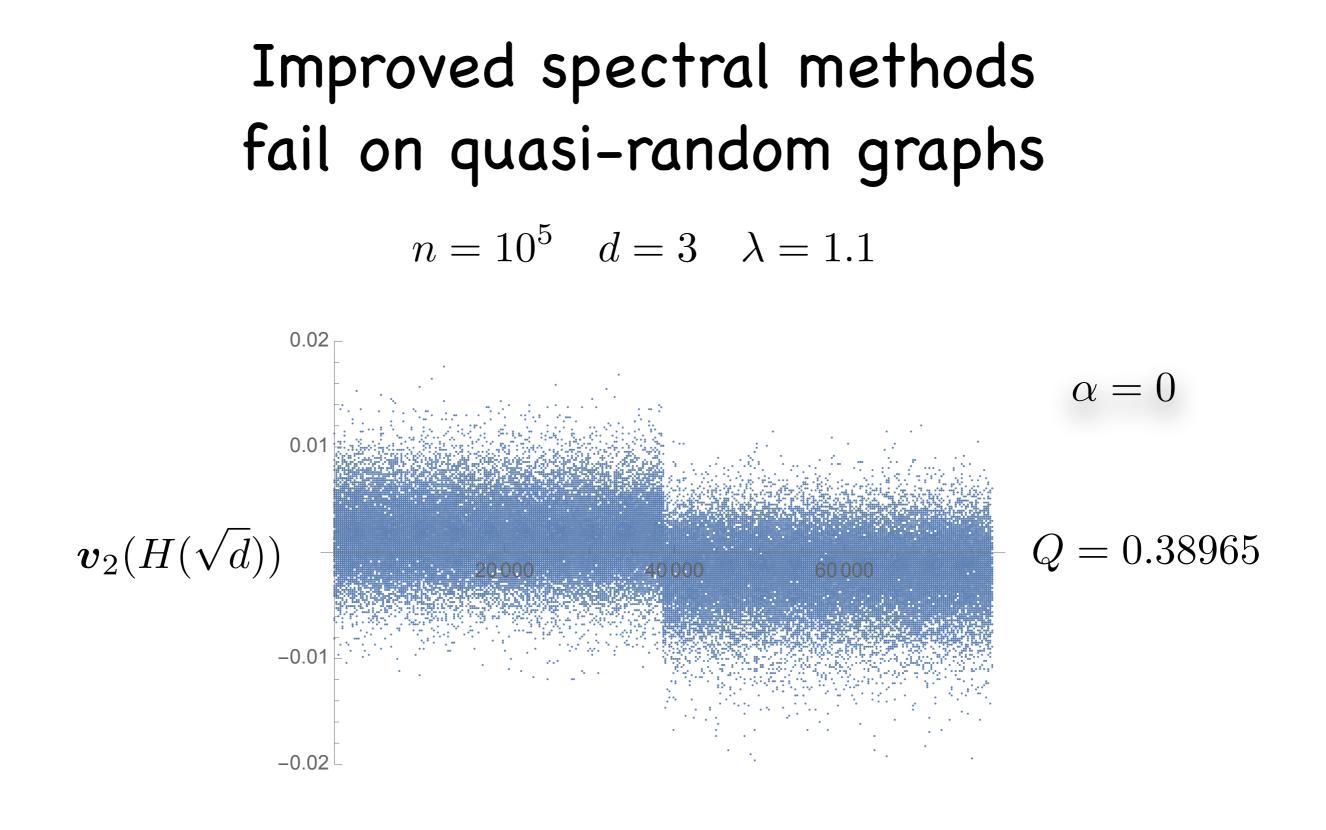
$$\lambda_c^{\text{Lap}} = \sqrt{\frac{d}{d-1}} > 1$$

## Improved spectral methods

- Non-backtracking matrix [Krzakala, Moore, Mossel, Neeman, Sly, Zdeborova, Zhang, 2013]
  - seems to avoid localization around large degree nodes
  - optimal for the SBM
  - complex spectrum, not easy to compute
- Bethe Hessian [Saade, Krzakala, Zdeborova, 2014]  $H(r) = (r^2 1)\mathbb{1} rA D$ 
  - symmetric matrix, real spectrum
  - easier to use
  - optimal for the SBM with  $r = \sqrt{d}$

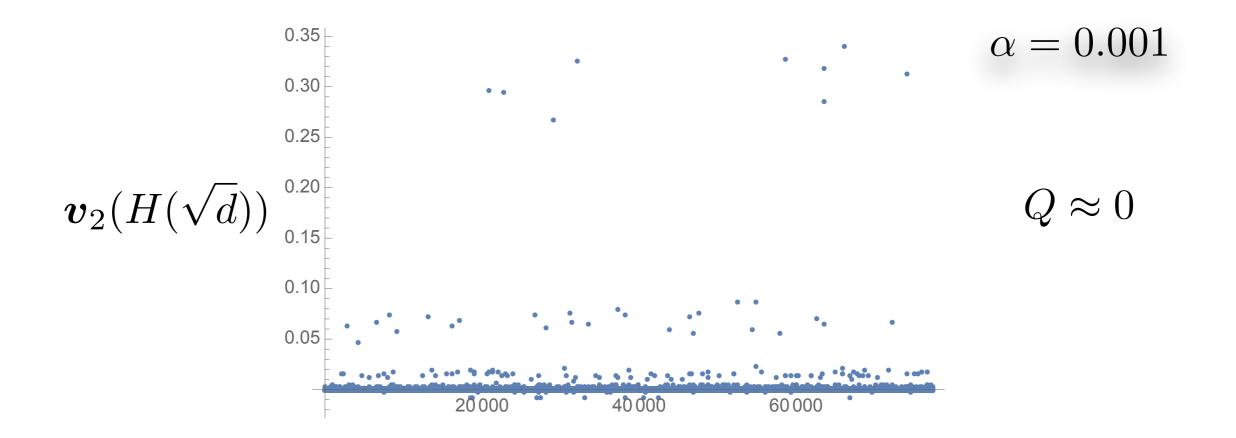
## Quasi-random graphs

- Generate a graph according to the SBM
- Choose a subset S of vertices of size  $|S|=\alpha n$
- For each vertex in  ${\cal S}$  connect all its neighbours
- The number of edges increases by  $\sim \alpha d^2 n/2$  i.e. by a fraction  $\sim \alpha d$
- A robust inference method should work also for  $\alpha>0$  at least in the regime  $\,\alpha\ll 1/d\,$

