# (S)ETH and A Survey of Consequences

Mohan Paturi

Simons Institute, August 2015

# Outline

- Exact Algorithms and Complexity
- 2 Exponential-Time Hypothesis
- S Explanatory Value of ETH and SETH
- Probabilistic Polynomial Time Algorithms
- Open Problems

### Exact Algorithms and Complexity

• All **NP**-complete problems are equivalent as far as polynomial time solvability is concerned.

- All **NP**-complete problems are equivalent as far as polynomial time solvability is concerned.
- However, some **NP**-complete problems have better exact algorithms than others

- All **NP**-complete problems are equivalent as far as polynomial time solvability is concerned.
- However, some **NP**-complete problems have better exact algorithms than others
- Exact algorithms deterministic or randomized algorithms that produce exact solutions

- All **NP**-complete problems are equivalent as far as polynomial time solvability is concerned.
- However, some **NP**-complete problems have better exact algorithms than others
- Exact algorithms deterministic or randomized algorithms that produce exact solutions
- Exact complexity worst-case complexity of exact algorithms

- All **NP**-complete problems are equivalent as far as polynomial time solvability is concerned.
- However, some **NP**-complete problems have better exact algorithms than others
- Exact algorithms deterministic or randomized algorithms that produce exact solutions
- Exact complexity worst-case complexity of exact algorithms
- What improvements can we expect over exhaustive search or standard algorithms?

- All **NP**-complete problems are equivalent as far as polynomial time solvability is concerned.
- However, some **NP**-complete problems have better exact algorithms than others
- Exact algorithms deterministic or randomized algorithms that produce exact solutions
- Exact complexity worst-case complexity of exact algorithms
- What improvements can we expect over exhaustive search or standard algorithms?
- What are the obstructions that limit the improvements?

- All **NP**-complete problems are equivalent as far as polynomial time solvability is concerned.
- However, some **NP**-complete problems have better exact algorithms than others
- Exact algorithms deterministic or randomized algorithms that produce exact solutions
- Exact complexity worst-case complexity of exact algorithms
- What improvements can we expect over exhaustive search or standard algorithms?
- What are the obstructions that limit the improvements?
- What principles explain the exact complexities of **NP**-complete problems?

• Two (or more) parameters with each instance: *m*, the size of the input and *n*, a complexity parameter

- Two (or more) parameters with each instance: *m*, the size of the input and *n*, a complexity parameter
- Natural and robust complexity parameters
  - k-SAT: formula  $F \rightarrow$  (formula size m, number of variables n)

- Two (or more) parameters with each instance: *m*, the size of the input and *n*, a complexity parameter
- Natural and robust complexity parameters
  - **(**) k-SAT: formula  $F \longrightarrow$  (formula size m, number of variables n)
  - ② Also, k-SAT: formula F → (formula size m, number of clauses)

- Two (or more) parameters with each instance: *m*, the size of the input and *n*, a complexity parameter
- Natural and robust complexity parameters
  - k-SAT: formula  $F \longrightarrow$  (formula size m, number of variables n)
  - ② Also, k-SAT: formula F → (formula size m, number of clauses)
  - HAMILTONIAN PATH: graph  $G = (V, E) \longrightarrow$  (size of the graph *m*, number of vertices *n*)

- Two (or more) parameters with each instance: *m*, the size of the input and *n*, a complexity parameter
- Natural and robust complexity parameters
  - **(**) k-SAT: formula  $F \longrightarrow$  (formula size m, number of variables n)
  - ② Also, k-SAT: formula F → (formula size m, number of clauses)
  - HAMILTONIAN PATH: graph  $G = (V, E) \longrightarrow$  (size of the graph *m*, number of vertices *n*)
  - Also, HAMILTONIAN PATH: graph G = (V, E) → (size of the graph  $m, \log n!$ )

• CIRCUIT SAT: circuit  $F \longrightarrow$  (circuit size *m*, number of variables *n*)

- CIRCUIT SAT: circuit  $F \longrightarrow$  (circuit size *m*, number of variables *n*)
- NP : Existentially quantified circuit ∃yC(x, y) → (circuit size m, number of existentially quantified Boolean variables |y|)

- CIRCUIT SAT: circuit  $F \longrightarrow$  (circuit size *m*, number of variables *n*)
- NP : Existentially quantified circuit ∃yC(x, y) → (circuit size m, number of existentially quantified Boolean variables |y|)
- CIRCUIT SAT is the "mother" of all **NP**-complete problems under this natural parametrization.

- CIRCUIT SAT: circuit  $F \longrightarrow$  (circuit size *m*, number of variables *n*)
- NP : Existentially quantified circuit ∃yC(x, y) → (circuit size m, number of existentially quantified Boolean variables |y|)
- CIRCUIT SAT is the "mother" of all **NP**-complete problems under this natural parametrization.
- Any **NP**-complete problem can be reduced to CIRCUIT SAT preserving the complexity parameter exactly.

• Given an **NP** problem instance with size parameter *m* and complexity parameter *n*,

- Given an **NP** problem instance with size parameter *m* and complexity parameter *n*,
- Standard (deterministic or random) algorithms are those achieve worst-case time complexity poly(m)2<sup>n</sup>

- Given an **NP** problem instance with size parameter *m* and complexity parameter *n*,
- Standard (deterministic or random) algorithms are those achieve worst-case time complexity poly(m)2<sup>n</sup>
- Improved exact algorithms are those that achieve worst-case time complexity  $poly(m)2^{\mu n}$  for  $\mu < 1$ .

- Given an **NP** problem instance with size parameter *m* and complexity parameter *n*,
- Standard (deterministic or random) algorithms are those achieve worst-case time complexity poly(m)2<sup>n</sup>
- Improved exact algorithms are those that achieve worst-case time complexity  $poly(m)2^{\mu n}$  for  $\mu < 1$ .
- Also known as moderately exponential-time or nontrivial exponential-time algorithms

# Improved Exponential Time Algorithms for k-SAT and k-COLORABILITY

# Improved Exponential Time Algorithms for k-SAT and k-COLORABILITY

# Improved Exponential Time Algorithms for k-SAT and k-COLORABILITY

# Improved Exponential Time Algorithms for k-SAT and k-COLORABILITY

• 
$$k$$
-SAT —  $2^{(1-\mu_k/(k-1))n}$  where  $\mu_k \approx 1.6$  for large  $k$ .

