

Active Statistical Query Learning

Maria-Florina Balcan

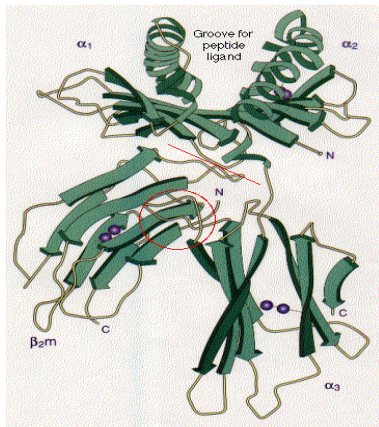


Vitaly Feldman, IBM Research

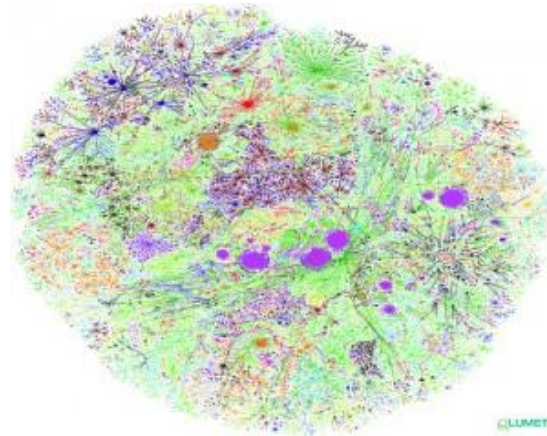
2-Minute Version

Modern applications: **massive amounts** of raw data.

Only **a tiny fraction** can be annotated by human experts.



Protein sequences



Billions of webpages



Images

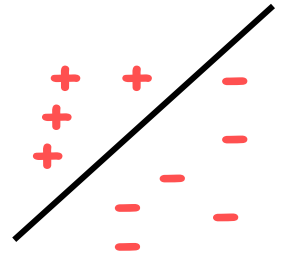
Active learning: leverage available data, minimize need for expert intervention.

2-Minute Version

Model for designing Statistical Active Learning (AL) algos



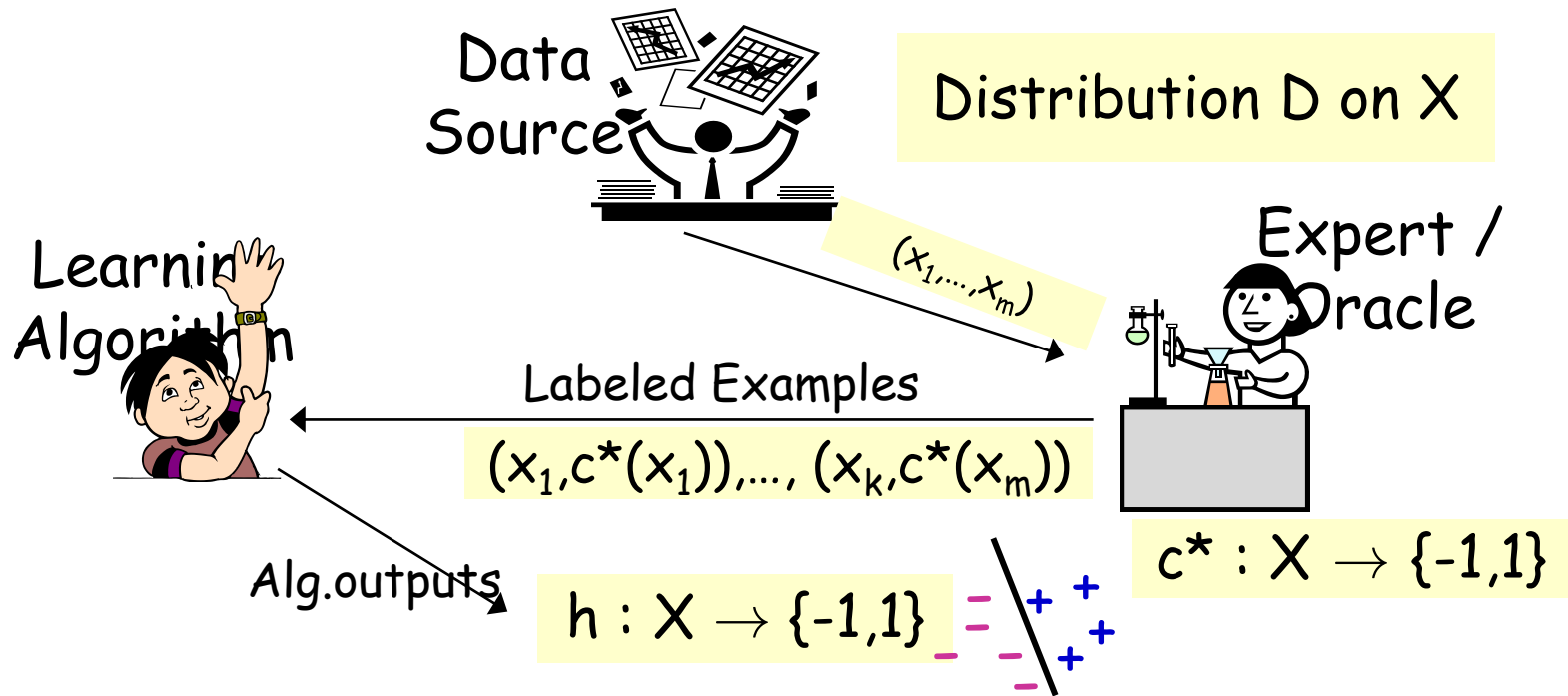
- Poly time statistical AL algos \rightarrow poly time algos tolerant to random classification noise.
- thresholds, rectangles, lin. separators.
- Naturally lead to differentially private AL algorithms.