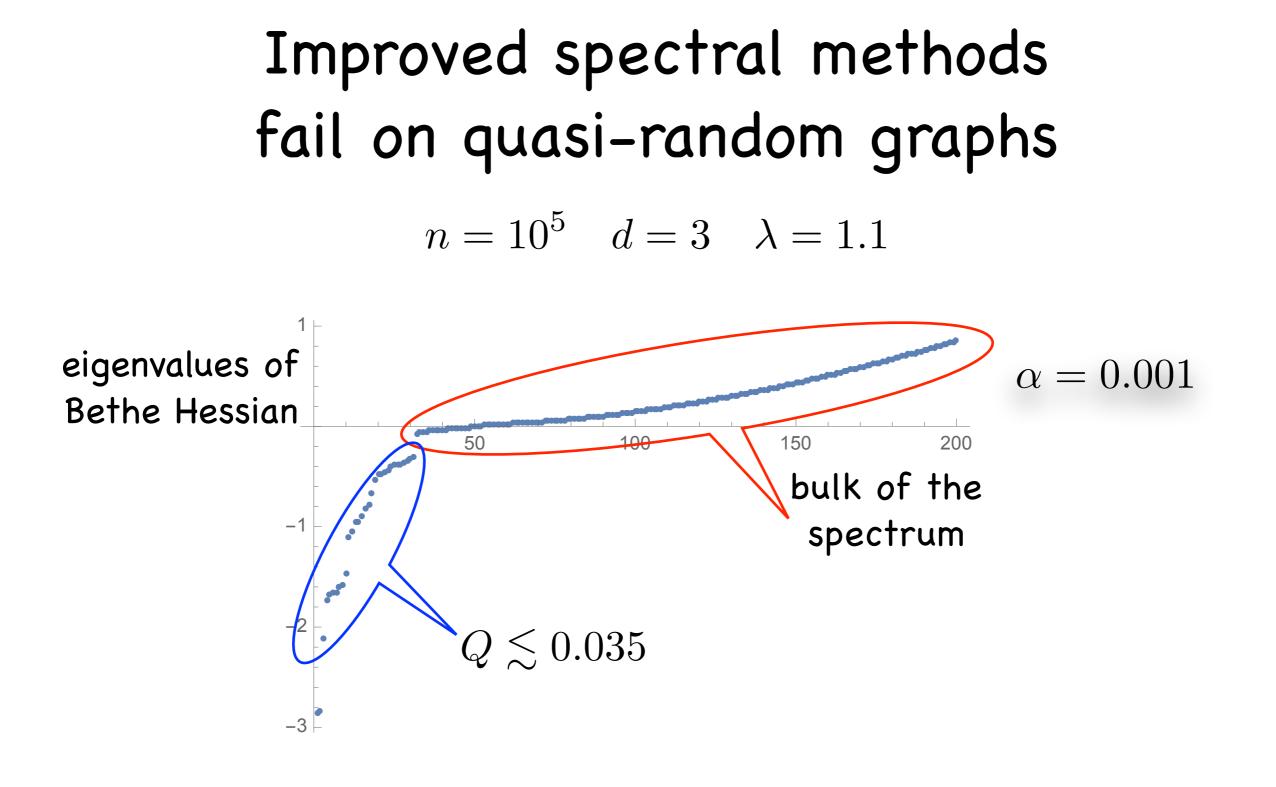


(on the 2-core 77336 nodes and 132763 edges)

Improved spectral methods fail on quasi-random graphs  $n = 10^5$  d = 3  $\lambda = 1.1$ 



(on the 2-core 77336 nodes and 133185 edges)



### SDP: a better relaxation?

• Maximize 
$$\sum_{i,j} A_{ij}^{\text{cen}} x_i x_j$$
 over  $x \in \{+1, -1\}^n$   
it is equivalent to maximize  $\sum_{i,j} A_{ij}^{\text{cen}} X_{ij} \equiv \langle A^{\text{cen}}, X \rangle$   
subject to  $X \in \mathbb{R}^{n \times n}$ ,  $X \succeq 0$  (i.e. all eigenvalues >= 0)

$$X_{ii} = 1$$
 and  $\boldsymbol{X}$  being of rank 1

- SDP <u>relaxes the rank</u> and maximizes  $\langle A^{
  m cen},X
  angle$ over the <u>convex</u> space of positive semidefinite matrices
- The maximizer is a matrix of rank m with  $m \in [1, n]$  to be projected back on a rank 1 matrix...

$$oldsymbol{X}^{ ext{opt}} \longrightarrow oldsymbol{\hat{x}}^{ ext{SDP}} (oldsymbol{\hat{x}}^{ ext{SDP}})^{\mathsf{T}}$$

## SDP-based algorithm

- Maximize  $\langle A^{
m cen},X
angle$  over rank-m matrices = correlation matrices between m-components variables of unit norm

$$C_{ij} = \underline{x}_i \cdot \underline{x}_j$$
, with  $\underline{x}_i \in \mathbb{R}^m$ ,  $\|\underline{x}_i\|^2 = \underline{x}_i \cdot \underline{x}_i = 1$ 

• Maximize  $\sum_{(ij)\in E} \underline{x}_i \cdot \underline{x}_j$  subject to  $\sum_i \underline{x}_i = \underline{0}$ 

by greedy T=0 dynamics (very fast! no gradient used)

- Given the maximizer  $\underline{x}^* = \{\underline{x}_1^*, \dots, \underline{x}_n^*\}$ compute the empirical covariance matrix (m x m)  $\Sigma_{jk} = \frac{1}{n} \sum_{i=1}^n (\underline{x}_i^*)_j (\underline{x}_i^*)_k$
- Project on its principal eigenvector  $\hat{x}_i^{\text{SDP}} = \operatorname{sign}(\underline{x}_i \cdot \underline{v}_1)$