# Improved Exponential Time Algorithms for k-SAT and k-COLORABILITY

- k-SAT, number of variables as the complexity parameter backtracking and local search Hertli (2012), PPSZ, Schöning, PPZ, Rolf, Iwama, · · · , Monien and Speckenmeyer (1985)
  - 3-SAT 2<sup>0.386n</sup>
  - 4-SAT 2<sup>0.554n</sup>
  - k-SAT  $2^{(1-\mu_k/(k-1))n}$  where  $\mu_k \approx 1.6$  for large k.
- *k*-COLORABILITY, number of vertices as the complexity parameter backtracking Beigel and Eppstein (2005), Byskov (2004), ···

# Improved Exponential Time Algorithms for k-SAT and k-COLORABILITY

- k-SAT, number of variables as the complexity parameter backtracking and local search Hertli (2012), PPSZ, Schöning, PPZ, Rolf, Iwama, · · · , Monien and Speckenmeyer (1985)
  - 3-SAT 2<sup>0.386n</sup>
  - 4-SAT 2<sup>0.554n</sup>
  - k-SAT  $2^{(1-\mu_k/(k-1))n}$  where  $\mu_k \approx 1.6$  for large k.
- *k*-COLORABILITY, number of vertices as the complexity parameter backtracking Beigel and Eppstein (2005), Byskov (2004), ···
  - 3-Colorability 2<sup>0.41n</sup>

# Improved Exponential Time Algorithms for k-SAT and k-COLORABILITY

- k-SAT, number of variables as the complexity parameter backtracking and local search Hertli (2012), PPSZ, Schöning, PPZ, Rolf, Iwama, · · · , Monien and Speckenmeyer (1985)
  - 3-SAT 2<sup>0.386n</sup>
  - 4-SAT 2<sup>0.554n</sup>
  - k-SAT  $2^{(1-\mu_k/(k-1))n}$  where  $\mu_k \approx 1.6$  for large k.
- k-COLORABILITY, number of vertices as the complexity parameter — backtracking Beigel and Eppstein (2005), Byskov (2004), ···
  - 3-Colorability 2<sup>0.41n</sup>
  - 4-COLORABILITY 2<sup>0.807n</sup>

### Improved Algorithms for HAMILTONIAN PATH

• HAMILTONIAN PATH, number of vertices as the complexity parameter — dynamic programming, inclusion-exclusion, determinant summation formulas, algebraic sieving Björklund (2010), Bax (1993), Karp (1982), Kohn, Gottlieb, and Kohn (1977), Held and Karp (1962), Bellman (1962)

### Improved Algorithms for HAMILTONIAN PATH

- HAMILTONIAN PATH, number of vertices as the complexity parameter — dynamic programming, inclusion-exclusion, determinant summation formulas, algebraic sieving Björklund (2010), Bax (1993), Karp (1982), Kohn, Gottlieb, and Kohn (1977), Held and Karp (1962), Bellman (1962)
  - HAMILTONIAN PATH 2<sup>n</sup>



# Improved Algorithms for HAMILTONIAN PATH

- HAMILTONIAN PATH, number of vertices as the complexity parameter — dynamic programming, inclusion-exclusion, determinant summation formulas, algebraic sieving Björklund (2010), Bax (1993), Karp (1982), Kohn, Gottlieb, and Kohn (1977), Held and Karp (1962), Bellman (1962)
  - HAMILTONIAN PATH 2<sup>n</sup>



• undirected HAMILTONIAN PATH — 2<sup>0.67n</sup>

#### Improved Algorithms for COLORABILITY

 COLORABILITY, number of vertices as the complexity parameter — dynamic programming, Möbius inversion Björklund, Husfeldt, Kaski, Koivisto (2006-2008), ···, Byskov (2004), Eppstein (2003), Lawler (1976)

• COLORABILITY — 2<sup>n</sup> in exponential space

#### Improved Algorithms for MAX INDEPENDENT SET

• MAX INDEPENDENT SET, number of vertices as the complexity parameter — backtracking, measure and conquer Fomin, Grandoni, and Kratsch (2005), Robson (1986), Jian (1986), Tarjan and Trojanowski (1977)

### Improved Algorithms for MAX INDEPENDENT SET

MAX INDEPENDENT SET, number of vertices as the complexity parameter — backtracking, measure and conquer Fomin, Grandoni, and Kratsch (2005), Robson (1986), Jian (1986), Tarjan and Trojanowski (1977)
2<sup>0.287n</sup> in polynomial space

### Improved Algorithms for MAX INDEPENDENT SET

- MAX INDEPENDENT SET, number of vertices as the complexity parameter backtracking, measure and conquer Fomin, Grandoni, and Kratsch (2005), Robson (1986), Jian (1986), Tarjan and Trojanowski (1977)
  - 2<sup>0.287n</sup> in polynomial space
  - 2<sup>0.276n</sup> in exponential space
- MAX INDEPENDENT SET, number of vertices as the complexity parameter backtracking, measure and conquer Fomin, Grandoni, and Kratsch (2005), Robson (1986), Jian (1986), Tarjan and Trojanowski (1977)
  - 2<sup>0.287n</sup> in polynomial space
  - 2<sup>0.276n</sup> in exponential space
- CIRCUIT SAT split and list, random restrictions, dynamic programming, algebraization, matrix multiplication Impagliazzo, P, William (2012), Williams (2011), Santhanam (2011), Tamaki and Seto (2012), Impagliazzo, P, and Schneider (2013)

- MAX INDEPENDENT SET, number of vertices as the complexity parameter backtracking, measure and conquer Fomin, Grandoni, and Kratsch (2005), Robson (1986), Jian (1986), Tarjan and Trojanowski (1977)
  - 2<sup>0.287n</sup> in polynomial space
  - 2<sup>0.276n</sup> in exponential space
- CIRCUIT SAT split and list, random restrictions, dynamic programming, algebraization, matrix multiplication Impagliazzo, P, William (2012), Williams (2011), Santhanam (2011), Tamaki and Seto (2012), Impagliazzo, P, and Schneider (2013)
  - **AC**<sup>0</sup> Satisfiability for circuits of size *cn* and depth  $d 2^{n(1-1/\Theta(c^d))}$

- MAX INDEPENDENT SET, number of vertices as the complexity parameter backtracking, measure and conquer Fomin, Grandoni, and Kratsch (2005), Robson (1986), Jian (1986), Tarjan and Trojanowski (1977)
  - 2<sup>0.287n</sup> in polynomial space
  - 2<sup>0.276n</sup> in exponential space
- CIRCUIT SAT split and list, random restrictions, dynamic programming, algebraization, matrix multiplication Impagliazzo, P, William (2012), Williams (2011), Santhanam (2011), Tamaki and Seto (2012), Impagliazzo, P, and Schneider (2013)
  - **AC**<sup>0</sup> Satisfiability for circuits of size *cn* and depth  $d 2^{n(1-1/\Theta(c^d))}$
  - ACC Satisfiability 2<sup>n−n<sup>ε</sup></sup>

- MAX INDEPENDENT SET, number of vertices as the complexity parameter backtracking, measure and conquer Fomin, Grandoni, and Kratsch (2005), Robson (1986), Jian (1986), Tarjan and Trojanowski (1977)
  - 2<sup>0.287n</sup> in polynomial space
  - 2<sup>0.276n</sup> in exponential space
- CIRCUIT SAT split and list, random restrictions, dynamic programming, algebraization, matrix multiplication Impagliazzo, P, William (2012), Williams (2011), Santhanam (2011), Tamaki and Seto (2012), Impagliazzo, P, and Schneider (2013)
  - **AC**<sup>0</sup> Satisfiability for circuits of size *cn* and depth  $d 2^{n(1-1)\Theta(c^d)}$
  - ACC Satisfiability 2<sup>n−n<sup>ε</sup></sup>
  - Formula Satisfiability for formulas of size  $cn 2^{n(1-1/c^2)}$

