

# An Isomorphism between Parameterized Complexity and Classical Complexity, for both Time and Space

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## Exponential complexity

Find exponential time algorithms for NP-hard problems beating the brute-force search.

### Conjecture (ETH)

*There is no algorithm solving 3SAT in time  $2^{o(n)}$ .*

## Parameterized complexity

Find algorithms for NP-hard problems whose superpolynomial behavior is confined in some parameter.

Conjecture (FPT  $\neq$  W[1])

*There is no algorithm solving  $k$ -CLIQUE in time  $f(k) \cdot n^{O(1)}$ , i.e.,  $k$ -CLIQUE is not fixed-parameter tractable.*

## The connection

Theorem (Downey and Fellows, 1999)

ETH *implies*  $\text{FPT} \neq \text{W}[1]$ .

The converse has been a major open problem, and seems hard to prove:

Theorem (Chen et. al, 2004)

ETH *implies that*  $k\text{-CLIQUE}$  *is not decidable in time*  $f(k) \cdot n^{o(k)}$ .

## An equivalence

Theorem (C. and Grohe, 2007)

$\text{FPT} = \text{W}[1]$  if and only if  $k\text{-CLIQUE}$  is decidable in time

$$2^{o(k \cdot \log n)} \cdot n^{O(1)}.$$

Remark

The brute-force algorithm for  $k\text{-CLIQUE}$  has running time

$$n^{k+O(1)} = 2^{k \cdot \log n} n^{O(1)}.$$

## Another equivalence

Theorem (Cai and Juedes, 2003)

ETH fails if and only if the *miniaturization* of  $3S_{AT}$  is fixed-parameter tractable.

Anything Similar in Space Complexity?

## A central problem in classical space complexity

STCONN

*Input:* A directed graph  $G$  and  $s, t \in V(G)$ .

*Problem:* Is there a path from  $s$  to  $t$  in  $G$ ?

### Theorem

1. STCONN is complete for NL.
2. STCONN is decidable in space  $O(\log^2 n)$ , i.e., Savitch's Theorem.

### Question

Can we decide STCONN in space  $o(\log^2 n)$ ?



## Parameterized STCONN

$k$ -STCONN

*Input:* A directed graph  $G$ ,  $s, t \in V(G)$ , and  $k \in \mathbb{N}$ .

*Parameter:*  $k$ .

*Problem:* Is there a path from  $s$  to  $t$  in  $G$  of length  $\leq k$ ?

### Question

Can we decide  $k$ -STCONN in space

$$f(k) + O(\log n)?$$

Equivalently, is  $k$ -STCONN in *parameterized logspace*?

The brute-force algorithm decides  $k$ -STCONN in space  $k \cdot \log n + O(\log n)$ .

Question  $k$ -STCONN  $\in$  DSPACE( $o(k \cdot \log n) + O(\log n)$ )?

*If so, then  $k$ -STCONN is in parameterized logspace.*

Theorem (Savitch, 1969)

*There is an algorithm deciding  $k$ -STCONN in space*

$$O(\log k \cdot \log n).$$

Note  $O(\log k \cdot \log n) \neq o(k \cdot \log n)$  by considering fixed  $k$  and  $n \rightarrow \infty$ .

Question  $k$ -STCONN  $\in$  DSPACE( $o(\log k \cdot \log n) + O(\log n)$ )?

## The space analogy (1)

Theorem (C. and Müller, 2014)

$k\text{-STCONN} \in \text{DSPACE}(f(k) + O(\log n)) \implies \text{STCONN} \in \text{DSPACE}(o(\log^2 n))$ .

Recall  $k\text{-CLIQUE} \in \text{DTIME}(f(k)n^{O(1)}) \implies 3\text{SAT} \in \text{DTIME}(2^{o(n)})$ .

Theorem (C. , Flum, and Müller, 2015)

$k\text{-STCONN} \in \text{DSPACE}(f(k) + o(\log k) \cdot \log n) \implies \text{STCONN} \in \text{DSPACE}(o(\log^2 n))$ .

Recall  $k\text{-CLIQUE} \in \text{DTIME}(f(k)n^{o(k)}) \implies 3\text{SAT} \in \text{DTIME}(2^{o(n)})$ .