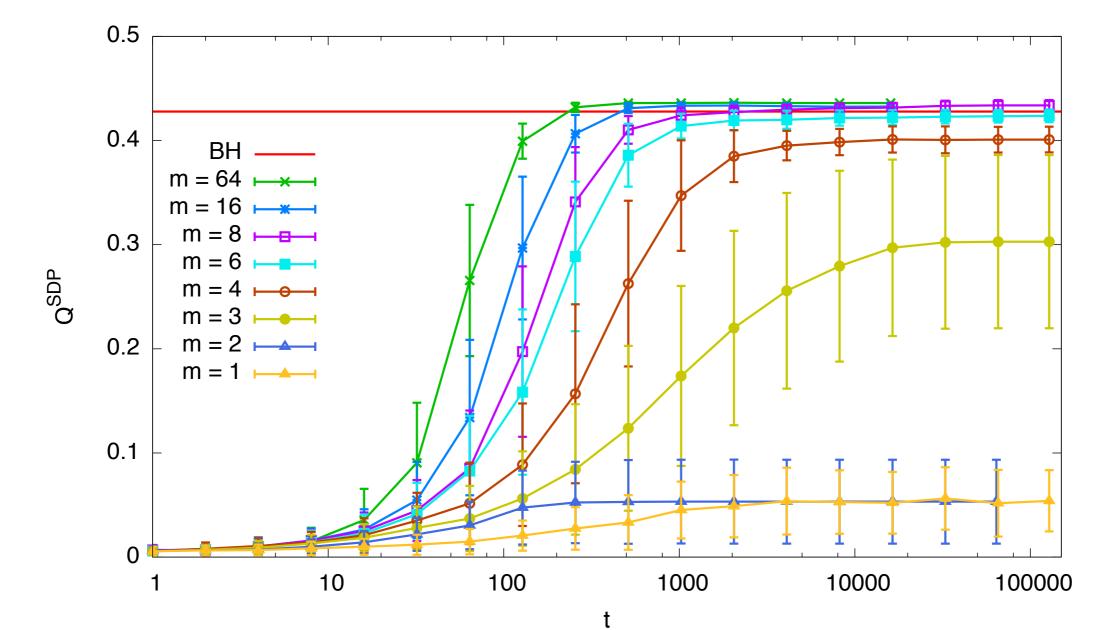
http://web.stanford.edu/~montanar/SDPgraph/

## SDP-based algorithm

- <u>Algorithm complexity</u>  $O(n m t_{conv})$  and <u>quality of inference</u> do depend on m
  - m=1 -> ML, very rough objective function, NP-hard
  - m=n -> SDP, convex objective function no local maxima for  $m>\sqrt{2n}$  [Burer, Monteiro, 2003]
  - m>1, but small -> smooth enough objective function ? local minima are "close enough"  $O(m^{-1/2})$ to global minimum [Montanari, 2016]
- Running times grows very mildly with m and n e.g. if stopping rule is max variation < 10^{-3} ->  $t_{\rm conv} \propto n^{0.22}$

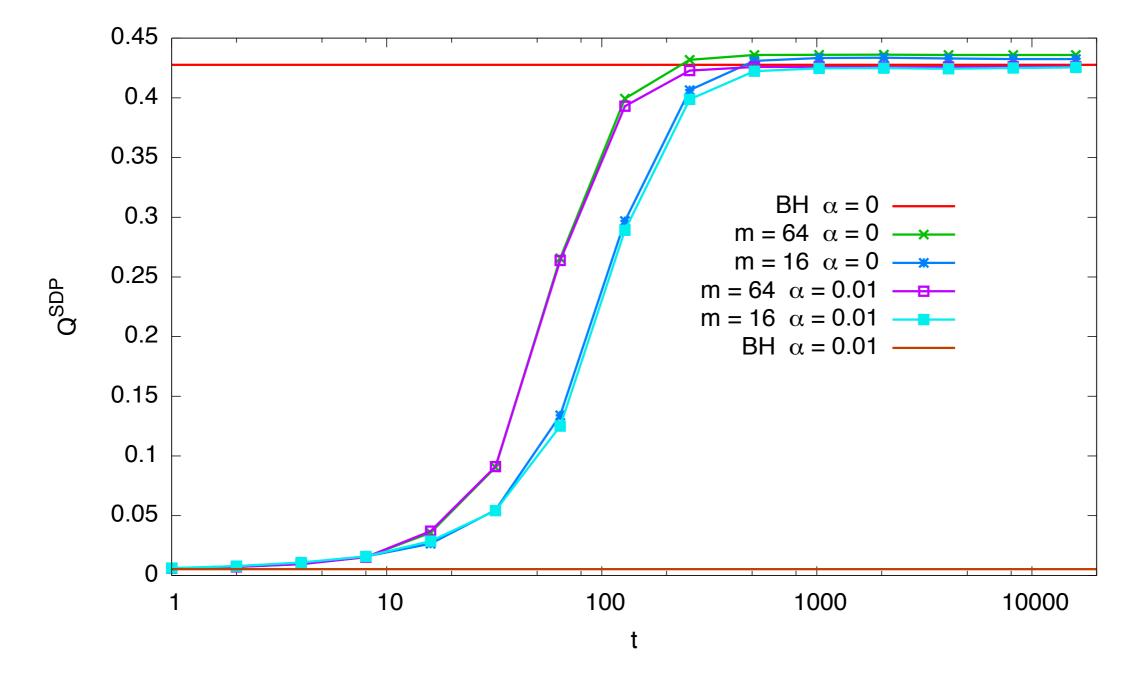
#### Small m values are fine!

$$n = 4 \cdot 10^4 \quad d = 3 \quad \lambda = 1.1 \quad \alpha = 0.0$$



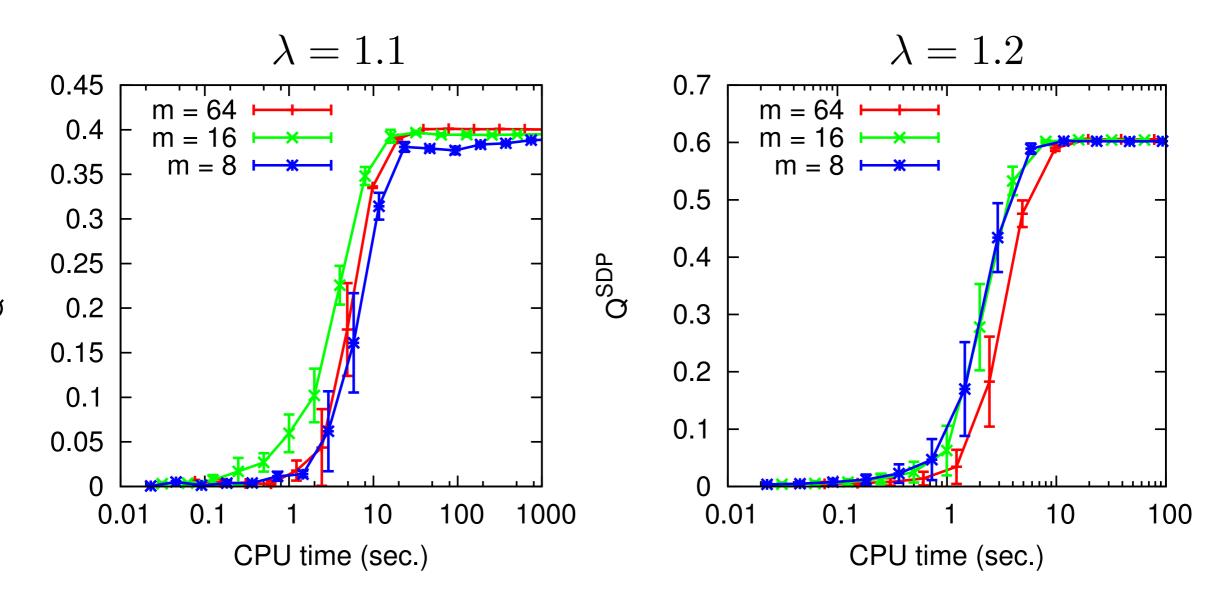
#### The algorithm is very robust!