Outline of the talk

- Passive Learning. Statistical Query Learning
- Active Learning
- Active Statistical Query Learning

Statistical / PAC learning model

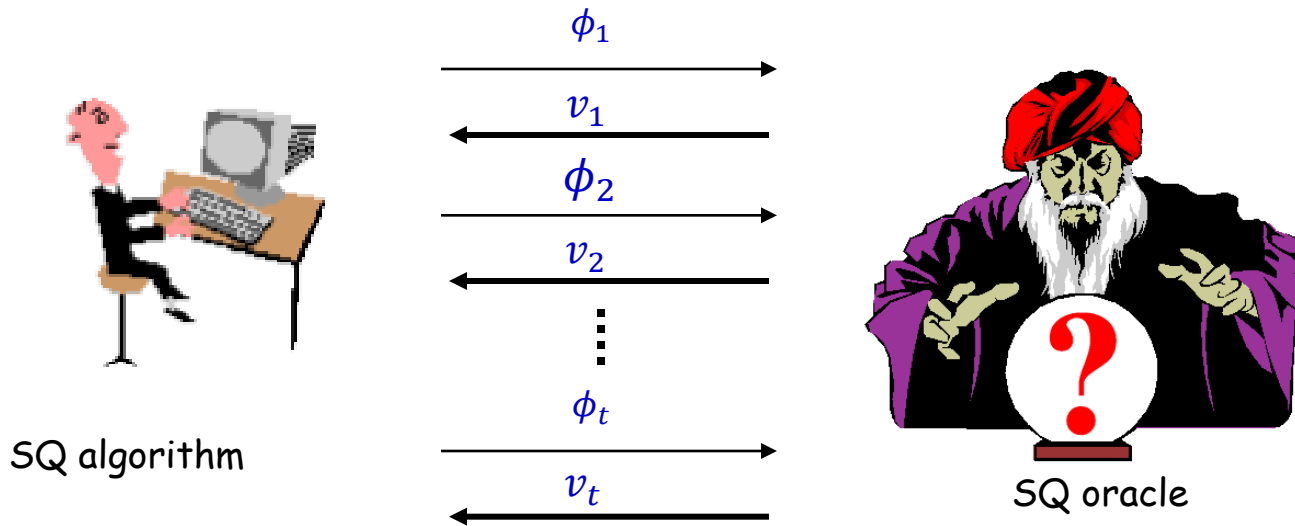


- Algo sees $(x_1, c^*(x_1)), \dots, (x_k, c^*(x_m))$, x_i i.i.d. from D ; $c^* \in \mathcal{C}$ [induce P]
- Do optimization over S , find hypothesis $h \in \mathcal{C}$.
- Goal: h has small error over D .

$$\text{err}(h) = \Pr_{x \in D}(h(x) \neq c^*(x))$$
- PAC model: poly time algo.