## The space analogy (2)

Theorem (C. , Flum, and Müller, 2015)

We have the equivalences:

$$\begin{aligned} k\text{-STCONN} &\in \text{DSPACE}(f(k) + O(\log n)) \\ &\iff k\text{-STCONN} \in \text{DSPACE}(o(k \cdot \log n) + O(\log n)) \\ &\iff k\text{-STCONN} \in \text{DSPACE}(o(\log k \cdot \log n) + O(\log n)) \end{aligned}$$

*Recall*

$$k\text{-CLIQUE} \in \text{DTIME}(f(k)n^{o(k)}) \iff k\text{-CLIQUE} \in \text{DTIME}(2^{o(k \cdot \log n)}n^{O(1)}).$$

## Easy direct proof for the space case

$$k\text{-STCONN} \in \text{DSPACE}(f(k) + O(\log n))$$

$$\iff k\text{-STCONN} \in \text{DSPACE}(o(k \cdot \log n) + O(\log n)) :$$

$$(\Leftarrow) \quad o(k \cdot \log n) \leq f(k) + \log n.$$

( $\Rightarrow$ ) An assumed algorithm for  $k\text{-STCONN}$  can find a path of length at most

$$d := d(n) = f^{-1}(\log n)$$

in logspace. Then we can modify Savitch's algorithm in such a way that every time we divide the path of length at most  $k_i$  into  $d$  sub-paths of length at most

$$k_{i+1} := \frac{k_i}{d}.$$

Thus the total space is bounded

$$O(\log_d k \cdot \log n) = O\left(\frac{\log k}{\log d} \cdot \log n\right) = o(\log k \cdot \log n) = o(k \cdot \log n). \quad \square$$

## Unifying Proofs for

1.  $\text{FPT} = \text{W}[1]$  if and only if  $k\text{-CLIQUE}$  is decidable in time  $2^{o(k \cdot \log n)} \cdot n^{O(1)}$ .
2. ETH fails if and only if the **miniaturization** of  $k\text{-CLIQUE}$  is fixed-parameter tractable.
3.  $k\text{-STCONN} \in \text{DSPACE}(f(k) + O(\log n))$  if and only if  $k\text{-STCONN} \in \text{DSPACE}(o(k \cdot \log n) + O(\log n))$ .

# The Miniaturization Isomorphism

## Parameterization vs. Size Measure

Let  $Q \subseteq \Sigma^*$  be a classical problem. A **parameterization**  $\kappa : \Sigma^* \rightarrow \mathbb{N}$  and a **size measure**  $\nu : \Sigma^* \rightarrow \mathbb{N}$  are both logspace computable functions.

- The parameter  $\kappa(x)$  is supposed to be much smaller than  $|x|$ .
- The size measure  $\nu(x)$  is supposed to be the length of an NP-witness of  $x$ .

### Example

1.  $k$ -CLIQUE:  $\kappa(G, k) := k$  or  $\nu(G, k) := k \cdot \log n$ .
2.  $k$ -STCONN:  $\kappa(G, k) := k$  or  $\nu(G, k) := k \cdot \log n$ .
3. 3SAT:  $\nu(\alpha) := \#\text{var}(\alpha)$  or  $\nu(\alpha) := \#\text{clause}(\alpha)$ .



## Tractability for time complexity

	Parameterized Complexity	Classical Complexity
Tractability	$(Q, \kappa) \in \text{FPT}$ i.e., $\text{DTIME}(f(\kappa(x)) x ^{O(1)})$	$(Q, \nu) \in \text{SUBEXP}$ i.e., $\text{DTIME}(2^{o(\nu(x))} x ^{O(1)})$
Intractability	$(Q, \kappa) \in \text{XP}$ i.e., $\text{DTIME}( x ^{f(\kappa(x))})$	$(Q, \nu) \in \text{EXP}$ i.e., $\text{DTIME}(2^{O(\nu(x))} x ^{O(1)})$

1. EXP: enumerate all NP-witnesses for  $x$ .
2. SUBEXP: avoid the enumeration.

## Reductions

	Parameterized Complexity	Classical Complexity
many-one	fpt-reduction	serf-reduction
many-to-many	fpt Turing reduction	serf Turing reduction

1. FPT and XP are closed under fpt- and fpt Turing reductions.
2. SUBEXP and EXP are closed under serf- and serf Turing reductions.

Lemma (Impagliazzo, Paturi, and Zane, 2001)

$(3SAT, \#var(\alpha))$  is reducible to  $(3SAT, \#clause(\alpha))$  by a serf Turing reduction.