$$n = 4 \cdot 10^4 \quad d = 3 \quad \lambda = 1.1$$



#### The algorithm is very fast!

$$n = 10^5$$
  $d = 3$ 



Q<sup>SDP</sup>

# SDP optimality

- Analytical predictions on SDP-based hidden partition detection (signal recovery) in the limit  $m\to\infty$ 

undetectable	, detectable	
$Q^{\scriptscriptstyle m SDP}pprox 0$	$\lambda_c^{\text{SDP}}  Q^{\text{SDP}} > 0$	

• A simpler synchronization problem:

$$\boldsymbol{Y} = \frac{\lambda}{n} \boldsymbol{x_0} \boldsymbol{x_0}^* + \boldsymbol{W}$$

- Recovery  $oldsymbol{x}_0$  given the noisy relative positions in  $oldsymbol{Y}$
- Different models:  $oldsymbol{x}_0 \in \mathbb{R}^n$   $W_{ij} \sim \mathsf{N}(0, 1/n)$

$$\boldsymbol{x}_0 \in \mathbb{C}^n \qquad W_{ij} \sim \mathsf{CN}(0, 1/n)$$

#### Different estimators

- Bayes optimal  $\hat{m{x}}^{ ext{Bayes}}(m{Y}) = \mathbb{E}ig\{m{x} \, \big| \, (\lambda/n) m{x} m{x}^* + m{W} = m{Y}ig\}$
- Maximum likelihood  $\hat{x}^{\text{ML}}(Y) = c(\lambda) \operatorname{argmax}_{x \in \{+1,-1\}^n} \langle x, Yx \rangle$ 
  - SDP maximize  $\langle \mathbf{X}, \mathbf{Y} \rangle$ , subject to  $\mathbf{X} \succeq 0$ ,  $X_{ii} = 1 \quad \forall i \in [n]$  $\hat{\mathbf{x}}^{\text{SDP}}(\mathbf{Y}) = \sqrt{n} c^{\text{SDP}}(\lambda) \mathbf{v}_1(\mathbf{X}_{\text{opt}}(\mathbf{Y}))$ argmax $\underline{x} \sum_{i,j} \text{Re}(Y_{ij}\underline{x}_i \cdot \underline{x}_j)$   $\underline{x}_i \in \mathbb{F}^m$ ,  $||\underline{x}_i|| = 1$

## Statistical physics approach

• <u>Unified framework</u>: statistical physics models with m-component variables:  $\underline{x}_i \in \mathbb{F}^m$ ,  $||\underline{x}_i|| = 1$ 

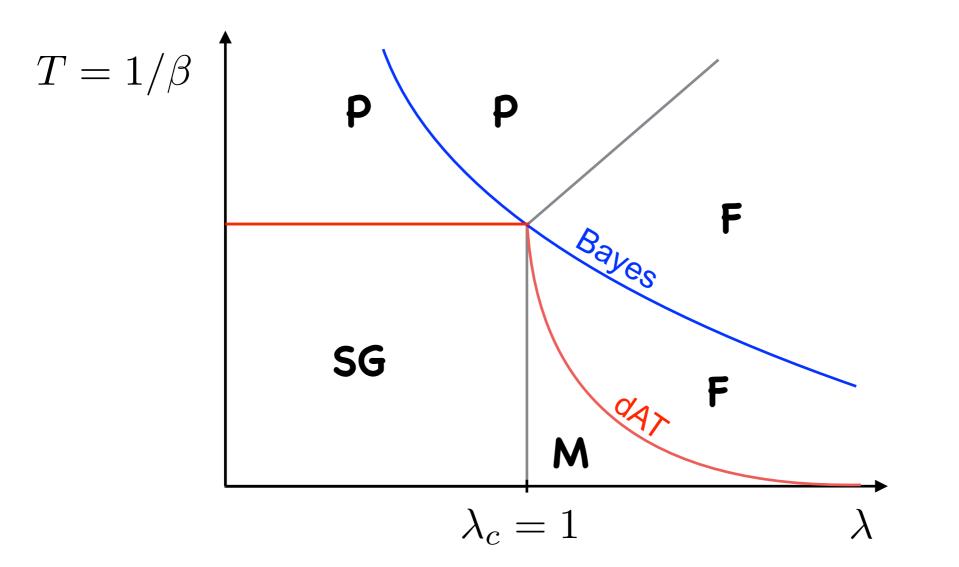
$$P(\underline{x}) = \frac{1}{Z} \exp\left[2m\beta \sum_{i < j} \operatorname{Re}(Y_{ij}\underline{x}_i \cdot \underline{x}_j)\right]$$

• Bayes: 
$$m = 1$$
,  $\beta = \begin{cases} \lambda/2 & \text{if } \mathbb{F} = \mathbb{R} \\ \lambda & \text{if } \mathbb{F} = \mathbb{C} \end{cases}$ 

- ML:  $m = 1, \quad \beta \to \infty$
- SDP:  $m \to \infty$ ,  $\beta \to \infty$

# Statistical physics approach

Ising variables (m=1), dense graph Sherrington-Kirkpatrick model  $H = -\sum_{i < j} J_{ij} s_i s_j$   $s_i \in \{-1, 1\}$  $J_{ij} \sim N(\lambda/n, 1/n)$ 



P: Q=0 easy
F: Q>0 easy
SG: Q=0 hard
M: Q>0 hard

## Statistical physics approach

• Ansatz for the marginals in m-component dense models

$$P_i(\underline{x}_i) = \frac{1}{Z_i} \exp\left[2m\beta(\underline{\xi}_i^\mathsf{T}\underline{x}_i + \underline{x}_i^\mathsf{T}\boldsymbol{C}_i\underline{x}_i)\right]$$