- MAX INDEPENDENT SET, number of vertices as the complexity parameter backtracking, measure and conquer Fomin, Grandoni, and Kratsch (2005), Robson (1986), Jian (1986), Tarjan and Trojanowski (1977)
  - 2<sup>0.287n</sup> in polynomial space
  - 2<sup>0.276n</sup> in exponential space
- CIRCUIT SAT split and list, random restrictions, dynamic programming, algebraization, matrix multiplication Impagliazzo, P, William (2012), Williams (2011), Santhanam (2011), Tamaki and Seto (2012), Impagliazzo, P, and Schneider (2013)
  - **AC**<sup>0</sup> Satisfiability for circuits of size *cn* and depth  $d 2^{n(1-1/\Theta(c^d))}$
  - ACC Satisfiability 2<sup>n−n<sup>ε</sup></sup>
  - Formula Satisfiability for formulas of size  $cn 2^{n(1-1/c^2)}$
  - Formula Satisfiability for formulas of size *cn* over the full binary basis 2<sup>n(1-1/2<sup>-c<sup>2</sup></sup>)</sup>

- MAX INDEPENDENT SET, number of vertices as the complexity parameter backtracking, measure and conquer Fomin, Grandoni, and Kratsch (2005), Robson (1986), Jian (1986), Tarjan and Trojanowski (1977)
  - 2<sup>0.287n</sup> in polynomial space
  - 2<sup>0.276n</sup> in exponential space
- CIRCUIT SAT split and list, random restrictions, dynamic programming, algebraization, matrix multiplication Impagliazzo, P, William (2012), Williams (2011), Santhanam (2011), Tamaki and Seto (2012), Impagliazzo, P, and Schneider (2013)
  - **AC**<sup>0</sup> Satisfiability for circuits of size *cn* and depth  $d = 2^{n(1-1/\Theta(c^d))}$
  - ACC Satisfiability 2<sup>n−n<sup>ε</sup></sup>
  - Formula Satisfiability for formulas of size  $cn 2^{n(1-1/c^2)}$
  - Formula Satisfiability for formulas of size *cn* over the full binary basis 2<sup>n(1-1/2<sup>-c<sup>2</sup></sup>)</sup>
  - Depth-2 Threshold Circuit Satisfiability for circuits with cn Paturi (S)ETH and A Survey of Consequences

## Exact Complexity — Motivating Questions

• Which problems have improved algorithms? Is there a  $2^{\mu n}$  algorithm for COLORABILITY or CNFSAT or CIRCUIT SAT for  $\mu < 1$ ?

# Exact Complexity — Motivating Questions

- Which problems have improved algorithms? Is there a  $2^{\mu n}$  algorithm for COLORABILITY or CNFSAT or CIRCUIT SAT for  $\mu < 1$ ?
- Can the improvements extend to arbitrarily small exponents? Is 3-SAT solvable in subexponential-time? How about 3-COLORABILITY?

# Exact Complexity — Motivating Questions

- Which problems have improved algorithms? Is there a  $2^{\mu n}$  algorithm for COLORABILITY or CNFSAT or CIRCUIT SAT for  $\mu < 1$ ?
- Can the improvements extend to arbitrarily small exponents? Is 3-SAT solvable in subexponential-time? How about 3-COLORABILITY?
- Can we prove improvements beyond a certain point are not possible (at least under some complexity assumption)? Lower bounding the exponent for 3-SAT under suitable complexity assumptions?

# Exact Complexity — Motivating Questions

- Which problems have improved algorithms? Is there a  $2^{\mu n}$  algorithm for COLORABILITY or CNFSAT or CIRCUIT SAT for  $\mu < 1$ ?
- Can the improvements extend to arbitrarily small exponents? Is 3-SAT solvable in subexponential-time? How about 3-COLORABILITY?
- Can we prove improvements beyond a certain point are not possible (at least under some complexity assumption)? Lower bounding the exponent for 3-SAT under suitable complexity assumptions?
- Is progress on different problems connected?
  Do improved algorithms for 3-SAT imply improved algorithms for 3-COLORABILITY or vice versa?
  If COLORABILITY has a 2<sup>cn</sup> algorithm, can we prove CNFSAT has a 2<sup>dn</sup> algorithm for some c, d < 1?</li>

# A Zoo of Algorithms, Techniques, and Analyses

• A lot of effort has gone into improving the exponents.

# A Zoo of Algorithms, Techniques, and Analyses

- A lot of effort has gone into improving the exponents.
- A disparate variety of algorithmic techniques and analyses have been used.

backtracking, local search, split and list, random restrictions, dynamic programming, algebraization, matrix multiplication, Möbius inversion, measure and conquer, inclusion-exclusion, determinant summation formulas, algebraic sieving

# A Zoo of Algorithms, Techniques, and Analyses

- A lot of effort has gone into improving the exponents.
- A disparate variety of algorithmic techniques and analyses have been used.

backtracking, local search, split and list, random restrictions, dynamic programming, algebraization, matrix multiplication, Möbius inversion, measure and conquer, inclusion-exclusion, determinant summation formulas, algebraic sieving

• A priori, it is not clear that we can expect a common principle to govern the exact complexities.

• Is there a connection between the exponential complexities of problems?

- Is there a connection between the exponential complexities of problems?
- If 3-COLORABILITY has a subexponential time (2<sup>εn</sup> for arbitrarily small ε) algorithm, does it imply a subexponential time algorithms for 3-SAT?

- Is there a connection between the exponential complexities of problems?
- If 3-COLORABILITY has a subexponential time (2<sup>εn</sup> for arbitrarily small ε) algorithm, does it imply a subexponential time algorithms for 3-SAT?
- Problem: In the standard reduction from 3-SAT of n variables and m clauses to 3-COLORABILITY, we get a graph on O(n + m) vertices and O(n + m) edges.

- Is there a connection between the exponential complexities of problems?
- If 3-COLORABILITY has a subexponential time (2<sup>εn</sup> for arbitrarily small ε) algorithm, does it imply a subexponential time algorithms for 3-SAT?
- Problem: In the standard reduction from 3-SAT of n variables and m clauses to 3-COLORABILITY, we get a graph on O(n + m) vertices and O(n + m) edges.
- Complexity parameter increases polynomially, thus preventing any useful conclusion about 3-SAT.

### Lemma (Sparsification Lemma, IPZ 1997)

- S ≤ 2<sup>εn</sup>; Sol(φ) = ⋃<sub>i</sub> Sol(φ<sub>i</sub>), where Sol(φ) is the set of satisfying assignments of φ
- ②  $\forall i \in [s]$  each literal occurs  $\leq O(\frac{k}{\epsilon})^{3k}$  times in  $\phi_i$ .

