

Your Dreams May Come True with MTP_2 ...

Caroline Uhler (MIT)

Joint work with Steffen Lauritzen, Elina Robeva,
Bernd Sturmfels, Ngoc Tran, Piotr Zwiernik

Simons Workshop:
Hyperbolic Polynomials and Hyperbolic Programming

May 2, 2019

Positive dependence and MTP_2 distributions

- A distribution (i.e. density function) p on $\mathcal{X} = \prod_{v \in V} \mathcal{X}_v$, with $\mathcal{X}_v \subseteq \mathbb{R}$ discrete or open subset, is **multivariate totally positive of order 2** (MTP_2) if

$$p(x)p(y) \leq p(x \wedge y)p(x \vee y) \quad \text{for all } x, y \in \mathcal{X},$$

where \wedge and \vee are applied coordinate-wise.

Positive dependence and MTP_2 distributions

- A distribution (i.e. density function) p on $\mathcal{X} = \prod_{v \in V} \mathcal{X}_v$, with $\mathcal{X}_v \subseteq \mathbb{R}$ discrete or open subset, is **multivariate totally positive of order 2** (MTP_2) if

$$p(x)p(y) \leq p(x \wedge y)p(x \vee y) \quad \text{for all } x, y \in \mathcal{X},$$

where \wedge and \vee are applied coordinate-wise.

- A random vector X is **positively associated** if for any non-decreasing functions $\phi, \psi : \mathbb{R}^m \rightarrow \mathbb{R}$

$$\text{cov}\{\phi(X), \psi(X)\} \geq 0.$$

Theorem (Fortuin-Kasteleyn-Ginibre inequality, 1971, Karlin & Rinott, 1980)

MTP_2 implies positive association.

No Yule-Simpson Paradox under MTP_2 !

The **Yule-Simpson paradox** says that we may have two random variables X and Y positively associated, but X and Y negatively associated conditionally on a third variable Z .

Sentences in 4863 murder cases in Florida over the six years 1973-1978:

Murderer	Sentence	
	Death	Other
Black	59	2547
White	72	2185

Victim	Murderer	Sentence	
		Death	Other
Black	Black	11	2309
	White	0	111
White	Black	48	238
	White	72	2074

Overall greater proportion of white murderers receiving death sentence than black (3.2% vs. 2.3%); this trend is reversed given color of victim.

Data from: Range (1979)

Gaussian-like properties of MTP_2 distribution

Reminder: A distribution p on $\mathcal{X} \subseteq \mathbb{R}^m$ is MTP_2 if

$$p(x)p(y) \leq p(x \wedge y)p(x \vee y), \quad \text{for all } x, y \in \mathcal{X}.$$

Theorem (Lebowitz, 1972; Karlin and Rinott, 1980)

If X is MTP_2 , then

- (i) any *marginal* distribution is MTP_2
- (ii) any *conditional* distribution is MTP_2
- (iii) $X_A \perp\!\!\!\perp X_B \iff \text{cov}(X_u, X_v) = 0$ for all $u \in A, v \in B$

Gaussian MTP_2 distributions

Theorem (Bølviken 1982, Karlin & Rinott, 1983)

A multivariate Gaussian distribution $p(x; K)$ is MTP_2 if and only if the inverse covariance matrix K is an *M-matrix*, that is

$$K_{uv} \leq 0 \quad \text{for all } u \neq v.$$

Gaussian MTP_2 distributions

Theorem (Bølviken 1982, Karlin & Rinott, 1983)

A multivariate Gaussian distribution $p(x; K)$ is MTP_2 if and only if the inverse covariance matrix K is an *M-matrix*, that is

$$K_{uv} \leq 0 \quad \text{for all } u \neq v.$$

Ex: 2016 Monthly correlations of global stock markets (*InvestmentFrontier.com*)

$$S = \begin{pmatrix} \text{Nasdaq} & \text{Canada} & \text{Europe} & \text{UK} & \text{Australia} \\ 1.000 & 0.606 & 0.731 & 0.618 & 0.613 \\ 0.606 & 1.000 & 0.550 & 0.661 & 0.598 \\ 0.731 & 0.550 & 1.000 & 0.644 & 0.569 \\ 0.618 & 0.661 & 0.644 & 1.000 & 0.615 \\ 0.613 & 0.598 & 0.569 & 0.615 & 1.000 \end{pmatrix} \begin{matrix} \text{Nasdaq} \\ \text{Canada} \\ \text{Europe} \\ \text{UK} \\ \text{Australia} \end{matrix}$$