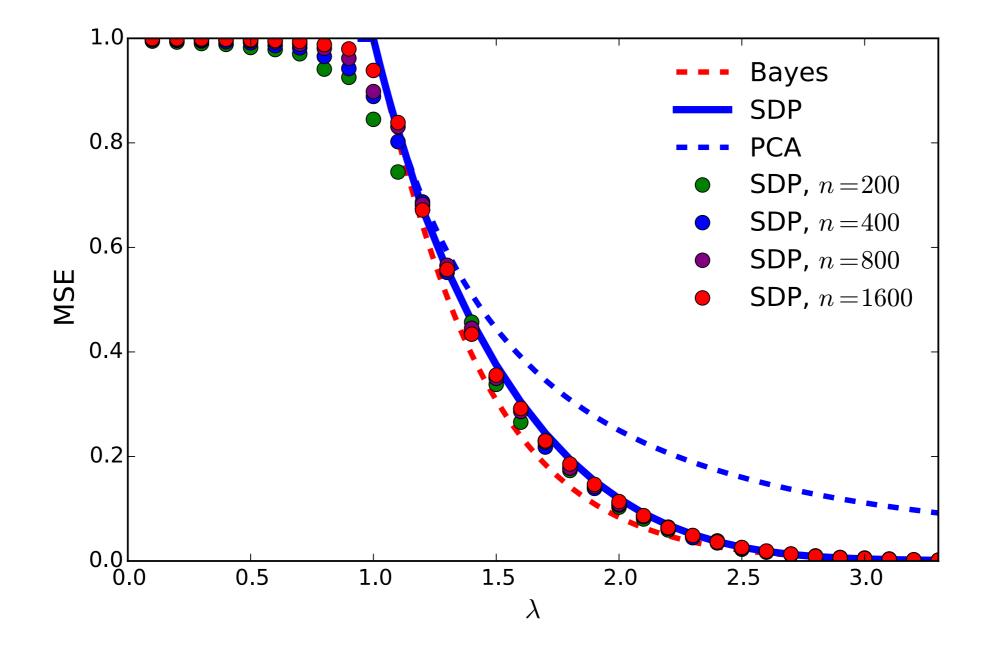
$$\underline{x}_i \in \mathbb{F}^m , ||\underline{x}_i|| = 1 \qquad \underline{\xi}_i \sim \mathcal{N}(\underline{\mu}, \mathbf{Q}) \qquad \mathbf{C}_i = \mathbf{C}$$

• Self consistency equations in the dense case

$$\underline{\mu} = \lambda \mathbb{E}[\langle \underline{x} \rangle]$$
$$Q = \mathbb{E}[\langle \underline{x} \rangle \langle \underline{x}^{\mathsf{T}} \rangle]$$
$$C = \beta m \mathbb{E}[\langle \underline{x} \underline{x}^{\mathsf{T}} \rangle - \langle \underline{x} \rangle \langle \underline{x}^{\mathsf{T}} \rangle]$$

#### Analytical solution: dense real case

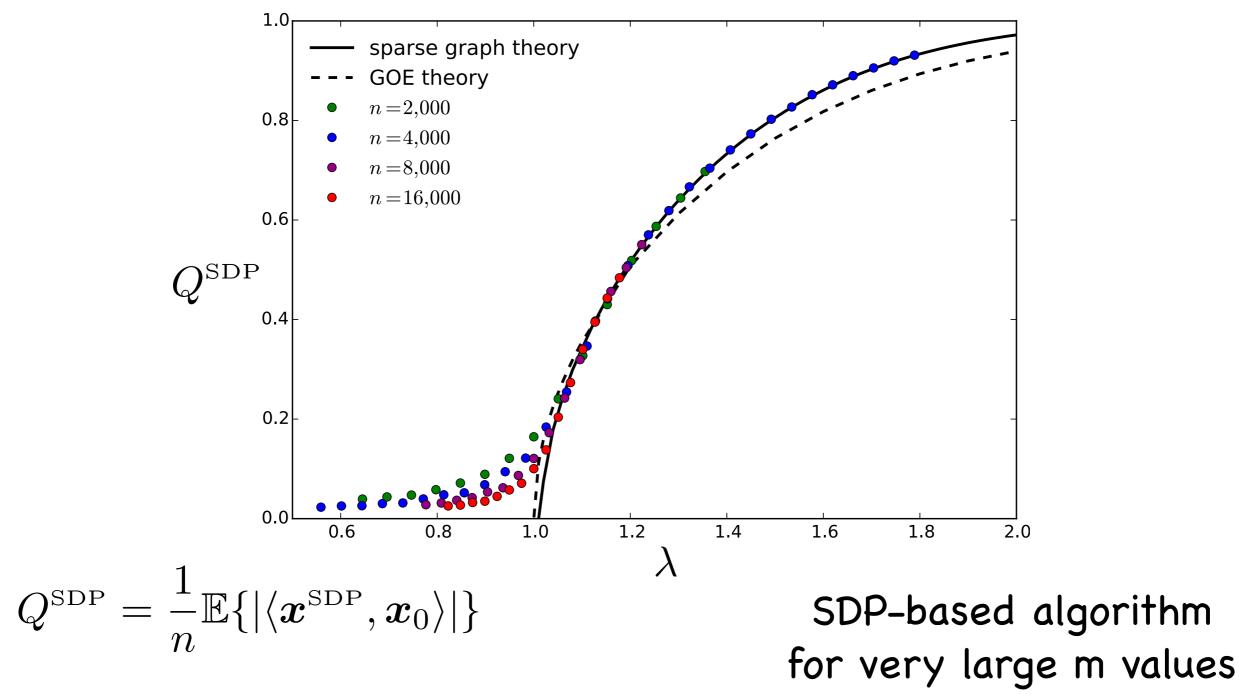
$$MSE_{n}(\hat{\boldsymbol{x}}) \equiv \frac{1}{n} \mathbb{E} \left\{ \min_{s \in \{+1,-1\}} \left\| \hat{\boldsymbol{x}}(\boldsymbol{Y}) - s \, \boldsymbol{x}_{0} \right\|_{2}^{2} \right\}$$