### Lemma (Sparsification Lemma, IPZ 1997)

- S ≤ 2<sup>εn</sup>; Sol(φ) = ⋃<sub>i</sub> Sol(φ<sub>i</sub>), where Sol(φ) is the set of satisfying assignments of φ
- ②  $\forall i \in [s]$  each literal occurs ≤  $O(\frac{k}{\epsilon})^{3k}$  times in  $\phi_i$ .
  - To complete the reduction from 3-SAT to 3-COLORABILITY and preserve linearity in the parameter value,

### Lemma (Sparsification Lemma, IPZ 1997)

- S ≤ 2<sup>εn</sup>; Sol(φ) = ⋃<sub>i</sub> Sol(φ<sub>i</sub>), where Sol(φ) is the set of satisfying assignments of φ
- ②  $\forall i \in [s]$  each literal occurs ≤  $O(\frac{k}{\epsilon})^{3k}$  times in  $\phi_i$ .
  - To complete the reduction from 3-SAT to 3-COLORABILITY and preserve linearity in the parameter value,
  - Apply Sparsification Lemma to the given 3-CNF  $\phi$ .

### Lemma (Sparsification Lemma, IPZ 1997)

- S ≤ 2<sup>εn</sup>; Sol(φ) = ⋃<sub>i</sub> Sol(φ<sub>i</sub>), where Sol(φ) is the set of satisfying assignments of φ
- ②  $\forall i \in [s]$  each literal occurs ≤  $O(\frac{k}{\epsilon})^{3k}$  times in  $\phi_i$ .
  - To complete the reduction from 3-SAT to 3-COLORABILITY and preserve linearity in the parameter value,
  - Apply Sparsification Lemma to the given 3-CNF  $\phi$ .
  - Consider each 3-CNF  $\phi_i$  with linearly many clauses and reduce it to a graph with linearly many vertices.

### Lemma (Sparsification Lemma, IPZ 1997)

- S ≤ 2<sup>εn</sup>; Sol(φ) = ⋃<sub>i</sub> Sol(φ<sub>i</sub>), where Sol(φ) is the set of satisfying assignments of φ
- ②  $\forall i \in [s]$  each literal occurs ≤  $O(\frac{k}{\epsilon})^{3k}$  times in  $\phi_i$ .
  - To complete the reduction from 3-SAT to 3-COLORABILITY and preserve linearity in the parameter value,
  - Apply Sparsification Lemma to the given 3-CNF  $\phi$ .
  - Consider each 3-CNF  $\phi_i$  with linearly many clauses and reduce it to a graph with linearly many vertices.
  - Now, a subexponential time algorithm for 3-COLORABILITY implies a subexponential time algorithm for 3-SAT.

### Lemma (Sparsification Lemma, IPZ 1997)

- S ≤ 2<sup>εn</sup>; Sol(φ) = ⋃<sub>i</sub> Sol(φ<sub>i</sub>), where Sol(φ) is the set of satisfying assignments of φ
- ②  $\forall i \in [s]$  each literal occurs ≤  $O(\frac{k}{\epsilon})^{3k}$  times in  $\phi_i$ .
  - To complete the reduction from 3-SAT to 3-COLORABILITY and preserve linearity in the parameter value,
  - Apply Sparsification Lemma to the given 3- $\text{CNF} \phi$ .
  - Consider each 3-CNF  $\phi_i$  with linearly many clauses and reduce it to a graph with linearly many vertices.
  - Now, a subexponential time algorithm for 3-COLORABILITY implies a subexponential time algorithm for 3-SAT.
  - Key ideas: subexponential time reductions, sparsification

 SNP — class of properties expressible by a series of second order existential quantifiers, followed by a series of first order universal quantifiers, followed by a basic formula —Papadimitriou and Yannakakis 1991

- SNP class of properties expressible by a series of second order existential quantifiers, followed by a series of first order universal quantifiers, followed by a basic formula —Papadimitriou and Yannakakis 1991
- **SNP** includes k-SAT and k-COLORABILITY for  $k \ge 3$ .

- SNP class of properties expressible by a series of second order existential quantifiers, followed by a series of first order universal quantifiers, followed by a basic formula —Papadimitriou and Yannakakis 1991
- **SNP** includes *k*-sat and *k*-COLORABILITY for  $k \ge 3$ .  $\exists S \forall (y_1, \dots, y_k) \forall (s_1, \dots, s_k) [R_{(s_1, \dots, s_k)}(y_1, \dots, y_k) \implies \land_{1 \le i \le k} S_{s_i}(y_i)$ , where  $s_i \in \{+, -\}$  and *S* is a subset of [n].

- SNP class of properties expressible by a series of second order existential quantifiers, followed by a series of first order universal quantifiers, followed by a basic formula —Papadimitriou and Yannakakis 1991
- **SNP** includes *k*-SAT and *k*-COLORABILITY for  $k \ge 3$ .  $\exists S \forall (y_1, \dots, y_k) \forall (s_1, \dots, s_k) [R_{(s_1, \dots, s_k)}(y_1, \dots, y_k) \implies \land_{1 \le i \le k} S_{s_i}(y_i)$ , where  $s_i \in \{+, -\}$  and *S* is a subset of [n].
- VERTEX COVER, CLIQUE, INDEPENDENT SET and *k*-SET COVER are in size-constrained **SNP**.

- SNP class of properties expressible by a series of second order existential quantifiers, followed by a series of first order universal quantifiers, followed by a basic formula —Papadimitriou and Yannakakis 1991
- **SNP** includes *k*-SAT and *k*-COLORABILITY for  $k \ge 3$ .  $\exists S \forall (y_1, \dots, y_k) \forall (s_1, \dots, s_k) [R_{(s_1, \dots, s_k)}(y_1, \dots, y_k) \implies \land_{1 \le i \le k} S_{s_i}(y_i)$ , where  $s_i \in \{+, -\}$  and *S* is a subset of [n].
- VERTEX COVER, CLIQUE, INDEPENDENT SET and *k*-SET COVER are in size-constrained **SNP**.
- HAMILTONIAN PATH is **SNP**-hard.

#### Theorem (Impagliazzo, P, and Zane (1977))

3-SAT admits a subexponential-time algorithm if and only if every problem in (size-constrained) **SNP** admits one.

#### Theorem (Impagliazzo, P, and Zane (1977))

3-SAT admits a subexponential-time algorithm if and only if every problem in (size-constrained) **SNP** admits one.

• Proof Sketch: Show that every problem in **SNP** is strongly many-one reducible to *k*-SAT for some *k*. Complexity parameter is the number of existential quantifiers.

#### Theorem (Impagliazzo, P, and Zane (1977))

3-SAT admits a subexponential-time algorithm if and only if every problem in (size-constrained) **SNP** admits one.

- Proof Sketch: Show that every problem in **SNP** is strongly many-one reducible to *k*-SAT for some *k*. Complexity parameter is the number of existential quantifiers.
- Reduce *k*-SAT to the union of subexponentially many linear-size *k*-SAT using Sparsification Lemma.

#### Theorem (Impagliazzo, P, and Zane (1977))

3-SAT admits a subexponential-time algorithm if and only if every problem in (size-constrained) **SNP** admits one.

- Proof Sketch: Show that every problem in **SNP** is strongly many-one reducible to *k*-SAT for some *k*. Complexity parameter is the number of existential quantifiers.
- Reduce *k*-SAT to the union of subexponentially many linear-size *k*-SAT using Sparsification Lemma.
- Reduce each linear-size *k*-SAT to 3-SAT with linearly many variables.