Statistical Query (SQ) Model [Kearns 93]

- Only statistical properties (not individual examples).
- Algo asks: "what is prob. a (labeled) example has property ϕ ? Pls. tell me up to additive error τ ."

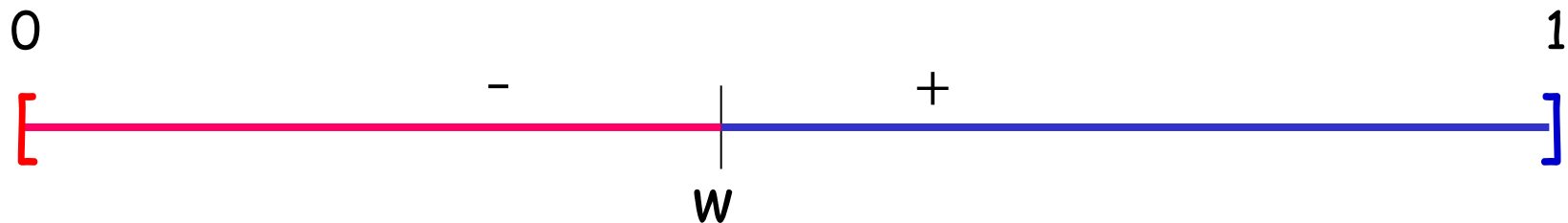


$$|v_i - \mathbf{E}_D[\phi_i(x, c^*(x))]| \leq \tau_i$$

τ_i is tolerance of the query

Must output h of error $\leq \epsilon$.

Simple Example: Threshold Fns



If D uniform

- Ask $p = \Pr(x \text{ is positive})$ up to tolerance ϵ .
[use query $\phi(x, l) = \frac{1+l}{2}$; $\tau = \epsilon$]
- Output $1-p$.

In general,

- Ask $p = \Pr(x \text{ is positive})$ up to tolerance $\epsilon/2$.
- Ask unlabeled SQs (binary search) to find z s.t.
 $\Pr(x \in (z, 1]) \in [p - \epsilon/2, p + \epsilon/2]$.
- Output z .

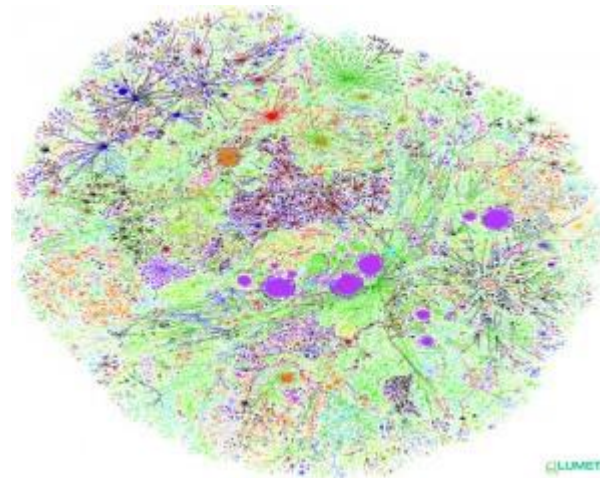
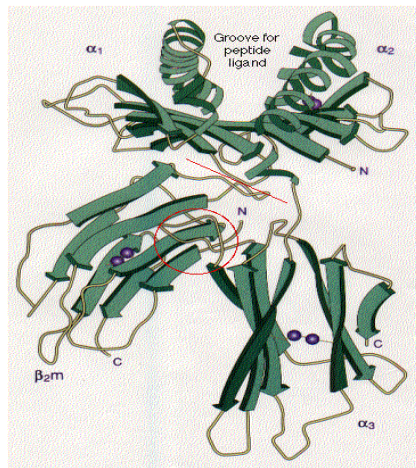
Properties of SQ model

- Can simulate SQ algos from random examples.
[Result of query ϕ, τ whp $1 - \delta$ from empirical expectation of $O\left(\frac{1}{\tau^2} \log\left(\frac{1}{\delta}\right)\right)$ random examples.]
- Can automatically convert to work in presence of random classification noise!
- Many ML algorithms have SQ analogues.
 - E.g, Perceptron, BFKV'96, DV'06 for linear separators.
- Can be made differentially private [BDMN'05]!