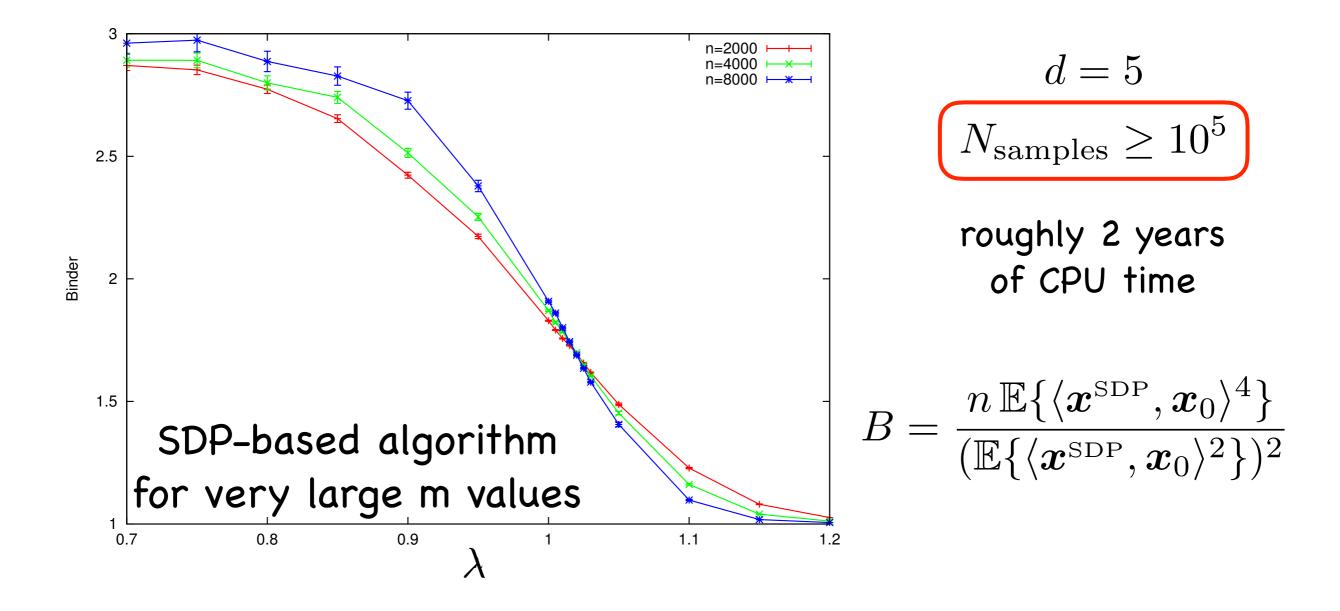
• Run the SDP-based algorithm for very large m values

• Approximate ansatz (exact in the large d limit)

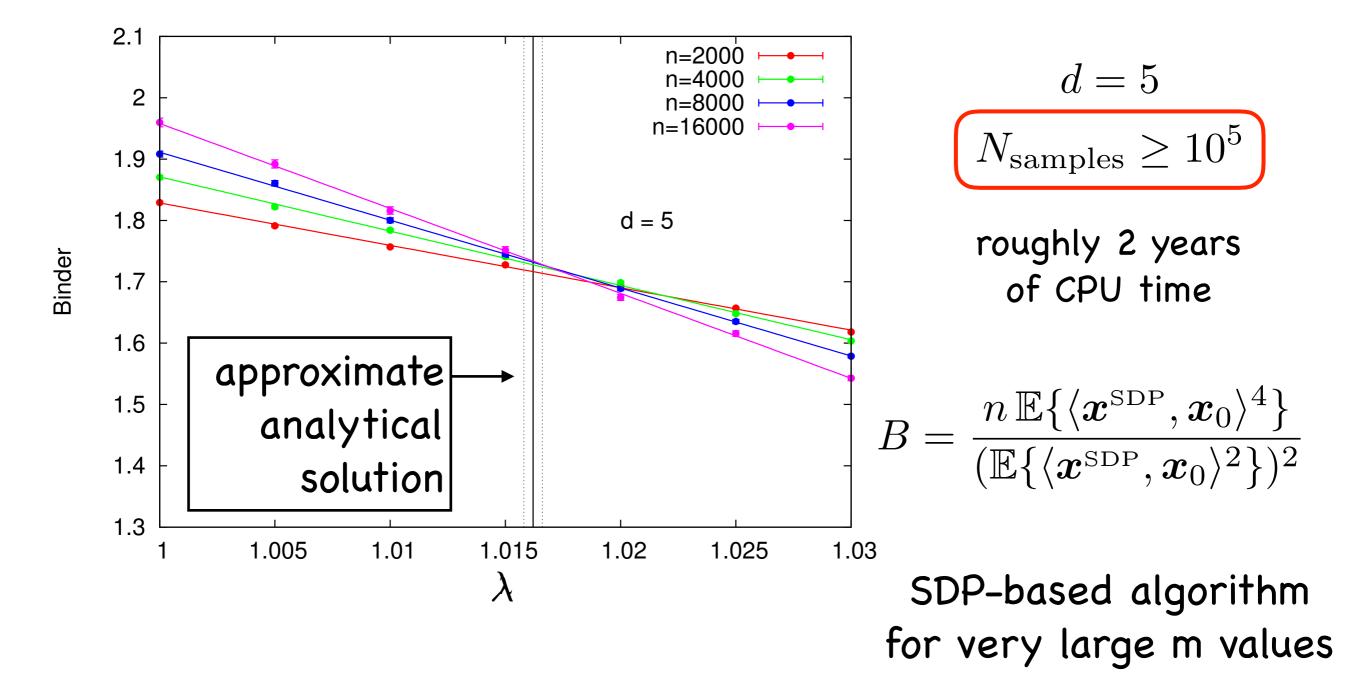




- Crossing of the Binder cumulants to locate exactly  $\lambda_c^{ ext{SDP}}$ 



- Crossing of the Binder cumulants to locate exactly  $\lambda_c^{ ext{SDP}}$ 



 In the recovery phase we assume the O(m) symmetry to break along the first component, while preserving O(m-1)

$$\underline{x}_i = (s_i, \boldsymbol{\tau}_i), \, s_i \in \mathbb{R}, \, \boldsymbol{\tau}_i \in \mathbb{R}^{m-1}$$

• We write the marginal for  $\underline{x}_i$  as

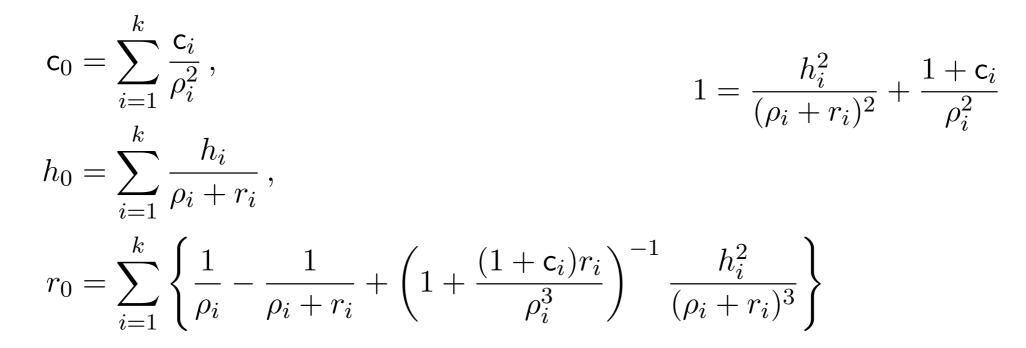
 $\exp\left\{2\beta\sqrt{mc_i}\langle \boldsymbol{z}_i,\boldsymbol{\tau}_i\rangle+2\beta mh_i\,s_i-\beta mr_is_i^2+O_m(1)\right\}\delta\left(s_i^2+\|\boldsymbol{\tau}_i\|_2^2-1\right)$ 