# Exponential-time Hypothesis (**ETH**)

• The previous theorem gives evidence that 3-SAT does not have a subexponential-time algorithm as it is unlikely that the whole class **SNP** has such algorithms.

# Exponential-time Hypothesis (**ETH**)

- The previous theorem gives evidence that 3-SAT does not have a subexponential-time algorithm as it is unlikely that the whole class **SNP** has such algorithms.
- While it seems beyond our scope to prove this, our plan is to explore the state of affairs given the likelihood.

# Exponential-time Hypothesis (ETH)

- The previous theorem gives evidence that 3-SAT does not have a subexponential-time algorithm as it is unlikely that the whole class **SNP** has such algorithms.
- While it seems beyond our scope to prove this, our plan is to explore the state of affairs given the likelihood.
- Let  $s_k = \inf \{ \delta | \exists 2^{\delta n} \text{ algorithm for } k\text{-sat} \};$

# Exponential-time Hypothesis (ETH)

- The previous theorem gives evidence that 3-SAT does not have a subexponential-time algorithm as it is unlikely that the whole class **SNP** has such algorithms.
- While it seems beyond our scope to prove this, our plan is to explore the state of affairs given the likelihood.
- Let  $s_k = \inf \{ \delta | \exists 2^{\delta n} \text{ algorithm for } k\text{-sat} \};$
- **ETH** Exponential Time Hypothesis:  $s_3 > 0$
## Exponential-time Hypothesis (**ETH**)

- The previous theorem gives evidence that 3-SAT does not have a subexponential-time algorithm as it is unlikely that the whole class **SNP** has such algorithms.
- While it seems beyond our scope to prove this, our plan is to explore the state of affairs given the likelihood.
- Let  $s_k = \inf \{ \delta | \exists 2^{\delta n} \text{ algorithm for } k\text{-sat} \};$
- **ETH** Exponential Time Hypothesis:  $s_3 > 0$
- Assuming **ETH**, we conclude none of the problems in (size-constrained) **SNP** have a subexponential time algorithms

## Exponential-time Hypothesis (**ETH**)

- The previous theorem gives evidence that 3-SAT does not have a subexponential-time algorithm as it is unlikely that the whole class **SNP** has such algorithms.
- While it seems beyond our scope to prove this, our plan is to explore the state of affairs given the likelihood.
- Let  $s_k = \inf \{ \delta | \exists 2^{\delta n} \text{ algorithm for } k\text{-sat} \};$
- **ETH** Exponential Time Hypothesis:  $s_3 > 0$
- Assuming **ETH**, we conclude none of the problems in (size-constrained) **SNP** have a subexponential time algorithms
- Furthermore, **SNP**-hard problems such as HAMILTONIAN PATH cannot have a subexponential time algorithm.

• We have a very little understanding of exponential time algorithms.

- We have a very little understanding of exponential time algorithms.
- For ETH to be useful,

- We have a very little understanding of exponential time algorithms.
- For ETH to be useful,
  - it must be able to provide an explanation for the exact complexities of various other problems,

- We have a very little understanding of exponential time algorithms.
- For ETH to be useful,
  - it must be able to provide an explanation for the exact complexities of various other problems,
  - ideally, by providing lower bounds that match the upper bounds from the best known algorithms.

- We have a very little understanding of exponential time algorithms.
- For ETH to be useful,
  - it must be able to provide an explanation for the exact complexities of various other problems,
  - ideally, by providing lower bounds that match the upper bounds from the best known algorithms.
- **ETH** will be useful if it helps factor out the essential difficulty of dealing with exponential time algorithms for **NP**-complete problems.

### Lower Bounds based on ETH — I

• We follow the nice summary provided by Lokshtanov, Marx and Saurabh (2011).

- We follow the nice summary provided by Lokshtanov, Marx and Saurabh (2011).
- All the following results assume ETH.

- We follow the nice summary provided by Lokshtanov, Marx and Saurabh (2011).
- All the following results assume ETH.
- Subexponential time lower bounds: There is no  $2^{o(\sqrt{n})}$  algorithm for VERTEX COVER, 3-COLORABILITY, and HAMILTONIAN PATH for planar graphs.

### Lower Bounds based on **ETH** — I

- We follow the nice summary provided by Lokshtanov, Marx and Saurabh (2011).
- All the following results assume ETH.
- Subexponential time lower bounds: There is no  $2^{o(\sqrt{n})}$  algorithm for VERTEX COVER, 3-COLORABILITY, and HAMILTONIAN PATH for planar graphs.
- Lower bounds for FPT problems: There is no  $2^{o(k)}n^{O(1)}$  algorithm to decide whether the graph has a vertex cover of size at most k.

Similar results hold for the problems

FEEDBACK VERTEX SET and LONGEST PATH. Cai and Juedes (2003)

### Lower Bounds based on ETH — I

- We follow the nice summary provided by Lokshtanov, Marx and Saurabh (2011).
- All the following results assume **ETH**.
- Subexponential time lower bounds: There is no  $2^{o(\sqrt{n})}$  algorithm for VERTEX COVER, 3-COLORABILITY, and HAMILTONIAN PATH for planar graphs.
- Lower bounds for FPT problems: There is no  $2^{o(k)}n^{O(1)}$  algorithm to decide whether the graph has a vertex cover of size at most k.

Similar results hold for the problems

FEEDBACK VERTEX SET and LONGEST PATH. Cai and Juedes (2003)

• Lower bounds for *W*[1]-complete problems: There is no  $f(k)n^{o(k)}$  algorithm for CLIQUE or INDEPENDENT SET. Chen, Chor, Fellows, Huang, Juedes, Kanj, and Xia (2005, 2006)

### Lower Bounds based on ETH — II

• Lower bounds for W[2]-complete problems: There is no  $f(k)n^{o(k)}$  algorithm for DOMINATING SET. Fellows (2011), Lokshtanov (2009)

- Lower bounds for W[2]-complete problems: There is no  $f(k)n^{o(k)}$  algorithm for DOMINATING SET. Fellows (2011), Lokshtanov (2009)
- Lower bounds for problems parameterized by treewidth CHROMATIC NUMBER parameterized by treewidth t does not admit an algorithm that runs in time 2<sup>o(t |g t)</sup> n<sup>O(1)</sup>. Lokshtanov, Marx, and Saurabh (2011), Cygan, Nederlof, Pilipczuk, van Rooij, Wojtaszczyk (2011)

- Lower bounds for W[2]-complete problems: There is no  $f(k)n^{o(k)}$  algorithm for DOMINATING SET. Fellows (2011), Lokshtanov (2009)
- Lower bounds for problems parameterized by treewidth CHROMATIC NUMBER parameterized by treewidth t does not admit an algorithm that runs in time 2<sup>o(t |g t)</sup> n<sup>O(1)</sup>. Lokshtanov, Marx, and Saurabh (2011), Cygan, Nederlof, Pilipczuk, van Rooij, Wojtaszczyk (2011)
- LIST COLORING parameterized by treewidth does not admit algorithms that run in  $f(t)n^{o(t)}$ . Fellows, Fomin, Lokshtanov, Rosamond, Saurabh, Szeider, and Thomassen (2011)

