

The Overlap Gap Property in Inference: A Short Survey.

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Simons workshop

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Introduction

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Can **geometrical phase transitions** explain these gaps?

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OGP [Gamarnik, Sudan ’14]

Set $\mathcal{T}_\epsilon = \{\langle \beta, \beta' \rangle : H(\beta), H(\beta') \leq (1 + \epsilon) \min_{\beta \in \Sigma} H(\beta)\} \subseteq \mathbb{R}$.

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- (Gamarnik, Jagannath, Wein '20) MIS, (Bresler, Huang '21) k-SAT.
- OGP implies failure of stable (low-degree) algorithms.

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Overlap Gap Property (OGP) for inference. [Gamarnik, Z '17]

- (1) *Definition and overview*
- (2) Two case-studies:
 - ▶ *sparse regression*
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- Sparse Linear Regression [Gamarnik, Z '17a, '17b]
- Planted Clique [Gamarnik, Z '19].
- Sparse PCA [Gamarnik, Jagannath, Sen '19], [Ben Arous, Wein, Z '20]
- Tensor PCA [Ben Arous, Gheissari, Jagannath '18]
- Group Testing [Iliopoulos, Z '21]

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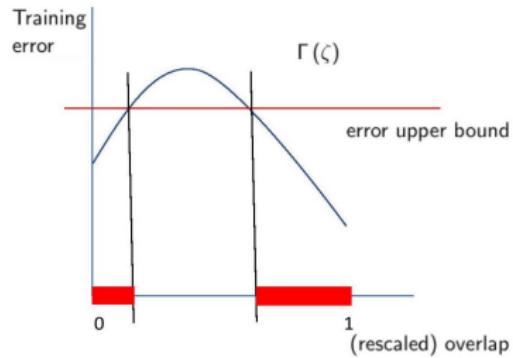
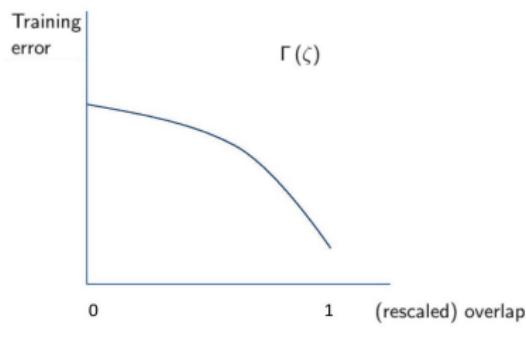
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Lemma: OGP if and only if Γ is non-monotonic.



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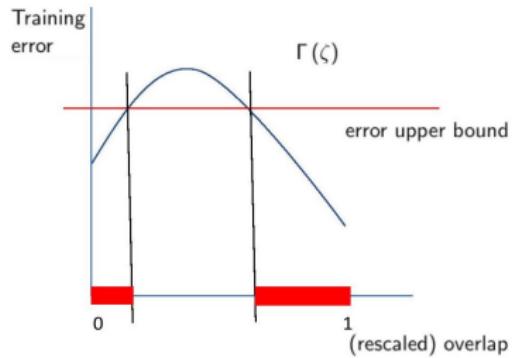
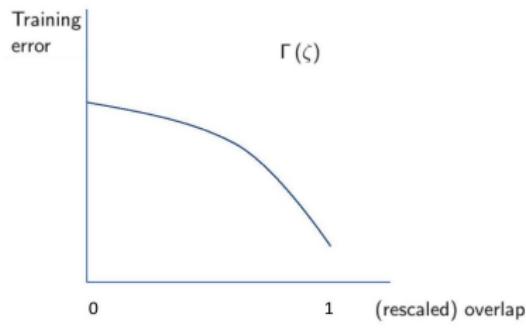
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- **1st MM:** lower bound on Γ . **2nd MM:** upper bound on Γ .