with  $oldsymbol{z}_i \sim \mathsf{N}(0, \mathrm{I}_{m-1})$ 

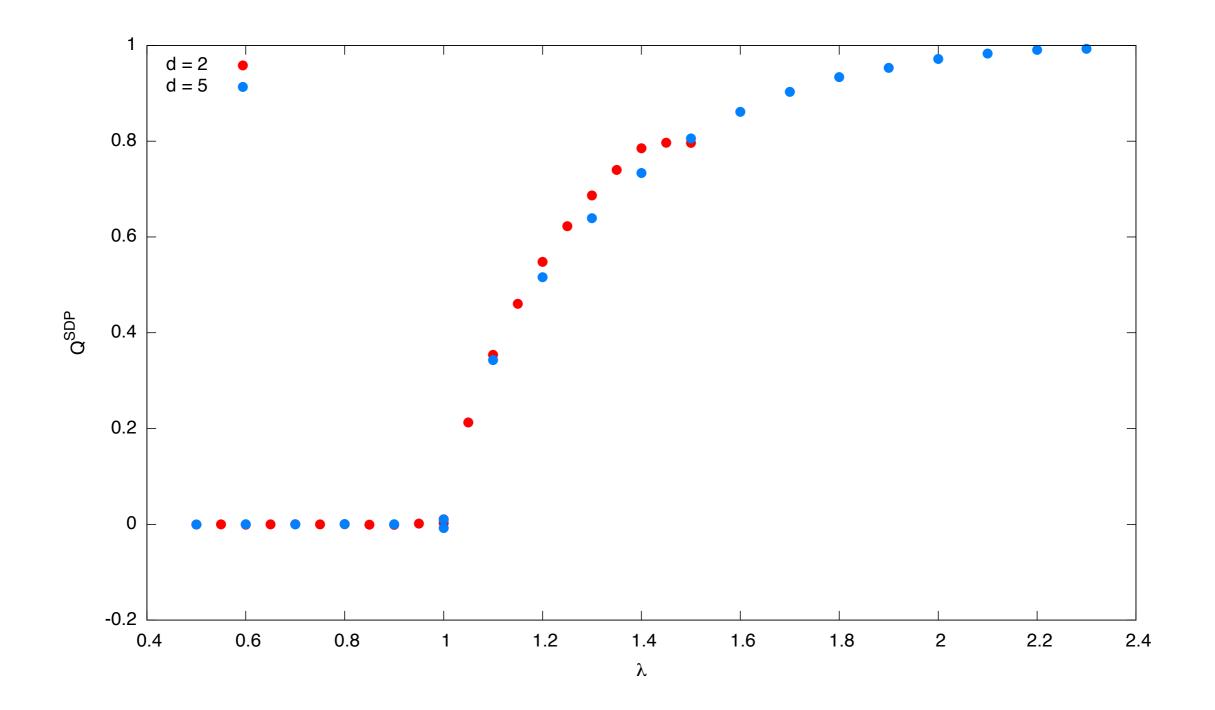
- Approximate because the  $z_i$  are correlated
- It should be valid in the limits  $d \to 1$  and  $~d \to \infty$

$$\exp\left\{2\beta\sqrt{m}\mathbf{c}_{i}\left\langle\boldsymbol{z}_{i},\boldsymbol{\tau}_{i}\right\rangle+2\beta mh_{i}s_{i}-\beta mr_{i}s_{i}^{2}+O_{m}(1)\right\}\delta\left(s_{i}^{2}+\|\boldsymbol{\tau}_{i}\|_{2}^{2}-1\right)$$

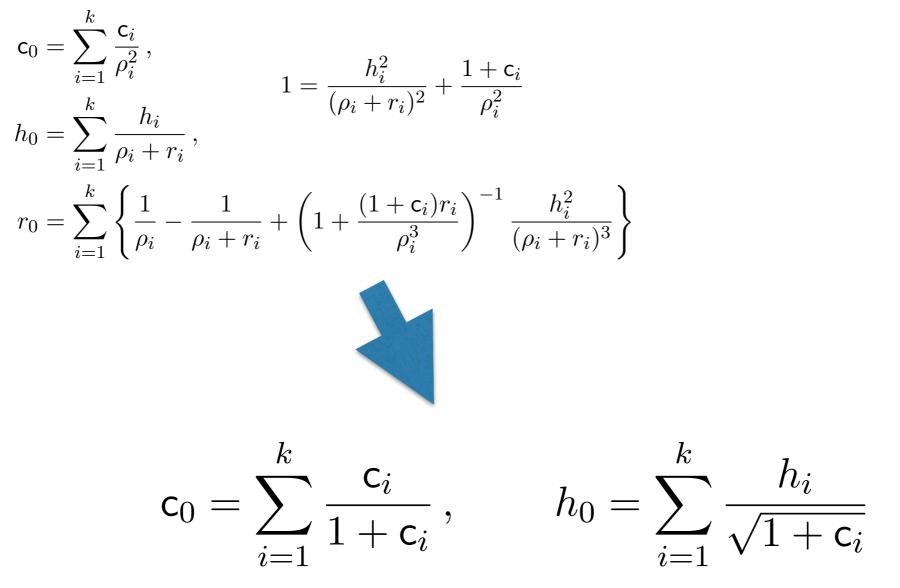
Cavity method -> self consistency equation for marginals