- Lower bounds for W[2]-complete problems: There is no  $f(k)n^{o(k)}$  algorithm for DOMINATING SET. Fellows (2011), Lokshtanov (2009)
- Lower bounds for problems parameterized by treewidth CHROMATIC NUMBER parameterized by treewidth t does not admit an algorithm that runs in time 2<sup>o(t |g t)</sup> n<sup>O(1)</sup>. Lokshtanov, Marx, and Saurabh (2011), Cygan, Nederlof, Pilipczuk, van Rooij, Wojtaszczyk (2011)
- LIST COLORING parameterized by treewidth does not admit algorithms that run in  $f(t)n^{o(t)}$ . Fellows, Fomin, Lokshtanov, Rosamond, Saurabh, Szeider, and Thomassen (2011)
- Workflow Satisfiability Problem parameterized by the number of steps k cannot have a 2<sup>o(k lg k)</sup>n<sup>O(1)</sup> algorithm. Crampton, Cohen, Gutin, and Jones (2013)

- Lower bounds for W[2]-complete problems: There is no  $f(k)n^{o(k)}$  algorithm for DOMINATING SET. Fellows (2011), Lokshtanov (2009)
- Lower bounds for problems parameterized by treewidth CHROMATIC NUMBER parameterized by treewidth t does not admit an algorithm that runs in time 2<sup>o(t |g t)</sup> n<sup>O(1)</sup>. Lokshtanov, Marx, and Saurabh (2011), Cygan, Nederlof, Pilipczuk, van Rooij, Wojtaszczyk (2011)
- LIST COLORING parameterized by treewidth does not admit algorithms that run in  $f(t)n^{o(t)}$ . Fellows, Fomin, Lokshtanov, Rosamond, Saurabh, Szeider, and Thomassen (2011)
- Workflow Satisfiability Problem parameterized by the number of steps k cannot have a 2<sup>o(k lg k)</sup>n<sup>O(1)</sup> algorithm. Crampton, Cohen, Gutin, and Jones (2013)
- Many others · · ·

Theorem (Impagliazzo and P, 1999)

If **ETH** is true, s<sub>k</sub> increases infinitely often

### Theorem (Impagliazzo and P, 1999)

If **ETH** is true, s<sub>k</sub> increases infinitely often

• Let 
$$s_{\infty} = \lim_{k \to \infty} s_k$$
.

### Theorem (Impagliazzo and P, 1999)

If **ETH** is true, s<sub>k</sub> increases infinitely often

• Let 
$$s_{\infty} = \lim_{k \to \infty} s_k$$
.

More specifically, we prove s<sub>∞</sub> − s<sub>k</sub> ≥ d/k for some absolute constant d > 0.

### Theorem (Impagliazzo and P, 1999)

If **ETH** is true, s<sub>k</sub> increases infinitely often

• Let 
$$s_{\infty} = \lim_{k \to \infty} s_k$$
.

- More specifically, we prove s<sub>∞</sub> − s<sub>k</sub> ≥ d/k for some absolute constant d > 0.
- Provides evidence to the observation that heuristics for *k*-SAT perform worse as *k* increases.

### Theorem (Impagliazzo and P, 1999)

If **ETH** is true, s<sub>k</sub> increases infinitely often

• Let 
$$s_{\infty} = \lim_{k \to \infty} s_k$$
.

- More specifically, we prove s<sub>∞</sub> − s<sub>k</sub> ≥ d/k for some absolute constant d > 0.
- Provides evidence to the observation that heuristics for *k*-SAT perform worse as *k* increases.
- Proof Sketch: Trade clause width up to reduce the number of variables: reduce k-SAT to k'-CNF for k' ≫ k such that the resultant formula has fewer variables.

- **ETH** implies that (d, 2)-CSP requires  $d^{cn}$  time where c is an absolute constant. The constant c depends on  $s_3$ . Traxler 2008
- (*d*, 2)-CSP is the class of constraint satisfaction problems where variables take *d* values and each clause has two variables.

- **ETH** implies that (d, 2)-CSP requires  $d^{cn}$  time where c is an absolute constant. The constant c depends on  $s_3$ . Traxler 2008
- (*d*, 2)-CSP is the class of constraint satisfaction problems where variables take *d* values and each clause has two variables.
- Proof involves reducing a (d, 2)-CSP instance to a (d', 2)-CSP instance for d' ≫ d, but with fewer variables.

- **ETH** implies that (d, 2)-CSP requires  $d^{cn}$  time where c is an absolute constant. The constant c depends on  $s_3$ . Traxler 2008
- (*d*, 2)-CSP is the class of constraint satisfaction problems where variables take *d* values and each clause has two variables.
- Proof involves reducing a (d, 2)-CSP instance to a (d', 2)-CSP instance for d' ≫ d, but with fewer variables.
- A special case of (k, 2)-CSP, k-COLORABILITY, has a 2<sup>n</sup> algorithm (exponent is independent of k).

- **ETH** implies that (d, 2)-CSP requires  $d^{cn}$  time where c is an absolute constant. The constant c depends on  $s_3$ . Traxler 2008
- (*d*, 2)-CSP is the class of constraint satisfaction problems where variables take *d* values and each clause has two variables.
- Proof involves reducing a (d, 2)-CSP instance to a (d', 2)-CSP instance for d' ≫ d, but with fewer variables.
- A special case of (k, 2)-CSP, k-COLORABILITY, has a 2<sup>n</sup> algorithm (exponent is independent of k).
- Greater expressiveness of k'-CNF and (d', 2)-CSP has been exploited.

## **SETH** — Strong Exponential Time Hypothesis

• Earlier result regarding the increasing complexity of k-SAT tempts one to hypothesize SETH — Strong Exponential Time Hypothesis:  $s_{\infty} = 1$ 

## **SETH** and Its Equivalent Statements

#### Theorem

The following statements are equivalent:

 ∀ε < 1, ∃k, k-SAT, the satisfiability problems for n-variable k-CNF formuals, cannot be computed in time O(2<sup>εn</sup>) time.

## **SETH** and Its Equivalent Statements

#### Theorem

The following statements are equivalent:

- ∀ε < 1, ∃k, k-SAT, the satisfiability problems for n-variable k-CNF formuals, cannot be computed in time O(2<sup>εn</sup>) time.
- ∀ε < 1, ∃k, k-HITTING SET, the HITTING SET problem for set systems over [n] with sets of size at most k, cannot be computed in time O(2<sup>εn</sup>) time.

# SETH and Its Equivalent Statements

### Theorem

The following statements are equivalent:

- ∀ε < 1, ∃k, k-SAT, the satisfiability problems for n-variable k-CNF formuals, cannot be computed in time O(2<sup>εn</sup>) time.
- ∀ε < 1, ∃k, k-HITTING SET, the HITTING SET problem for set systems over [n] with sets of size at most k, cannot be computed in time O(2<sup>εn</sup>) time.
- ∀ε < 1, ∃k, k-SET SPLITTING, the SET SPLITTING problem for set systems over [n] with sets of size at most k, cannot be computed in time O(2<sup>εn</sup>) time.