Gaussian MTP₂ distributions

Theorem (Bølviken 1982, Karlin & Rinott, 1983)

A multivariate Gaussian distribution $p(x; K)$ is MTP₂ if and only if the inverse covariance matrix K is an *M-matrix*, that is

$$K_{uv} \leq 0 \quad \text{for all } u \neq v.$$

Ex: 2016 monthly correlations of global stock markets (*InvestmentFrontier.com*)

$$S^{-1} = \begin{pmatrix} \text{Nasdaq} & \text{Canada} & \text{Europe} & \text{UK} & \text{Australia} \\ 2.629 & -0.480 & -1.249 & -0.202 & -0.490 \\ -0.480 & 2.109 & -0.039 & -0.790 & -0.459 \\ -1.249 & -0.039 & 2.491 & -0.675 & -0.213 \\ -0.202 & -0.790 & -0.675 & 2.378 & -0.482 \\ -0.490 & -0.459 & -0.213 & -0.482 & 1.992 \end{pmatrix} \begin{matrix} \text{Nasdaq} \\ \text{Canada} \\ \text{Europe} \\ \text{UK} \\ \text{Australia} \end{matrix}$$

Sample distribution is MTP₂! If you sample a correlation matrix uniformly at random the probability of it being MTP₂ is $< 10^{-6}$!

Discrete MTP_2 distributions

Reminder: A distribution p on $\mathcal{X} \subseteq \mathbb{R}^m$ is MTP_2 if

$$p(x)p(y) \leq p(x \wedge y)p(x \vee y), \quad \text{for all } x, y \in \mathcal{X}.$$

- Distribution of 3 binary variables X , Y and Z is MTP_2 iff

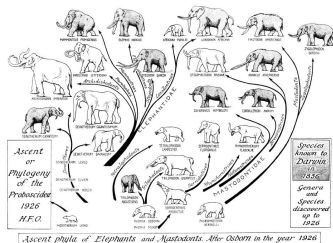
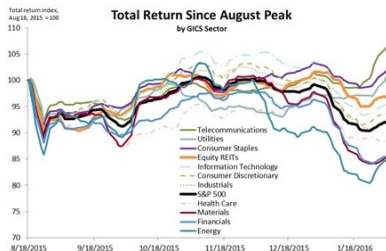
$$\begin{array}{lll} p_{001}p_{110} \leq p_{000}p_{111} & p_{010}p_{101} \leq p_{000}p_{111} & p_{100}p_{011} \leq p_{000}p_{111} \\ p_{011}p_{101} \leq p_{001}p_{111} & p_{011}p_{110} \leq p_{010}p_{111} & p_{101}p_{110} \leq p_{100}p_{111} \\ p_{001}p_{010} \leq p_{000}p_{011} & p_{001}p_{100} \leq p_{000}p_{101} & p_{010}p_{100} \leq p_{000}p_{110} \end{array}$$

- Dataset on **EPH-gestosis** analyzed by *Wermuth & Marchetti (2014)*
 - edema (high body water retention)
 - proteinuria (high amounts of urinary proteins)
 - hypertension (elevated blood pressure)

$$\begin{bmatrix} n_{000} & n_{010} & n_{001} & n_{011} \\ n_{100} & n_{110} & n_{101} & n_{111} \end{bmatrix} = \begin{bmatrix} 3299 & 107 & 1012 & 58 \\ 78 & 11 & 65 & 19 \end{bmatrix}.$$

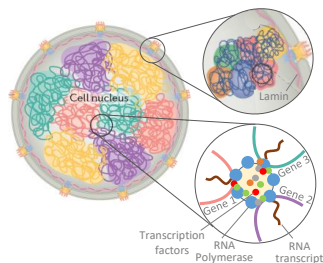
- This sample distribution is MTP_2 ! Although when you sample 3-dim binary distributions only about 2% are MTP_2 .