Classic Paradigm Insufficient Nowadays

Modern applications: **massive amounts** of raw data.

Only **a tiny fraction** can be annotated by human experts.

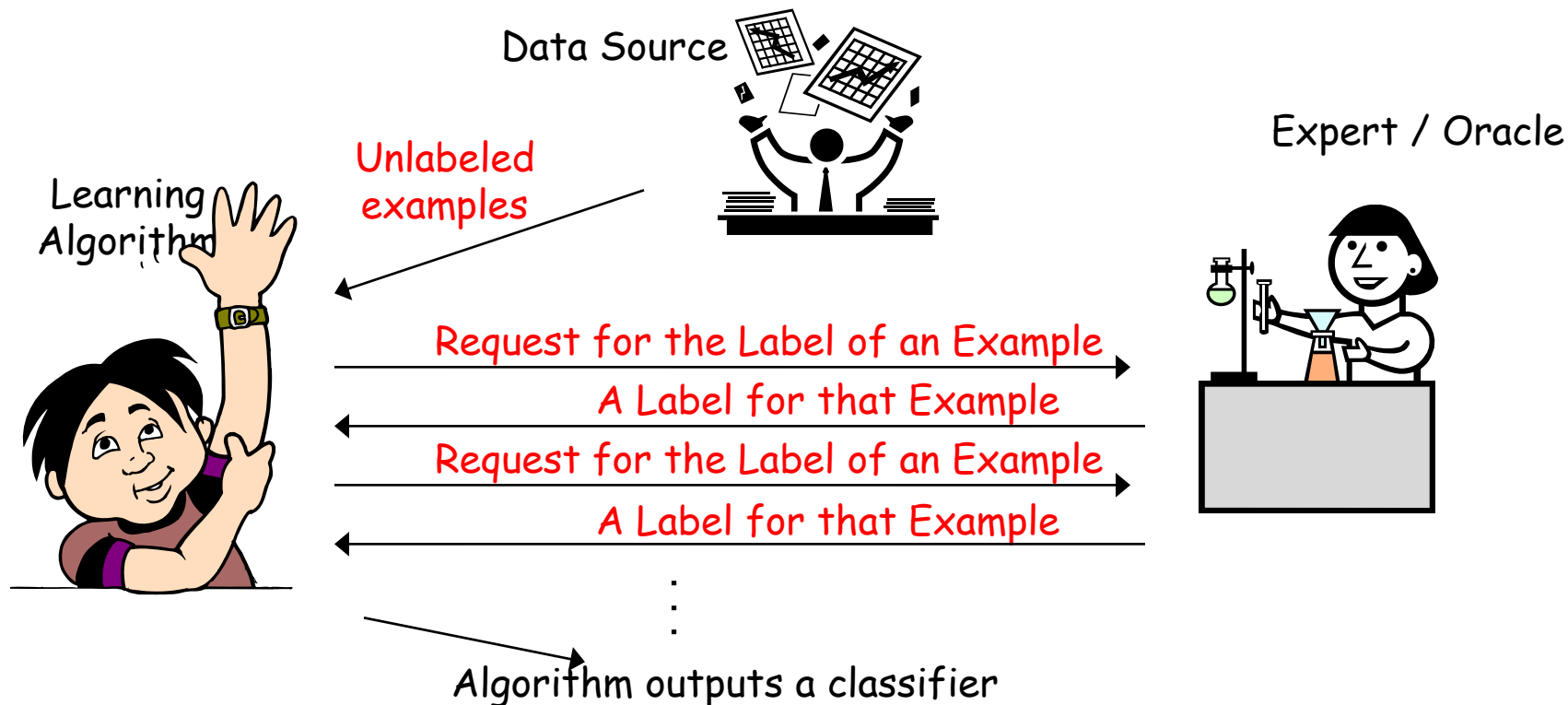


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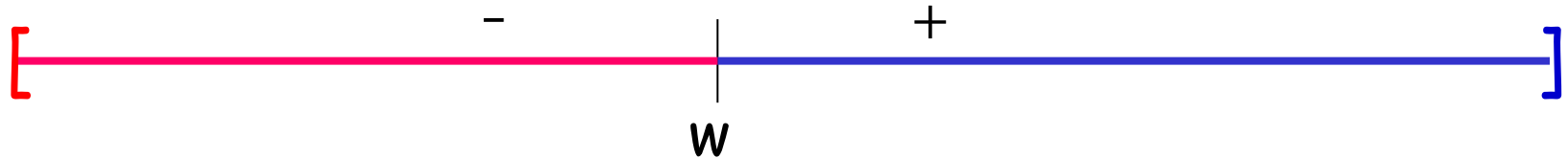
Active Learning: Major Area in Modern ML