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The Sparse Regression Model

Setup

Let $\beta^* \in \{0, 1\}^p$ be a **binary k-sparse** vector (regime $k = o(p)$).
For

- $X \in \mathbb{R}^{n \times p}$ consisting of i.i.d $\mathcal{N}(0, 1)$ entries
- $W \in \mathbb{R}^n$ consisting of i.i.d. $\mathcal{N}(0, \sigma^2)$ entries

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Goal: Statistical and Computational Limit

Minimum $n = n_p$: given (Y, X) recover β^* w.h.p. as $p \rightarrow +\infty$.

Computational-Statistical Gap

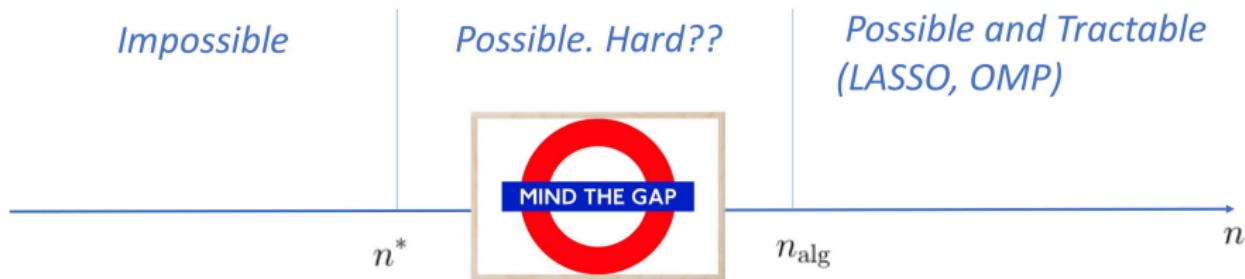
Under $k/\sigma^2 = \omega(1)$:



$$n^* = \frac{2k \log \frac{p}{k}}{\log(k/\sigma^2 + 1)}, n_{\text{alg}} = 2k \log \frac{p}{k}.$$

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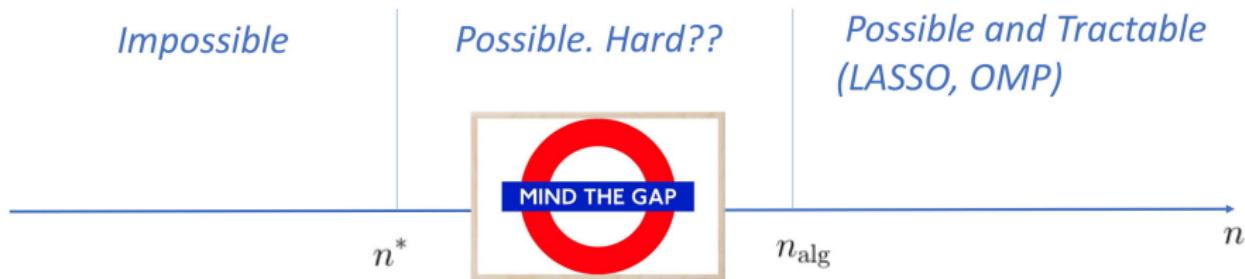
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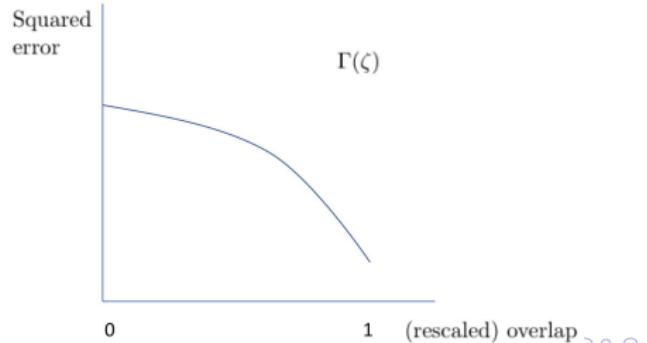
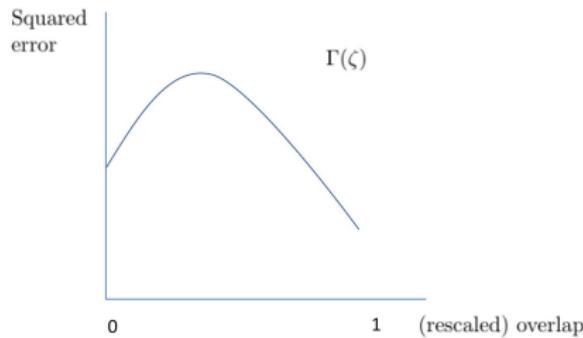
OGP via likelihood loss function

$$\min_{\beta \in \{0,1\}^p, \|\beta\|_0 = k} n^{-\frac{1}{2}} \|Y - X\beta\|_2$$