— Cygan, Dell, Lokshtanov, Marx, Nederlof, Okamoto, P, Saurabh, Wahlstrom, 2012

### Lower Bounds based on SETH - I

• If **SETH** holds, *k*-DOMINATING SET does not have a  $f(k)n^{k-\varepsilon}$  time algorithm. — Patrascu and Williams, 2009

- If **SETH** holds, *k*-DOMINATING SET does not have a  $f(k)n^{k-\varepsilon}$  time algorithm. Patrascu and Williams, 2009
- SETH implies that INDEPENDENT SET parameterized by treewidth cannot be solved faster than 2<sup>tw</sup> n<sup>O(1)</sup> — Lokshtanov, Marx, and Saurabh 2010

- If **SETH** holds, *k*-DOMINATING SET does not have a  $f(k)n^{k-\varepsilon}$  time algorithm. Patrascu and Williams, 2009
- SETH implies that INDEPENDENT SET parameterized by treewidth cannot be solved faster than 2<sup>tw</sup> n<sup>O(1)</sup> — Lokshtanov, Marx, and Saurabh 2010
- **SETH** implies that DOMINATING SET parameterized by treewidth cannot be solved faster than  $3^{tw} n^{O(1)}$  Lokshtanov, Marx, and Saurabh 2010
- Many others · · ·

### Lower Bounds based on SETH - II

#### Theorem

**SETH** determines the exact complexities of the following problems in **P**.

- ∀ε > o, the ORTHOGONAL VECTORS problem for n binary vectors of dimension ω(log n) cannot be solved in time O(n<sup>2-ε</sup>). Williams 2004
- ∀ε > o, the VECTOR DOMINATION problem for n vectors of dimension ωlog n cannot be solved in time O(n<sup>2-ε</sup>). Williams 2004, Impagliazzo, Paturi, Schneider 2013

### Lower Bounds based on SETH - II

#### Theorem

**SETH** determines the exact complexities of the following problems in **P**.

- ∀ε > o, the ORTHOGONAL VECTORS problem for n binary vectors of dimension ω(log n) cannot be solved in time O(n<sup>2-ε</sup>). Williams 2004
- ∀ε > o, the VECTOR DOMINATION problem for n vectors of dimension ωlog n cannot be solved in time O(n<sup>2-ε</sup>). Williams 2004, Impagliazzo, Paturi, Schneider 2013
- ∀ε > o, the FRÉCHET DISTANCE problem for two piece-wise linear curves with n pieces n cannot be solved in time O(n<sup>2-ε</sup>). — Bringmann - 2014

### Lower Bounds based on SETH - II

#### Theorem

**SETH** determines the exact complexities of the following problems in **P**.

- ∀ε > o, the ORTHOGONAL VECTORS problem for n binary vectors of dimension ω(log n) cannot be solved in time O(n<sup>2-ε</sup>). Williams 2004
- ∀ε > o, the VECTOR DOMINATION problem for n vectors of dimension ωlog n cannot be solved in time O(n<sup>2-ε</sup>). — Williams - 2004, Impagliazzo, Paturi, Schneider - 2013
- ∀ε > o, the FRÉCHET DISTANCE problem for two piece-wise linear curves with n pieces n cannot be solved in time O(n<sup>2-ε</sup>). — Bringmann - 2014
- Many others · · · Borassi, Crescenzi, Habib 2014, Abboud, Vassilevska Williams, 2014
## Probabilistic Polynomial Time Algorithms

• Consider natural, though restricted, models of computation for exponential time algorithms.

- Consider natural, though restricted, models of computation for exponential time algorithms.
- **OP**(*T*(*n*, *m*)): one-sided error probabilistic algorithms that run in time *T*(*n*, *m*)

- Consider natural, though restricted, models of computation for exponential time algorithms.
- **OP**(*T*(*n*, *m*)): one-sided error probabilistic algorithms that run in time *T*(*n*, *m*)
- **OPP**: **OP**(T(n, m)) where T(n, m) is polynomially bounded.

- Consider natural, though restricted, models of computation for exponential time algorithms.
- **OP**(*T*(*n*, *m*)): one-sided error probabilistic algorithms that run in time *T*(*n*, *m*)
- **OPP**: **OP**(T(n, m)) where T(n, m) is polynomially bounded.
- Includes several Davis-Putnam style backtracking algorithms, local search algorithms

- Consider natural, though restricted, models of computation for exponential time algorithms.
- **OP**(*T*(*n*, *m*)): one-sided error probabilistic algorithms that run in time *T*(*n*, *m*)
- **OPP**: **OP**(T(n, m)) where T(n, m) is polynomially bounded.
- Includes several Davis-Putnam style backtracking algorithms, local search algorithms

- Consider natural, though restricted, models of computation for exponential time algorithms.
- **OP**(*T*(*n*, *m*)): one-sided error probabilistic algorithms that run in time *T*(*n*, *m*)
- **OPP**: **OP**(T(n, m)) where T(n, m) is polynomially bounded.
- Includes several Davis-Putnam style backtracking algorithms, local search algorithms
- OPP: space efficiency, parallelization, speed-up by quantum computation

- Consider natural, though restricted, models of computation for exponential time algorithms.
- **OP**(*T*(*n*, *m*)): one-sided error probabilistic algorithms that run in time *T*(*n*, *m*)
- **OPP**: **OP**(T(n, m)) where T(n, m) is polynomially bounded.
- Includes several Davis-Putnam style backtracking algorithms, local search algorithms
- OPP: space efficiency, parallelization, speed-up by quantum computation
- What is the best success probability achievable in OPP or OP(T(n, m))?

## Probabilistic Polynomial Time Algorithms

• CIRCUIT SAT problem can be solved with probability  $2^{-n+O(\lg T(n,m))}$  using OP(T(n,m)) algorithms.

- CIRCUIT SAT problem can be solved with probability  $2^{-n+O(\lg T(n,m))}$  using OP(T(n,m)) algorithms.
- Best-known deterministic algorithm takes time 2<sup>n</sup>poly(m).

- CIRCUIT SAT problem can be solved with probability  $2^{-n+O(\lg T(n,m))}$  using OP(T(n,m)) algorithms.
- Best-known deterministic algorithm takes time 2<sup>n</sup>poly(m).
- Hamiltonian path problem can be solved with probability 1/n! in OPP.

- CIRCUIT SAT problem can be solved with probability  $2^{-n+O(\lg T(n,m))}$  using OP(T(n,m)) algorithms.
- Best-known deterministic algorithm takes time 2<sup>n</sup>poly(m).
- Hamiltonian path problem can be solved with probability 1/n! in OPP.
- The best known deterministic exponential time algorithm takes time 2<sup>O(n)</sup>poly(m).

### Time and Success Probability Trade-off

• Let  $X(n) = (\lg t + \lg 1/p)/n$  where p is the best success probability for time t.

## Time and Success Probability Trade-off

• Let  $X(n) = (\lg t + \lg 1/p)/n$  where p is the best success probability for time t.

• Let 
$$X = \lim_{n \to \infty} X(n)$$
.

- Let  $X(n) = (\lg t + \lg 1/p)/n$  where p is the best success probability for time t.
- Let  $X = \lim_{n \to \infty} X(n)$ .
- How does X behave as a function of t?