- Learner can choose specific examples to be labeled.
- Goal: use fewer labeled examples.
 - Need to pick **informative** examples to be labeled.

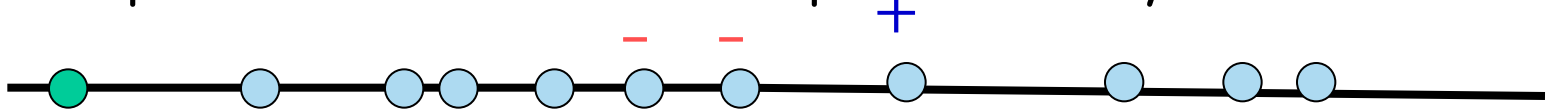
Provable Guarantees, Active Learning

- Canonical theoretical example [CAL92, Dasgupta04]



Active Algorithm

- Sample with $1/\epsilon$ unlabeled examples; do binary search.



Passive supervised: $\Omega(1/\epsilon)$ labels to find an ϵ -accurate threshold.

Active: only $O(\log 1/\epsilon)$ labels. **Exponential improvement.**

Lots of exciting activity in recent years

- Very general “disagreement based” algos [query pts from region of disagreement, throw out hyp. when statistically confident they are suboptimal]
 - First analyzed in [Balcan, Beygelzimer, Langford'06].
 - [Hanneke07, Dasgupta, Monteleoni'07, Wang'09, Fridman'09, Koltchinskii'10, BeygelzimerHsuLangfordZhang'10, Hsu'10, ...]
- Algos for specific (noise free) cases e.g., linear separators.
 - QBC [Freund et al., '97]
 - Active Perceptron [Dasgupta, Kalai, Monteleoni'05]
 - Margin Based AL [Balcan BroderZhang'07] [BalcanLong'13]

Computationally inefficient

Very specific



Open: poly time, noise tolerant AL algos.



This work: framework for designing poly time AL algos tolerant to random classification noise that satisfy DP naturally.

Active Statistical Query Model

Instead of access to random examples, algo only **gets active estimates of statistical properties**.

Query (χ, ϕ) , $\chi: X \rightarrow [0,1]$ filter [prob. of querying label of x]

"What is prob. a labeled example from $P_{|X}$ has property ϕ ?"

Pls. tell me up to additive error τ if $E_D[\chi(x)] \geq \tau_f$ "



If $E_D[\chi(x)] \geq \tau_f$ then $\left| v - E_{P_{|X}}[\phi(x, f(x))] \right| \leq \tau$
 τ_f filter tolerance; τ tolerance of query (χ, ϕ)

Algo gets an estimate of the prob that ϕ satisfied cond. on x satisfying χ .

Active Statistical Query Model

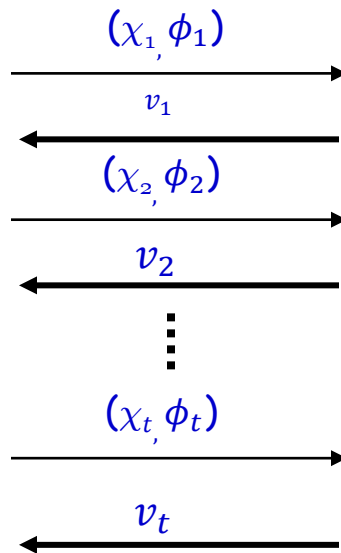
Query (χ, ϕ) , $\chi: X \rightarrow [0,1]$ filter [prob. of querying label of x]

"What is the prob. a labeled example from $P_{|X}$ has property ϕ ?"