The OGP for Regression — Phase Transition

For $\zeta \in [0, 1]$,

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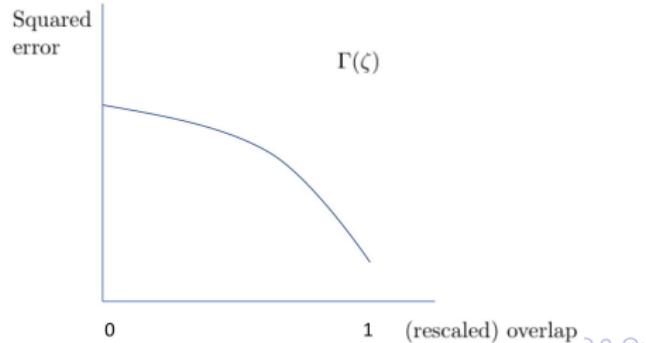
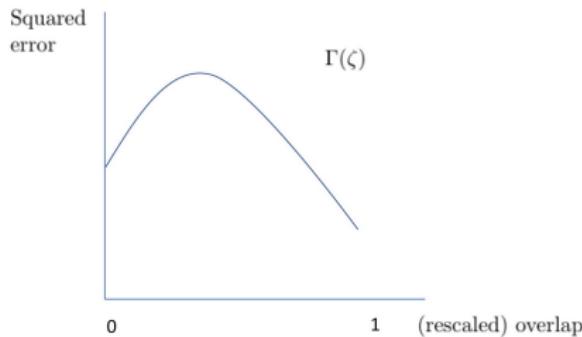
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Theorem (Gamarnik, Z '17)

Suppose $k \leq \exp(\sqrt{\log p})$. There exists $C > 1 > c > 0$ such that,

- If $n^* < n < cn_{\text{alg}}$ then w.h.p. Γ is not monotonic (OGP).
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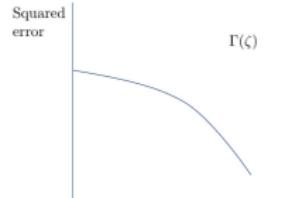
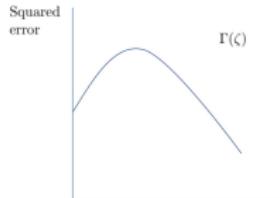
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OGP coincides with the failure of
convex relaxation and **compressed sensing** methods!



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The Planted Clique Model [Jerrum '92], [Kučera '95]

Generating Assumptions for $G(n, 1/2, k)$:

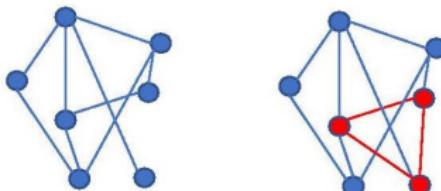
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$n = 7, k = 3, \mathcal{G}_0$ (left) and \mathcal{G} (right) :