MTP₂ constraints are often implicit



|X| is MTP₂ in:

- Gaussian / binary tree models
- Gaussian / binary latent tree models
 - Binary latent class models
 - Single factor analysis models



Hyperbolic MTP₂ exponential families

- An **exponential family** is a parametric model with density

$$p_{\theta}(x) = \exp(\langle \theta, T(x) \rangle - A(\theta)),$$

sample space \mathcal{X} with measure ν , sufficient statistics $T : \mathcal{X} \rightarrow \mathbb{R}^d$,
and **space of canonical parameters**: $C = \{\theta \in \mathbb{R}^d : A(\theta) < +\infty\}$

- **Gaussian distribution**: $A(\theta) = -\alpha \log \det(\theta)$, $C = \mathbb{S}_{>0}^p$
- **Hyperbolic exponential family**: $A(\theta) = -\alpha \log(f(\theta))$, f hyperbolic with hyperbolicity cone C

Hyperbolic MTP_2 exponential families

- An **exponential family** is a parametric model with density

$$p_{\theta}(x) = \exp(\langle \theta, T(x) \rangle - A(\theta)),$$

sample space \mathcal{X} with measure ν , sufficient statistics $T : \mathcal{X} \rightarrow \mathbb{R}^d$,
and **space of canonical parameters**: $C = \{\theta \in \mathbb{R}^d : A(\theta) < +\infty\}$

- **Gaussian distribution**: $A(\theta) = -\alpha \log \det(\theta)$, $C = \mathbb{S}_{>0}^p$
- **Hyperbolic exponential family**: $A(\theta) = -\alpha \log(f(\theta))$, f hyperbolic with hyperbolicity cone C

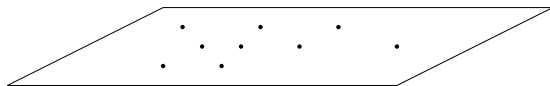
Theorem (Lauritzen, Uhler & Zwiernik, 2019)

The space of canonical parameters for any MTP_2 exponential family is given by $C \cap K$, where $K \subset \mathbb{R}$ is a closed convex cone whose dual is generated by

$$\{T(x \wedge y) + T(x \vee y) - T(x) - T(y) : x, y \in \mathcal{X} \text{ differing in 2 entries}\}.$$

Density estimation

Given i.i.d. samples $X = \{x_1, \dots, x_n\} \subset \mathbb{R}^m$ from an unknown distribution on \mathbb{R}^m with density p , can we estimate p ?



- **parametric:** assume p lies in some parametric family
 - **finite-dimensional optimization problem** (estimate parameters)
 - restrictive: real-world distribution might not lie in specified family
- **non-parametric:** assume that p lies in a non-parametric family:
 - **infinite-dimensional optimization problem**

ML Estimation for Gaussian MTP₂ distributions

Let $X_1, \dots, X_n \sim \mathcal{N}(0, \Sigma)$, $S := \frac{1}{n} \sum_{i=1}^n X_i X_i^T$ sample covariance matrix.

Primal: Max-Likelihood:

$$\begin{aligned} & \underset{K \succeq 0}{\text{maximize}} && \log \det(K) - \text{trace}(KS) \\ & \text{subject to} && K_{uv} \leq 0, \quad \forall u \neq v. \end{aligned}$$

Dual: Min-Entropy:

$$\begin{aligned} & \underset{\Sigma \succeq 0}{\text{minimize}} && -\log \det(\Sigma) - m \\ & \text{subject to} && \Sigma_{vv} = S_{vv}, \quad \Sigma_{uv} \geq S_{uv}. \end{aligned}$$

- Maximum likelihood estimation under MTP₂ is a **convex optimization problem** with **strong duality**

ML Estimation for Gaussian MTP₂ distributions

Let $X_1, \dots, X_n \sim \mathcal{N}(0, \Sigma)$, $S := \frac{1}{n} \sum_{i=1}^n X_i X_i^T$ sample covariance matrix.