Pls. tell me up to additive error τ if $E_D[\chi(x)] \geq \tau_f$ "



Active SQ algorithm



Active SQ oracle

Simulating Active Statistical Queries

Query (χ, ϕ) , τ_f , τ : if $E_D[\chi(x)] \geq \tau_f$ then $|v - E_{p|\chi}[\phi(x, f(x))]| \leq \tau$

Fact Can be simulated with $\frac{1}{\tau^2} \log\left(\frac{1}{\delta}\right)$ labeled examples and $\frac{1}{\tau_f} \frac{1}{\tau^2} \log\left(\frac{1}{\delta}\right)$ unlabeled samples.



Design algo with τ large [only τ_f small], much less labeled data.

Notes:

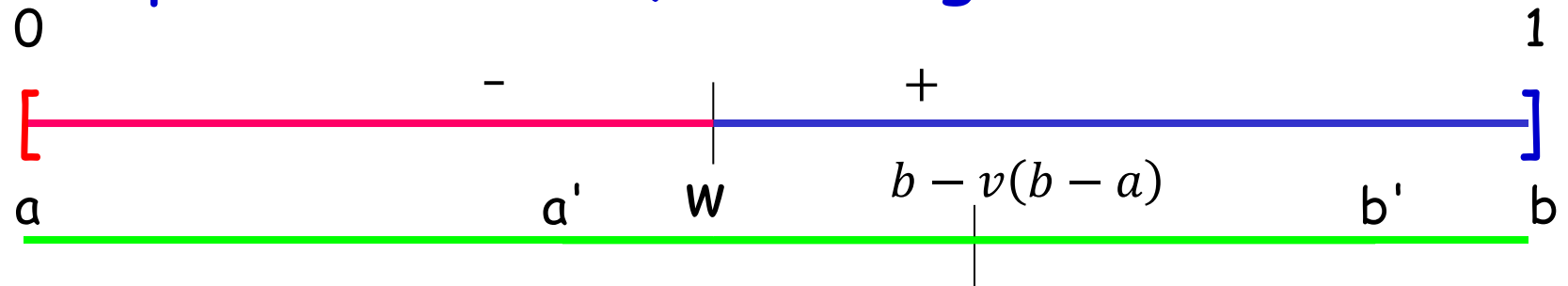
1. Generalizes SQ model ($\chi = 1$, $\tau_f = 1$).
2. Since $E_{P|\chi}[\phi(x, l)] = \frac{E_P[\phi(x, l) \chi(x)]}{E_P[\phi(x, l)]}$, can use 2 passive SQs.

Need to estimate $E_P[\phi(x, l) \chi(x)]$ within $\tau E_P[\phi(x, l)]$

Too much labeled data.



Example: Active SQ Learning of Thresholds



Passive SQ: Ask query $\phi(x, l) = \frac{1+l}{2}$ with tolerance ϵ ; so $1/\epsilon^2$ labels

Active SQ: Key : **localize/filter** and use only **constant** tolerance



Assume $w \in [a, b]$

Ask query $\phi(x, l) = \frac{1+l}{2}$; $\chi(x) = I_{x \in [a, b]}$; $\tau = \frac{1}{4}$, $\tau_f = b - a$; get v .

Know $|v - E[\phi(x, l) | x \in [a, b]]| \leq \frac{1}{4}$; $|E[\phi(x, l) | x \in [a, b]]| = \frac{b-w}{b-a}$

So $w \in \left[b - \left(v + \frac{1}{4} \right) (b - a), b - \left(v - \frac{1}{4} \right) (b - a) \right]$ twice smaller than $[a, b]$

Only $\log\left(\frac{1}{\epsilon}\right)$ rounds, and $\log\left(\frac{1}{\epsilon}\right) \log\left(\frac{\log\left(\frac{1}{\epsilon}\right)}{\delta}\right)$ labeled examples

Noise Tolerance

Fact Query $(\chi, \phi), \tau_f, \tau$

Under RCN given access to P^η estimate $E_{P|\chi}[\phi(x, l)]$ within τ using $\frac{1}{\tau^2} \frac{1}{(1-2\eta)^2} \log\left(\frac{1}{\delta}\right)$ labeled and $\frac{1}{\tau_f} \frac{1}{\tau^2} \frac{1}{(1-2\eta)^2} \log\left(\frac{1}{\delta}\right)$ unlabeled examples.