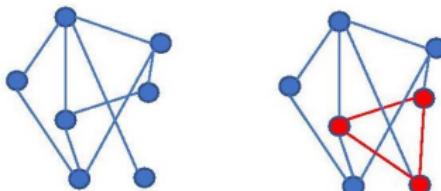
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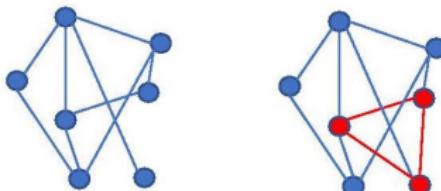
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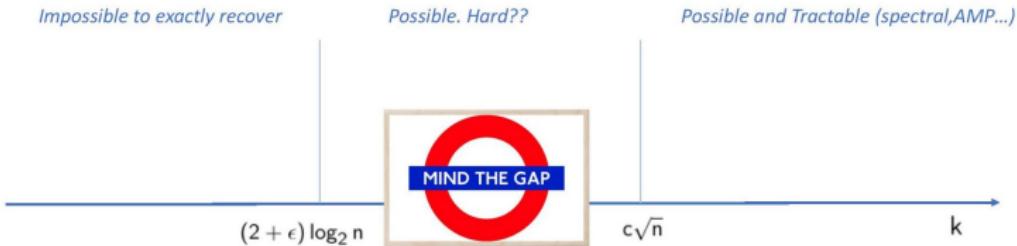
Goal: Recover \mathcal{PC} from observing $\mathcal{G} \sim G(n, 1/2, k)$.

Question: For how small $k = k_n$ can we recover?