Primal: Max-Likelihood:

$$\begin{aligned} & \underset{K \succeq 0}{\text{maximize}} && \log \det(K) - \text{trace}(KS) \\ & \text{subject to} && K_{uv} \leq 0, \quad \forall u \neq v. \end{aligned}$$

Dual: Min-Entropy:

$$\begin{aligned} & \underset{\Sigma \succeq 0}{\text{minimize}} && -\log \det(\Sigma) - m \\ & \text{subject to} && \Sigma_{vv} = S_{vv}, \quad \Sigma_{uv} \geq S_{uv}. \end{aligned}$$

- Maximum likelihood estimation under MTP₂ is a **convex optimization problem** with **strong duality**
- the global optimum is characterized by **KKT conditions**
- **Complementary slackness** implies that the MLE $\hat{K}^{-1} = \hat{\Sigma}$ satisfies $(\hat{\Sigma}_{uv} - S_{uv}) \hat{K}_{uv} = 0 \quad \forall u \neq v$

ML Estimation for Gaussian MTP₂ distributions

Let $X_1, \dots, X_n \sim \mathcal{N}(0, \Sigma)$, $S := \frac{1}{n} \sum_{i=1}^n X_i X_i^T$ sample covariance matrix.

Primal: Max-Likelihood:

$$\begin{aligned} & \underset{K \succeq 0}{\text{maximize}} && \log \det(K) - \text{trace}(KS) \\ & \text{subject to} && K_{uv} \leq 0, \quad \forall u \neq v. \end{aligned}$$

Dual: Min-Entropy:

$$\begin{aligned} & \underset{\Sigma \succeq 0}{\text{minimize}} && -\log \det(\Sigma) - m \\ & \text{subject to} && \Sigma_{vv} = S_{vv}, \quad \Sigma_{uv} \geq S_{uv}. \end{aligned}$$

- Maximum likelihood estimation under MTP₂ is a **convex optimization problem** with **strong duality**
- the global optimum is characterized by **KKT conditions**
- **Complementary slackness** implies that the MLE $\hat{K}^{-1} = \hat{\Sigma}$ satisfies $(\hat{\Sigma}_{uv} - S_{uv}) \hat{K}_{uv} = 0 \quad \forall u \neq v$
- **Linear algebra:** If M is an M-matrix, then $(M^{-1})_{ij} \geq 0$ for all i, j

ML Estimation for Gaussian MTP₂ distributions

Let $X_1, \dots, X_n \sim \mathcal{N}(0, \Sigma)$, $S := \frac{1}{n} \sum_{i=1}^n X_i X_i^T$ sample covariance matrix.

Primal: Max-Likelihood:

$$\begin{aligned} & \underset{K \succeq 0}{\text{maximize}} && \log \det(K) - \text{trace}(KS) \\ & \text{subject to} && K_{uv} \leq 0, \quad \forall u \neq v. \end{aligned}$$

Dual: Min-Entropy:

$$\begin{aligned} & \underset{\Sigma \succeq 0}{\text{minimize}} && -\log \det(\Sigma) - m \\ & \text{subject to} && \Sigma_{vv} = S_{vv}, \quad \Sigma_{uv} \geq S_{uv}. \end{aligned}$$

- Maximum likelihood estimation under MTP₂ is a **convex optimization problem** with **strong duality**
- the global optimum is characterized by **KKT conditions**
- **Complementary slackness** implies that the MLE $\hat{K}^{-1} = \hat{\Sigma}$ satisfies $(\hat{\Sigma}_{uv} - S_{uv}) \hat{K}_{uv} = 0 \quad \forall u \neq v$
- **Linear algebra:** If M is an M-matrix, then $(M^{-1})_{ij} \geq 0$ for all i, j
- **Graphical model:** \hat{G} (support of \hat{K}) is in general **sparse!!!**

Ultrametric matrices and inverse M-matrices

- U is **ultrametric**: $U_{ii} \geq U_{ij} = U_{ji} \geq \min(U_{ik}, U_{jk}) \geq 0$ for all i, j, k .