[Active SQs can be simulated from examples corrupted with RCN noise.]

Key points: Break into part affected by noise, and part unaffected; estimate each within $\frac{\tau}{2}$

$$\phi(x, l) = \frac{\phi(x, 1) - \phi(x, -1)}{2} l + \frac{\phi(x, 1) + \phi(x, -1)}{2}$$

$$E_{P^\eta|\chi} \left[\frac{\phi(x, 1) - \phi(x, -1)}{2} l \right] = (1 - 2\eta) E_{P|\chi} \left[\frac{\phi(x, 1) - \phi(x, -1)}{2} l \right]$$

sufficient to estimate it within $(1 - 2\eta)\tau/2$

Active SQ Learning of Linear Separators

Run a passive SQ algo to get w_0 with $\text{err}(w_0) < C$.

iterate $k = 2, \dots, s$

- let μ_k be the indicator fnc of being within γ_{k-1} of w_{k-1} .
- Let $\chi_k = \frac{\sum_{\{i \leq k\}} \mu_i}{k}$
- Run **passive SQ** over $D_{|\chi_k}$ to output w_k of error $\frac{C}{k}$ over $D_{|\chi_k}$.
[passive SQs over $D_{|\chi_k}$ implemented as active SQs with $\tau_f = C\epsilon$]

Theorem D log-concave in \mathbb{R}^d .

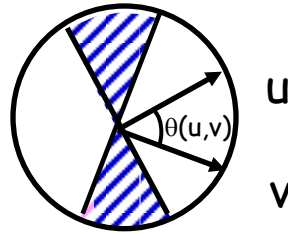
If $\gamma_k = O\left(\frac{C}{2^k}\right)$ then after $s = \log\left(\frac{1}{\epsilon}\right)$ iterations $\text{err}(w_s) \leq \epsilon$

Total number of labeled examples is $\text{poly}\left(d, \log\left(\frac{1}{\epsilon}\right)\right)$

Linear Separators, Log-Concave Distributions

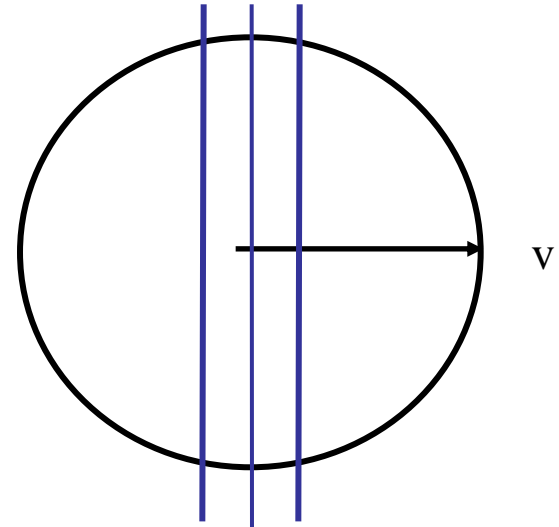
Fact 1

$$d(u, v) \approx \frac{\theta(u, v)}{\pi}$$



Fact 2

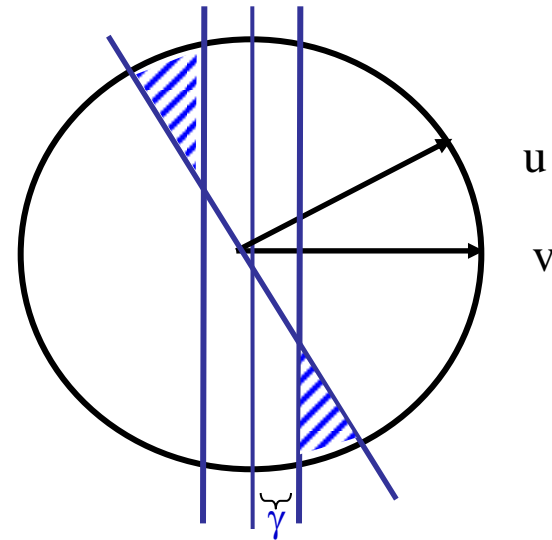
$$\Pr_x [|v \cdot x| \leq \gamma] \leq \gamma.$$