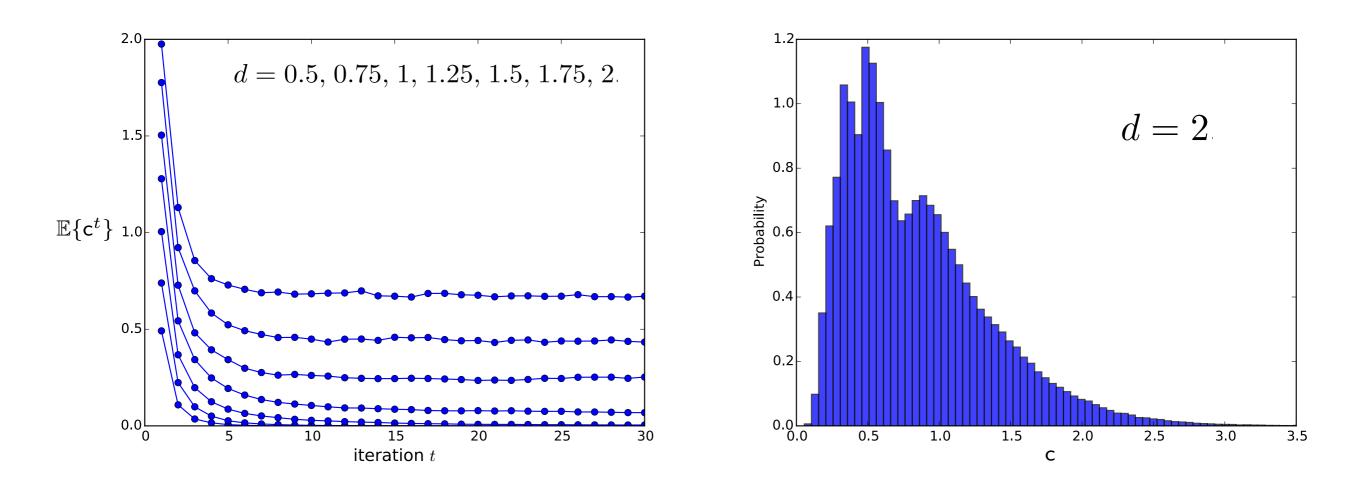


- Solve by population dynamics
- At the fixed point  $Q^{\text{SDP}} = \mathbb{E}[\operatorname{sign}(h^*)]$

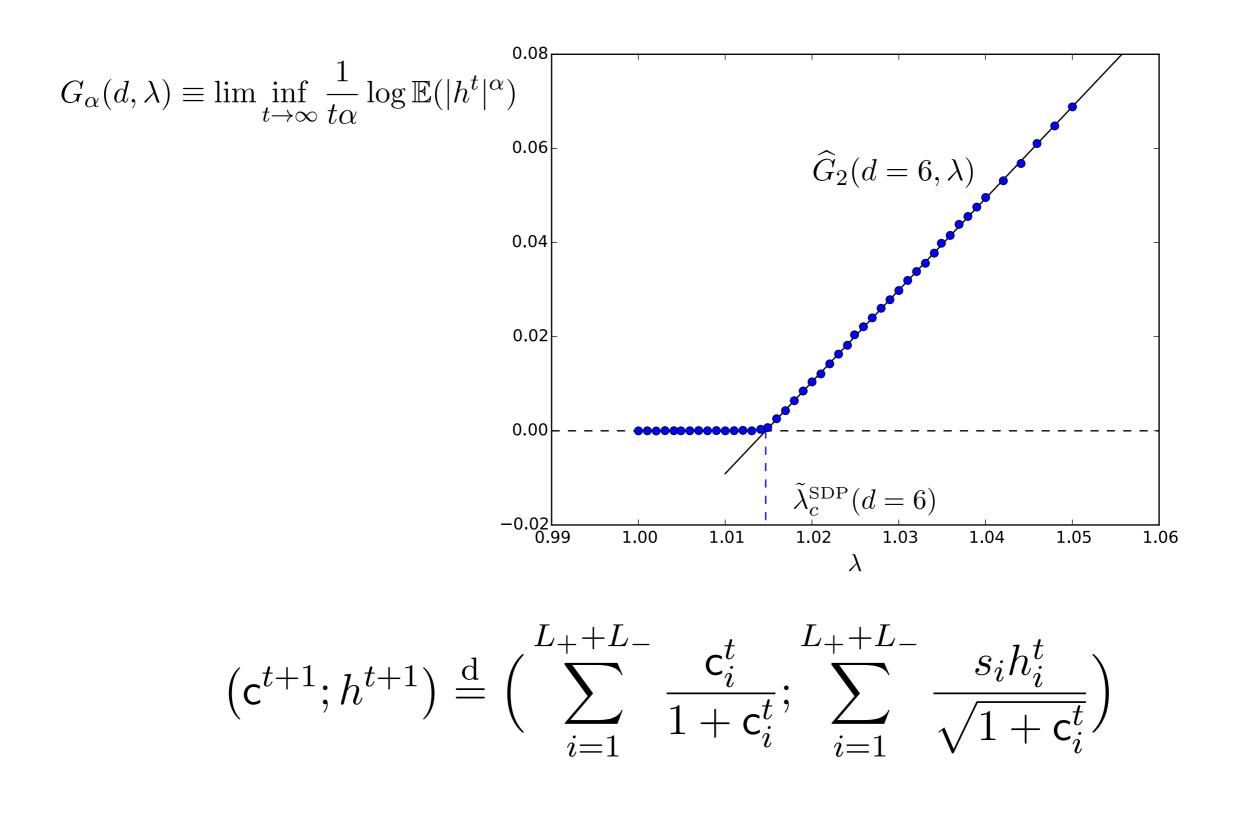


• To linear order in  $h \implies r_i = 0$ 

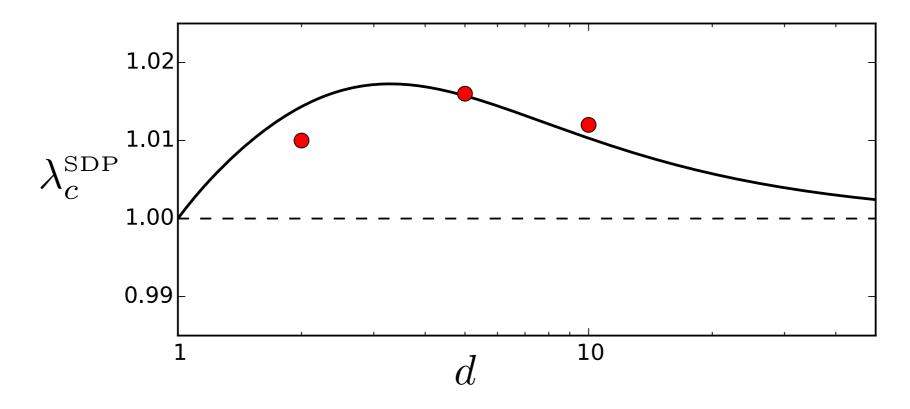




$$\left(\mathbf{c}^{t+1}; h^{t+1}\right) \stackrel{\mathrm{d}}{=} \left(\sum_{i=1}^{L_{+}+L_{-}} \frac{\mathbf{c}_{i}^{t}}{1+\mathbf{c}_{i}^{t}}; \sum_{i=1}^{L_{+}+L_{-}} \frac{s_{i}h_{i}^{t}}{\sqrt{1+\mathbf{c}_{i}^{t}}}\right)$$



• SDP at most 2% sub-optimal!



- Red points: numerical solution of the replica/cavity equations (crossing of Binder cumulants)
- Black line: approximated analytical solution

### Take-home messages

- SDP relaxations are very effective:
  - robust and quasi-optimal
  - may outperform spectral relaxations
- Better than SDP are SDP-inspired algorithms (small m) http://web.stanford.edu/~montanar/SDPgraph/
- It is worth studying the statistical physics of models with m-component variables:
  - unifying framework to study and solve several estimators in statistical inference
  - different physics, better algorithms