## Tractability for space complexity

	Parameterized Complexity	Classical Complexity
Tractability	$(Q, \kappa) \in \text{para-L}$ i.e., $\text{DSPACE}(f(\kappa(x)) + O(\log  x ))$	$(Q, \nu) \in \text{SUBLIN}$ i.e., $\text{DSPACE}(o(\nu(x)) + O(\log  x ))$
Intractability	$(Q, \kappa) \in \text{XL}$ i.e., $\text{DSPACE}(f(\kappa(x)) \log  x )$	$(Q, \nu) \in \text{LIN}$ i.e., $\text{DSPACE}(O(\nu(x)) + O(\log  x ))$

1. LIN: store NP-witnesses for  $x$ .
2. SUBLIN: avoid storing NP-witnesses for  $x$ .

## Reductions

	Parameterized Complexity	Classical Complexity
many-one	pl-reduction	slrf-reduction
many-to-many	pl Turing reduction	slrf Turing reduction

1. para-L and XL are closed under pl- and pl Turing reductions.
2. SUBLIN and LIN are closed under slrf- and slrf Turing reductions.

## The Miniaturization

Let  $Q \subseteq \Sigma^*$  be a problem and  $\nu$  its size measure.

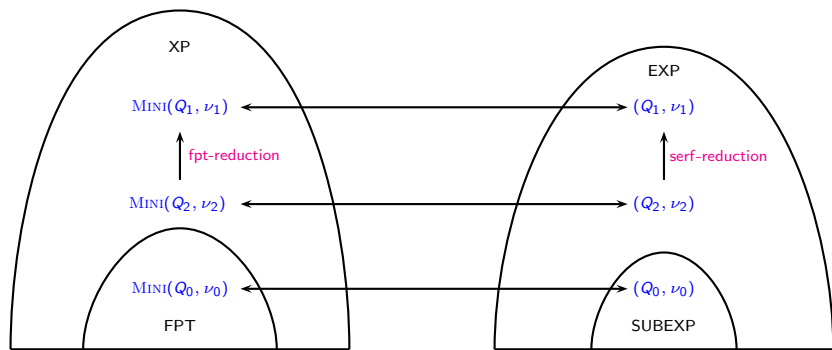
MINI( $Q, \nu$ )

*Input:*  $x \in \Sigma^*$  and  $m$  in unary with  $m \geq |x|$ .

*Parameter:*  $\left\lceil \frac{\nu(x)}{\log m} \right\rceil$ .

*Problem:* Decide whether  $x \in Q$ .

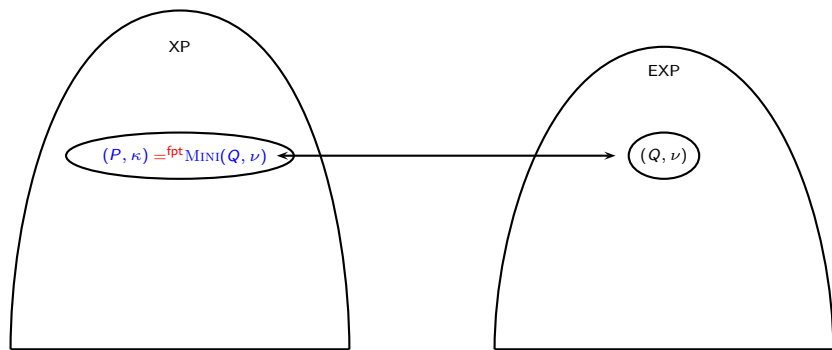
## The Isomorphism for Time Complexity (1)



### Theorem

1.  $(Q, \nu) \in \text{SUBEXP} \iff \text{MINI}(Q, \nu) \in \text{FPT}$ .
2.  $(Q, \nu) \in \text{EXP} \iff \text{MINI}(Q, \nu) \in \text{XP}$ .
3.  $(Q_1, \nu_1) \leq^{\text{serf}} (Q_2, \nu_2) \iff \text{MINI}(Q_1, \nu_1) \leq^{\text{fpt}} \text{MINI}(Q_2, \nu_2)$ .

## The Isomorphism for Time Complexity (2)



### Theorem

For any  $(P, \kappa) \in \text{XP}$  there exists a  $(Q, \nu) \in \text{EXP}$  such that

$$(P, \kappa) =^{\text{fpt}} \text{MINI}(Q, \nu).$$

## The Isomorphism for Time Complexity (3)

### Theorem

For any  $(P, \kappa) \in \text{XP}$  there exists a  $(Q, \nu) \in \text{EXP}$  such that

$$(P, \kappa) =^{\text{fpt}} \text{MINI}(Q, \nu).$$

$(Q, \nu) \in \text{EXP}$  constructed in the proof is artificial.