Theorem (Dellacherie, Martinez and San Martin, 2014)

Let U be an ultrametric matrix with strictly positive entries on the diagonal. Then U is non-singular if and only if no two rows are equal. Moreover, if U is non-singular, then U^{-1} is an M-matrix.

Theorem (Slawski and Hein, 2015)

The MLE in a Gaussian MTP_2 model exists with probability 1 when $n \geq 2$.

Ultrametric matrices and inverse M-matrices

- U is **ultrametric**: $U_{ii} \geq U_{ij} = U_{ji} \geq \min(U_{ik}, U_{jk}) \geq 0$ for all i, j, k .

Theorem (Dellacherie, Martinez and San Martin, 2014)

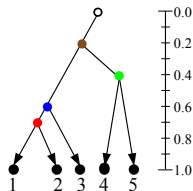
Let U be an ultrametric matrix with strictly positive entries on the diagonal. Then U is non-singular if and only if no two rows are equal. Moreover, if U is non-singular, then U^{-1} is an M-matrix.

Theorem (Slawski and Hein, 2015)

The MLE in a Gaussian MTP_2 model exists with probability 1 when $n \geq 2$.

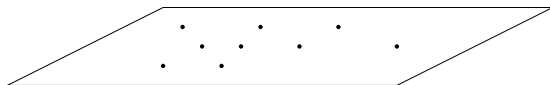
New proof: Construct primal & dual feasible point by **single-linkage clustering**

$$S = \left(\begin{array}{ccc|cc} 1 & 0.7 & 0.6 & 0.2 & 0.1 \\ 0.7 & 1 & 0.5 & 0.1 & -0.5 \\ 0.6 & 0.5 & 1 & -0.3 & 0.1 \\ \hline 0.2 & 0.1 & -0.3 & 1 & 0.4 \\ 0.1 & -0.5 & 0.1 & 0.4 & 1 \end{array} \right) \rightarrow \left(\begin{array}{ccc|cc} 1 & 0.7 & 0.6 & 0.2 & 0.2 \\ 0.7 & 1 & 0.6 & 0.2 & 0.2 \\ 0.6 & 0.6 & 1 & 0.2 & 0.2 \\ \hline 0.2 & 0.2 & 0.2 & 1 & 0.4 \\ 0.2 & 0.2 & 0.2 & 0.4 & 1 \end{array} \right)$$



Density estimation

Given i.i.d. samples $X = \{x_1, \dots, x_n\} \subset \mathbb{R}^m$ from an unknown distribution on \mathbb{R}^m with density p , can we estimate p ?



- **parametric:** assume p lies in some parametric family
 - **finite-dimensional optimization problem** (estimate parameters)
 - restrictive: real-world distribution might not lie in specified family
- **non-parametric:** assume that p lies in a non-parametric family:
 - **infinite-dimensional optimization problem**
 - need constraints that are:
 - strong enough so that there is no **spiky** behavior
 - weak enough so that function class is large

Shape-constrained density estimation

- monotonically decreasing densities: [Grenander 1956, Rao 1969]
- convex densities: [Anevski 1994, Groeneboom, Jongbloed, and Wellner 2001]
- **log-concave** densities: [Cule, Samworth, and Stewart 2010]
- generalized additive models with shape constraints: [Chen and Samworth 2016]

Shape-constrained density estimation

- monotonically decreasing densities: [Grenander 1956, Rao 1969]
- convex densities: [Anevski 1994, Groeneboom, Jongbloed, and Wellner 2001]
- **log-concave** densities: [Cule, Samworth, and Stewart 2010]
- generalized additive models with shape constraints: [Chen and Samworth 2016]
- **Maximum likelihood estimation under MTP_2** : Given i.i.d. samples $X = \{x_1, \dots, x_n\} \subset \mathbb{R}^m$,

$$\begin{aligned} & \text{maximize}_p \quad \sum_{i=1}^n \log(p(x_i)) \\ & \text{s.t.} \quad p \text{ is an } MTP_2 \text{ density.} \end{aligned}$$