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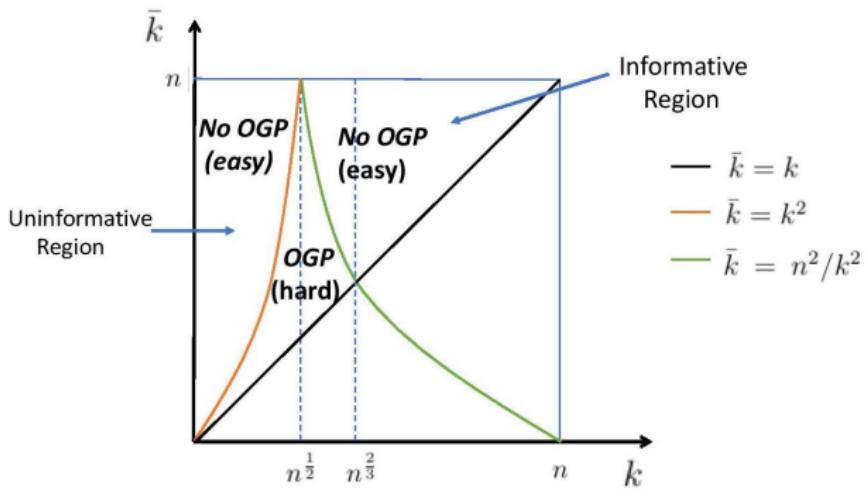
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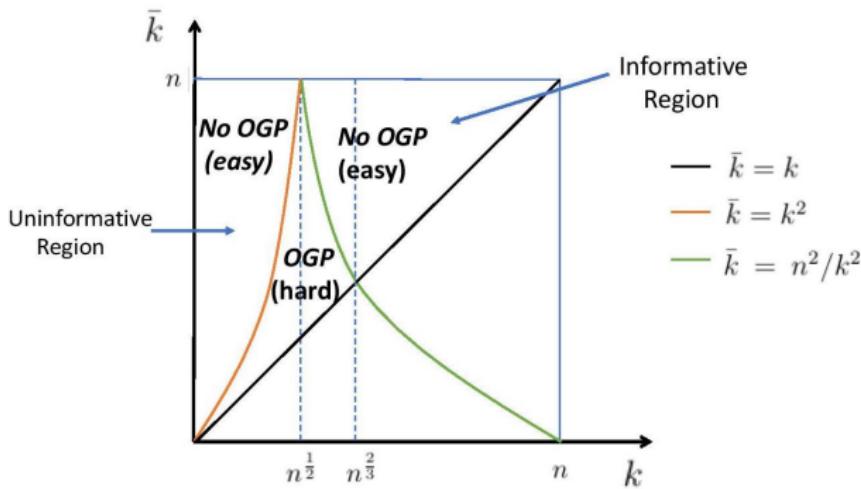
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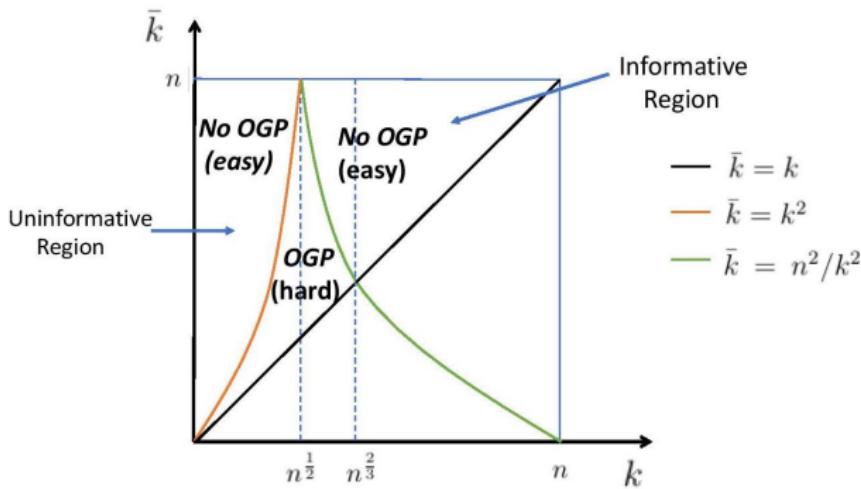
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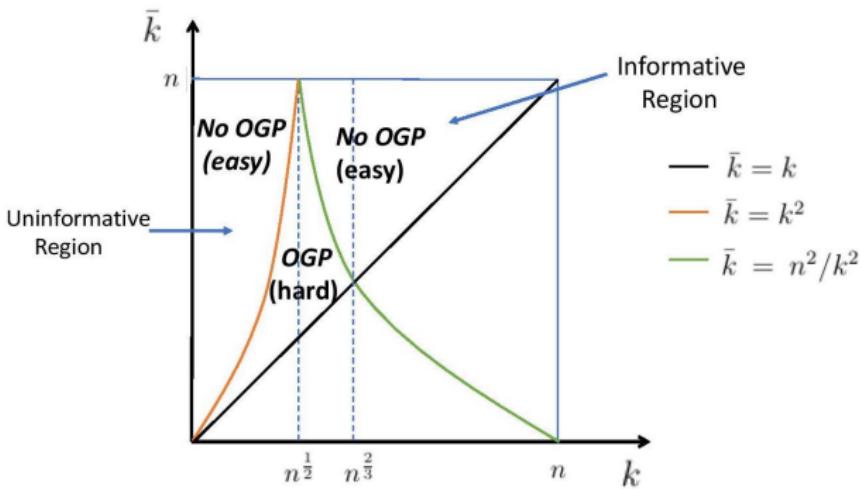
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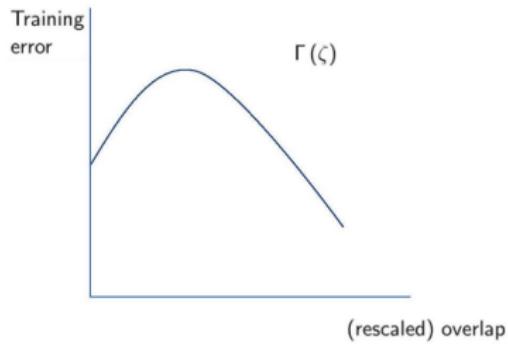
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Thank you!!

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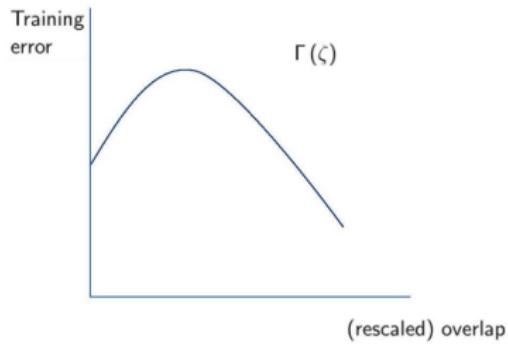
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Sparse PCA: OGP height is low-degree sub-exponential time prediction.

