

Adversarial Bandits: Theory and Algorithms

Haipeng Luo

University of Southern California

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Stochastic MAB is a special case where ℓ_1, \dots, ℓ_T are iid generated

A Closer Look

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 - ▶ foundation for all other regret measures
 - ▶ for games, implies convergence to equilibrium/optimal social welfare

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- highlight how to control the variance of estimators
- highlight the differences between full-info and bandit

Warm-Up: The Expert Problem

The full-info counterpart of adversarial MAB:

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Not trivial at all even with full information!

At round t , sample $i_t \sim p_t \in \Delta_K$ s.t. (for some learning rate $\eta > 0$)

$$p_{t,i} \propto \exp\left(-\eta \sum_{\tau < t} \ell_{\tau,i}\right)$$

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called by many names: Hedge, Multiplicative Weights Update (MWU), ...

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Define potential $\Phi_t = \frac{1}{\eta} \ln \left(\sum_{i=1}^K \exp(-\eta \sum_{\tau \leq t} \ell_{\tau,i}) \right)$.

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$$e^{-z} \leq 1 - z + z^2, \quad \forall z \geq 0 \text{ and } \ell_{t,i} \geq 0$$

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$$\ln(1+z) \leq z$$

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Telescoping and rearranging gives:

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Since $\ell_{t,i}^2 \leq 1$, picking the best η gives $\text{Reg} = \mathcal{O}(\sqrt{T \ln K})$ (optimal)

A More Modern View

Hedge is a special case of **Follow-the-Regularized-Leader** (FTRL):

$$p_t = \operatorname{argmin}_{p \in \Delta_K} \left\langle p, \sum_{\tau < t} \ell_\tau \right\rangle + \frac{1}{\eta} \psi(p)$$

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- $\|\ell_t\|_{p_t}^2 = \ell_t^\top \nabla^{-2} \psi(p_t) \ell_t$ (important **local norm**)

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• $\|\ell_t\|_{p_t}^2 = \ell_t^\top \nabla^{-2} \psi(p_t) \ell_t$ (important **local norm**)

• for Shannon entropy: $\|\ell_t\|_{p_t}^2 = \sum_i p_{t,i} \ell_{t,i}^2$

stability term

penalty term

From Full-Info to Bandit

The Exp3 Algorithm

Auer-CesaBianchi-Freund-Schapire'02

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Regret Analysis for Exp3

Key challenge: the **variance** of the estimator can be huge

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Note the gap between this and Exp3's regret bound $\mathcal{O}(\sqrt{TK \ln K})$

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Audibert-Bubeck'09, Abernethy-Lee-Tewari'15

Consider FTRL with the **1/2-Tsallis entropy** $\psi(p) = -\sum_{i=1}^K \sqrt{p_i}$,

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Teaser for Thodoris' talk: not only minimax optimal for adversarial losses, but (surprisingly) also *instance-optimal for stochastic losses!* (Zimmert-Seldin'19)

Beyond Minimax Optimality: Adaptive and Problem-Dependent Regret Bounds

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Worst-case robustness (\sqrt{TK} -regret) might be **overly pessimistic**. Can we adapt to **easier instances** with smaller regret?

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variance of losses $Q = \frac{1}{K} \sum_{t,i} (\ell_{t,i} - \frac{1}{T} L_i)$	$\tilde{O}(\sqrt{QK})$	Hazan-Kale'11, Bubeck-Cohen-Li'17

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variance of losses $Q = \frac{1}{K} \sum_{t,i} (\ell_{t,i} - \frac{1}{T} L_i)$ $Q^* = \sum_t (\ell_{t,i^*} - \frac{1}{T} L^*)$	$\tilde{O}(\sqrt{QK})$ $\tilde{O}(\sqrt{Q^*K})$	Hazan-Kale'11, Bubeck-Cohen-Li'17 Wei-Luo'18

Robustness versus Adaptivity

Worst-case robustness (\sqrt{TK} -regret) might be **overly pessimistic**. Can we adapt to **easier instances** with smaller regret?

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imply **faster convergence** in games

Consider FTRL with the **log-barrier** regularizer $\psi(p) = -\sum_{i=1}^K \ln p_i$,

$$p_t = \operatorname{argmin}_{p \in \Delta_K} \left\langle p, \sum_{\tau < t} \hat{\ell}_\tau \right\rangle + \frac{1}{\eta} \psi(p)$$

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penalty	$\ln K$	\sqrt{K}	$K \ln T$
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Achieving Path-Length Bounds

Wei-Luo'18

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Surprisingly powerful for MAB and beyond:

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(Wei-Luo'18, Ito'21)

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