Shape-constrained density estimation

- monotonically decreasing densities: [Grenander 1956, Rao 1969]
- convex densities: [Anevski 1994, Groeneboom, Jongbloed, and Wellner 2001]
- **log-concave** densities: [Cule, Samworth, and Stewart 2010]
- generalized additive models with shape constraints: [Chen and Samworth 2016]
- **Maximum likelihood estimation under MTP_2** : Given i.i.d. samples $X = \{x_1, \dots, x_n\} \subset \mathbb{R}^m$,

$$\begin{aligned} & \text{maximize}_p \quad \sum_{i=1}^n \log(p(x_i)) \\ & \text{s.t.} \quad p \text{ is an } MTP_2 \text{ density.} \\ & \quad \quad p \text{ log-concave.} \end{aligned}$$

Log-concave density estimation

- Log-concavity is natural assumption: ensures density is continuous and includes many distributions: Gaussian, Uniform(a, b), Gamma(k, θ) for $k \geq 1$, Beta(a, b) for $a, b \geq 1$, etc.

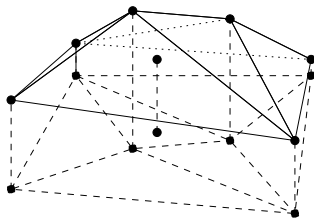
Log-concave density estimation

- Log-concavity is natural assumption: ensures density is continuous and includes many distributions: Gaussian, $\text{Uniform}(a, b)$, $\text{Gamma}(k, \theta)$ for $k \geq 1$, $\text{Beta}(a, b)$ for $a, b \geq 1$, etc.

Theorem (Cule, Samworth and Stewart, 2008)

When $n \geq m + 1$, a log-concave MLE \hat{p} exists and is unique with probability 1. Moreover, $\log(\hat{p})$ is a *tent-function* supported on the convex hull of the data.

Finite-dimensional optimization problem!



Questions:

- When does the MLE under log-concavity and MTP_2 / LLC exist? Is it unique?
- What is the shape of the MLE under log-concavity and MTP_2 / LLC?
 - Is the MLE always exp(tent function)?
- Can we compute the MLE?

Log- L^{\natural} -concave (LLC) functions

- A function $f : \mathbb{R}^m \rightarrow \mathbb{R}$ is **MTP₂** if

$$f(x)f(y) \leq f(x \wedge y) f(x \vee y) \quad \text{for all } x, y \in \mathbb{R}^m.$$

- A function $f : \mathbb{R}^m \rightarrow \mathbb{R}$ is **log- L^{\natural} -concave (LLC)** if

$$f(x)f(y) \leq f((x + \alpha \mathbf{1}) \wedge y) f(x \vee (y - \alpha \mathbf{1})) \quad \forall \alpha \geq 0 \text{ and } x, y \in \mathbb{R}^m.$$

Log- L^{\natural} -concave (LLC) functions

- A function $f : \mathbb{R}^m \rightarrow \mathbb{R}$ is **MTP₂** if

$$f(x)f(y) \leq f(x \wedge y) f(x \vee y) \quad \text{for all } x, y \in \mathbb{R}^m.$$

- A function $f : \mathbb{R}^m \rightarrow \mathbb{R}$ is **log- L^{\natural} -concave (LLC)** if

$$f(x)f(y) \leq f((x + \alpha \mathbf{1}) \wedge y) f(x \vee (y - \alpha \mathbf{1})) \quad \forall \alpha \geq 0 \text{ and } x, y \in \mathbb{R}^m.$$

Theorem (Murota, 2008)

A function $f : \mathbb{Z}^m \rightarrow \mathbb{R}$ is LLC if and only if it is log-concave, i.e.,

$$f(x)f(y) \leq f\left(\left\lfloor \frac{x+y}{2} \right\rfloor\right) f\left(\left\lceil \frac{x+y}{2} \right\rceil\right) \quad \text{for all } x, y \in \mathbb{Z}^m.$$

Ex.: A Gaussian distribution with covariance matrix Σ is LLC if and only if $K = \Sigma^{-1}$ is a **diagonally dominant M-matrix**, i.e.,

$$K_{ij} \leq 0 \text{ for all } i \neq j \quad \text{and} \quad \sum_{j=1}^m K_{ij} \geq 0 \text{ for all } i = 1, \dots, m.$$