- Let  $X(n) = (\lg t + \lg 1/p)/n$  where p is the best success probability for time t.
- Let  $X = \lim_{n \to \infty} X(n)$ .
- How does X behave as a function of t?
- For the CIRCUIT SAT problem, based on the best known algorithms, X = 1 whether t is polynomial in n or exponential in n.

- Let X(n) = (lg t + lg 1/p)/n where p is the best success probability for time t.
- Let  $X = \lim_{n \to \infty} X(n)$ .
- How does X behave as a function of t?
- For the CIRCUIT SAT problem, based on the best known algorithms, X = 1 whether t is polynomial in n or exponential in n.
- On the other hand, for HAMILTONIAN PATH, based on the best known algorithms,  $X = \infty$  when t is polynomial in n and  $X \leq 1$  when t is exponential is n.

- Let X(n) = (lg t + lg 1/p)/n where p is the best success probability for time t.
- Let  $X = \lim_{n \to \infty} X(n)$ .
- How does X behave as a function of t?
- For the CIRCUIT SAT problem, based on the best known algorithms, X = 1 whether t is polynomial in n or exponential in n.
- On the other hand, for HAMILTONIAN PATH, based on the best known algorithms,  $X = \infty$  when t is polynomial in n and  $X \leq 1$  when t is exponential is n.
- For what problems, does this quantity decrease/stay the same over a certain range of time?

- Let X(n) = (lg t + lg 1/p)/n where p is the best success probability for time t.
- Let  $X = \lim_{n \to \infty} X(n)$ .
- How does X behave as a function of t?
- For the CIRCUIT SAT problem, based on the best known algorithms, X = 1 whether t is polynomial in n or exponential in n.
- On the other hand, for HAMILTONIAN PATH, based on the best known algorithms,  $X = \infty$  when t is polynomial in n and  $X \leq 1$  when t is exponential is n.
- For what problems, does this quantity decrease/stay the same over a certain range of time?
- We present (weak) evidence that for CIRCUIT SAT,  $(\log t + \log 1/p)/n$  may not significantly decrease with increasing time.

## Circuit Family for deciding CIRCUIT SAT



Circuit D with n variables

# Success Probability for $\operatorname{CIRCUIT}$ SAT with OPP algorithms

#### Theorem (P, Pudlák 2010)

If CIRCUIT SAT can be decided with probabilistic circuits of size  $m^k$  for some k with success probability  $2^{-\delta n}$  for  $\delta < 1$ , then there exists a  $\mu < 1$  depending on k and  $\delta$  such that CIRCUIT SAT(n, m) can be decided by deterministic circuits of size  $2^{O(n^{\mu} \lg^{1-\mu} m)}$ .

## Results: Quasilinear Size Circuits

#### Theorem

If CIRCUIT SAT can be decided with probabilistic circuits of size  $\tilde{O}(m)$  with success probability  $2^{-\delta n}$  for  $\delta < 1$ , then CIRCUIT SAT(n, m) can be decided by deterministic circuits of size  $O(\text{poly}(m)n^{O(\lg \lg m)})$ .

## Results: Quasilinear Size Circuits

#### Theorem

If CIRCUIT SAT can be decided with probabilistic circuits of size  $\tilde{O}(m)$  with success probability  $2^{-\delta n}$  for  $\delta < 1$ , then CIRCUIT SAT(n, m) can be decided by deterministic circuits of size  $O(\text{poly}(m)n^{O(\lg \lg m)})$ .

• The consequence is very close to the statement  $\mathbf{NP}\subseteq\mathbf{P}/\texttt{poly}.$ 

## Success Probability for $\operatorname{CIRCUIT}\,\operatorname{SAT}$ with Subexponential Size Circuits

#### Theorem (P, Pudlák 2010)

If CIRCUIT SAT can be decided with probabilistic circuits of size  $2^{o(n)}\tilde{O}(m)$  with success probability  $2^{-\delta n}$  for  $\delta < 1$ , then CIRCUIT SAT(n, m) can be decided by deterministic circuits of size  $2^{o(n)}$  poly(m).

## Exponential Amplification Lemma

#### Lemma (P and Pudlák 2010)

**Exponential Amplification Lemma:** Let  $\mathcal{F}$  be an f-bounded family for some  $f : \mathbb{N} \times \mathbb{N} \to \mathbb{R}$  that decides CIRCUIT SAT with success probability  $2^{-\delta n}$  for  $0 < \delta < 1$ . Then there exists a g-bounded circuit family  $\mathcal{G}$  that decides CIRCUIT SAT with success probability at least  $2^{-\delta^2 n}$  where  $g(n,m) = O(f(\lceil \delta n \rceil + 5, \tilde{O}(f(n,m)))).$ 

## Exponential Amplification Lemma

#### Lemma (P and Pudlák 2010)

**Exponential Amplification Lemma:** Let  $\mathcal{F}$  be an f-bounded family for some  $f : \mathbb{N} \times \mathbb{N} \to \mathbb{R}$  that decides CIRCUIT SAT with success probability  $2^{-\delta n}$  for  $0 < \delta < 1$ . Then there exists a g-bounded circuit family  $\mathcal{G}$  that decides CIRCUIT SAT with success probability at least  $2^{-\delta^2 n}$  where  $g(n,m) = O(f(\lceil \delta n \rceil + 5, \tilde{O}(f(n,m)))).$ 

•  $\mathcal{F}: (f(n,m), \delta n) \rightarrow \mathcal{G}: (g(n,m), \delta^2 n)$ 

## Drucker's Recent Result

#### Theorem (Drucker, 2013)

For any  $\mu < 1$ , if there is an OPP algorithm which takes the description of a 3-SAT formula of length m as input and decides its satisfiability with success probability at least  $2^{-m^{\mu}}$ , then **NP**  $\subseteq$  **coNP**/poly

## Other Connections

- Hardest instances
- Satisfiability and circuit lower bounds
- • •

#### • Assuming ETH or other suitable assumption, prove

#### • Assuming ETH or other suitable assumption, prove

#### • Assuming ETH or other suitable assumption, prove

• a specific lower bound on  $s_3$ 

- Assuming ETH or other suitable assumption, prove
  - a specific lower bound on  $s_3$
  - $s_{\infty} = 1$  (SETH)
- Assuming **SETH**, can we prove a 2<sup>n</sup> lower bound on COLORABILITY?

- Assuming ETH or other suitable assumption, prove
  - a specific lower bound on  $s_3$
  - $s_{\infty} = 1$  (SETH)
- Assuming **SETH**, can we prove a 2<sup>n</sup> lower bound on COLORABILITY?
- Are there better non-**OPP** algorithms for *k*-SAT or CIRCUIT SAT?

- Assuming ETH or other suitable assumption, prove
  - a specific lower bound on  $s_3$
  - $s_{\infty} = 1$  (SETH)
- Assuming **SETH**, can we prove a 2<sup>n</sup> lower bound on COLORABILITY?
- Are there better non-**OPP** algorithms for *k*-SAT or CIRCUIT SAT?
- Does there exist a  $c^{-n}$  success probability **OPP** algorithm for HAMILTONIAN PATH?

## **Thank You**