### Theorem

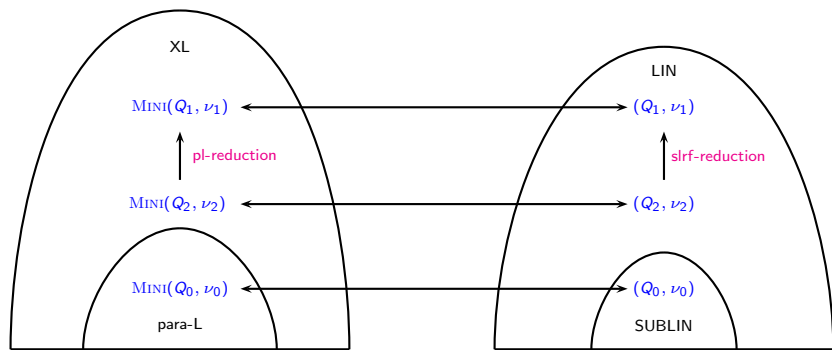
$$(k\text{-CLIQUE}, k) =^{\text{fpt}} \text{MINI}(k\text{-CLIQUE}, k \cdot \log n).$$

Hence,  $k\text{-CLIQUE} \in \text{DTIME}\left(f(k)n^{O(1)}\right)$  if and only if

$k\text{-CLIQUE} \in \text{DTIME}\left(2^{O(k \cdot \log n)}n^{O(1)}\right)$ .



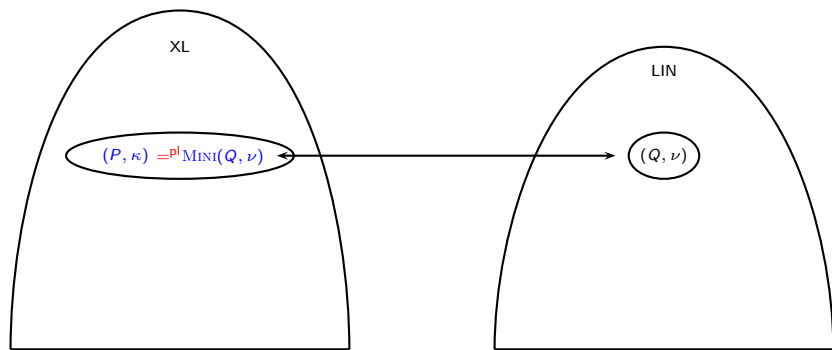
## The Isomorphism for Space Complexity (1)



### Theorem

1.  $(Q, \nu) \in \text{SUBLIN} \iff \text{MINI}(Q, \nu) \in \text{para-L}$ .
2.  $(Q, \nu) \in \text{LIN} \iff \text{MINI}(Q, \nu) \in \text{XL}$ .
3.  $(Q_1, \nu_1) \leq^{\text{slrf}} (Q_2, \nu_2) \iff \text{MINI}(Q_1, \nu_1) \leq^{\text{pl}} \text{MINI}(Q_2, \nu_2)$ .

## The Isomorphism for Space Complexity (2)



### Theorem

For any  $(P, \kappa) \in \text{XL}$  there exists a  $(Q, \nu) \in \text{LIN}$  such that

$$(P, \kappa) =^{\text{pl}} \text{MINI}(Q, \nu).$$

## The Isomorphism for Space Complexity (3)

### Theorem

For any  $(P, \kappa) \in \text{XL}$  there exists a  $(Q, \nu) \in \text{LIN}$  such that

$$(P, \kappa) \stackrel{\text{pl}}{=} \text{MINI}(Q, \nu).$$

### Theorem

$$(k\text{-STCONN}, k) \stackrel{\text{pl}}{=} \text{MINI}(k\text{-STCONN}, k \cdot \log n).$$

Hence,  $k\text{-STCONN} \in \text{DSPACE}(f(k) + O(\log n))$  if and only if  
 $k\text{-STCONN} \in \text{DSPACE}(o(k \cdot \log n) + O(\log n))$ .

## An application

Many tight bounds under ETH, what about  $\text{STCONN} \notin \text{DSPACE}(o(\log^2 n))$ ?

Theorem (C. , Elberfeld, Flum, and Müller, 2015)

For every  $d \geq 2$  there is an algorithm deciding

<b>Input:</b>	A database $\mathcal{A}$ and a <b>Boolean conjunctive query <math>\varphi</math> with <math>d</math> variables.</b>
<b>Parameter:</b>	$ \varphi $ .
<b>Problem:</b>	Decide whether $\mathcal{A} \models \varphi$ .

in space

$$O(\log |\varphi| \cdot \log |\mathcal{A}|).$$

Assume  $\text{STCONN} \notin \text{DSPACE}(o(\log^2 n))$ . Then there is no algorithm using space

$$f(|\varphi|) + o(\log |\varphi|) \cdot \log |\mathcal{A}|.$$

THANK YOU