Existence and uniqueness of the MLE

Theorem (Robeva, Sturmfels, Tran and Uhler, 2018)

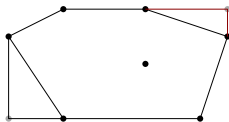
Let X_1, \dots, X_n be i.i.d samples from a distribution with density f_0 supported on a full-dimensional subset of \mathbb{R}^m . The following hold with probability one:

- If $n \geq 3$, the MTP_2 log-concave MLE exists and is unique.
 - If $n \geq 2$, the LLC log-concave MLE exists and is unique.
-
- This result is in contrast with existence of the MLE under log-concavity, where $n \geq m + 1$ samples are needed for existence
 - Proof uses convergence properties for log-concave distributions, and does not shed light on the shape of the MLE.

Support of the MLE

Under MTP_2 we need the density to be nonzero at additional points:

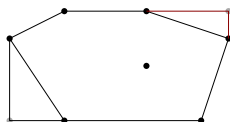
\implies "Min-max convex hull" of X



Support of the MLE

Under MTP_2 we need the density to be nonzero at additional points:

\implies "Min-max convex hull" of X



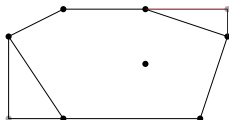
- $MM(X) :=$ smallest min-max closed set S containing X , i.e.
 $x, y \in S \implies x \wedge y, x \vee y \in S$
- $MMconv(X) :=$ smallest min-max closed & convex set containing X

Is it always true that $MMconv(X) = conv(MM(X))$?

Support of the MLE

Under MTP_2 we need the density to be nonzero at additional points:

\Rightarrow "Min-max convex hull" of X



- $MM(X) :=$ smallest min-max closed set S containing X , i.e.
 $x, y \in S \Rightarrow x \wedge y, x \vee y \in S$
- $MMconv(X) :=$ smallest min-max closed & convex set containing X

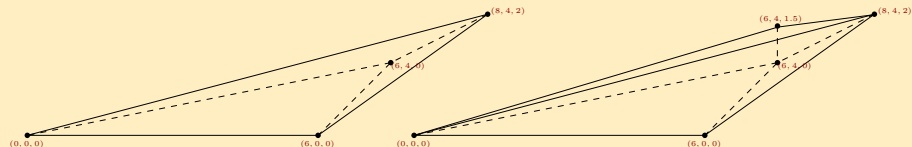
Is it always true that $MMconv(X) = conv(MM(X))$?

Lemma

If $X \subseteq \mathbb{R}^2$ or $X \subseteq \{0, 1\}^m$, then $MMconv(X) = conv(MM(X))$.

Support of the MLE in higher dimensions

Ex: Consider $X = \{(0, 0, 0), (6, 0, 0), (6, 4, 0), (8, 4, 2)\} \subseteq \mathbb{R}^3$.

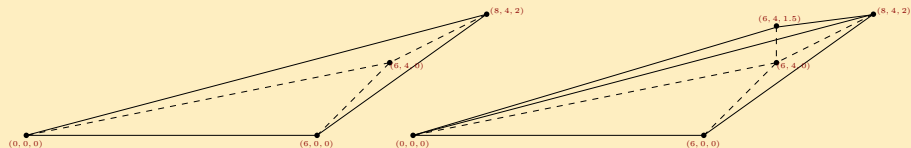


- $\text{MM}(X) = X$
- But $\text{conv}(\text{MM}(X))$ is **not min-max closed!**

$$(6, 4, 3/2) = \max\{(6, 4, 0), (6, 3, 3/2)\} \notin \text{conv}(\text{MM}(X)).$$

Support of the MLE in higher dimensions

Ex: Consider $X = \{(0, 0, 0), (6, 0, 0), (6, 4, 0), (8, 4, 2)\} \subseteq \mathbb{R}^3$.



- $MM(X) = X$
- But $\text{conv}(MM(X))$ is **not min-max closed!**

$$(6, 4, 3/2) = \max\{(6, 4, 0), (6, 3, 3/2)\} \notin \text{conv}(MM(X)).$$

Theorem (The 2-D Projections Theorem)

Let $\pi_{ij} : \mathbb{R}^m \rightarrow \mathbb{R}^2$, $x \mapsto (x_i, x_j)$. Then for any finite subset $X \subseteq \mathbb{R}^m$,

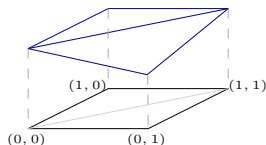
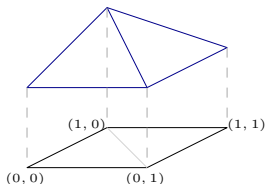
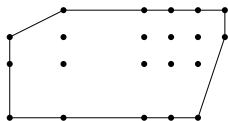
$$MM\text{conv}(X) = \bigcap_{1 \leq i < j \leq m} \pi_{ij}^{-1}(\text{conv}(\pi_{ij}(MM(X)))).$$

Exponentials of tent functions $h_{X,y}$

Theorem (Robeva, Sturmfels, Tran and Uhler, 2018)

Let $X \subset \mathbb{R}^m$ be a finite set of points. The exponential of a tent function $h_{X,y}$ is MTP_2 if and only if all of the walls of the subdivision h induces are **bimonotone**.

A linear inequality $a \cdot x + b \leq 0$ is **bimonotone** if it has the form $a_i x_i + a_j x_j + b \leq 0$, where $a_i a_j \leq 0$.

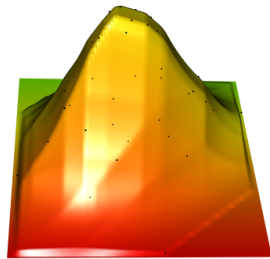
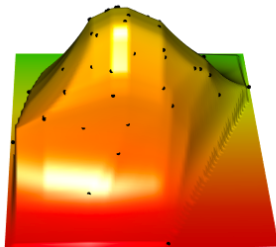
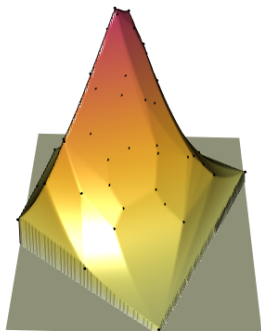


Shape of the MLE

Theorem (Robeva, Sturmfels, Tran and Uhler, 2018)

If $X \subseteq \mathbb{R}^2$ or $X \subseteq \{0,1\}^m$ ($X \subseteq \mathbb{Q}^m$), then the MTP_2 (LLC) MLE is of the form $\exp(\text{tent function})$ and the set of MTP_2 (LLC) tent pole heights define a convex polytope.

\implies We can use the **conditional gradient method** to compute the MLE



Conclusions

- We conjecture that the MTP_2 -MLE is always the exponential of a tent function (we provide conjectured tent pole locations)
- LLC estimate provides an MTP_2 estimate (might not be the MLE)
- Total positivity constraints are often implicit and reflect real processes
 - ferromagnetism
 - latent tree models
- Total positivity represents interesting shape constraint for non-parametric density estimation: broad enough class to be of interest in applications, constrained enough to obtain good density estimates with few samples
- MTP_2 / LLC is well-suited for high-dimensional applications

References

MTP₂ distributions not only have broad applications for data analysis, but also lead to interesting new problems in combinatorics, geometry & algebra.

- Fallat, Lauritzen, Sadeghi, Uhler, Wermuth, & Zwiernik: Total positivity in Markov structures, *Annals of Statistics* 45 (2017)
- Lauritzen, Uhler, & Zwiernik: Maximum likelihood estimation in Gaussian models under total positivity, to appear in *Annals of Statistics* (arXiv:1702.04031)
- Robeva, Sturmfels, & Uhler: Geometry of log-concave density estimation, *Discrete & Computational Geometry* 61 (2019)
- Robeva, Sturmfels, Tran & Uhler: Maximum likelihood estimation for totally positive log-concave densities (arXiv:1806.10120)
- Lauritzen, Uhler, & Zwiernik: Total positivity in structured binary distributions (to appear on the arXiv today!)

Thank you!