Linear Separators, Log-Concave Distributions

Fact 3 If $\theta(u, v) = \beta$ and $\gamma = C\beta$

$$\Pr_x [(u \cdot x)(v \cdot x) < 0, |v \cdot x| \geq \gamma] \leq \frac{\beta}{4}.$$

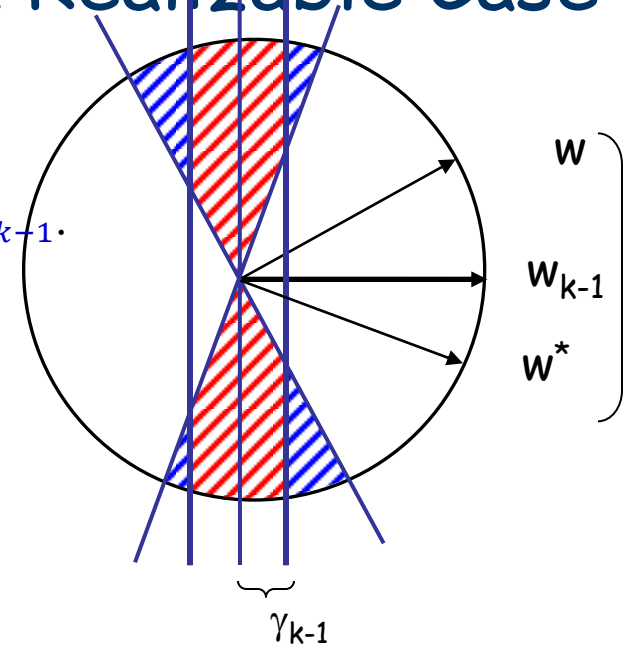


Margin Based Active-Learning, Realizable Case

Run a passive SQ algo to get w_0 with $\text{err}(w_0) < C$.

iterate $k = 2, \dots, s$

- let μ_k indicator fnc of being within margin γ_{k-1} of w_{k-1} .
- Let $\chi_k = \frac{\sum_{\{i \leq k\}} \mu_i}{k}$
- Run passive SQ over $D_{|\chi_k}$ with error $\frac{C}{k}$ and filter tolerance $C\epsilon$ to obtain w_k



Proof Idea

Induction: all w s.t. $\text{err}_{D_{|\mu_i}}(w) \leq C, i \leq k, \text{err}_D(w) \leq \frac{1}{2^k}$. So, $\text{err}_D(w_k) \leq \frac{1}{2^k}$

Let w s.t. $\text{err}_{D_{|\mu_i}}(w) \leq C$ for $i \leq k$.

$$\text{err}(w) = \Pr(w \text{ errs on } x, |w_{k-1} \cdot x| \geq \gamma_{k-1}) + \Pr(w \text{ errs on } x, |w_{k-1} \cdot x| \leq \gamma_{k-1})$$

Proof Idea

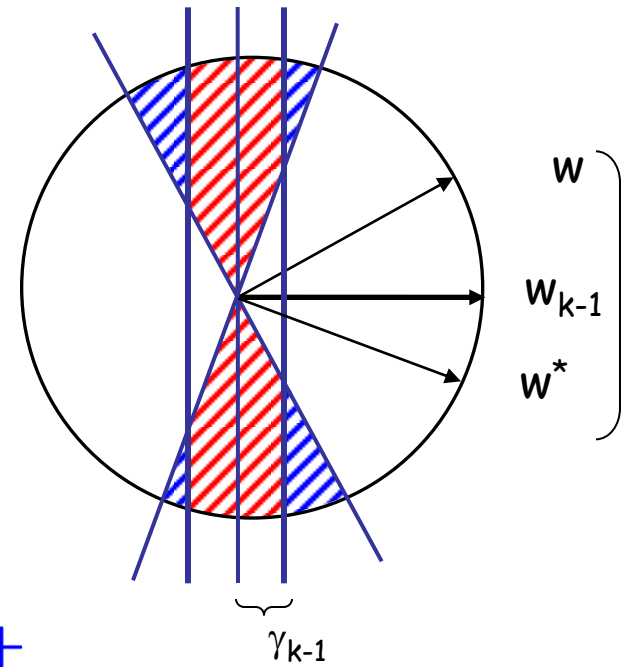
By induction $\text{err}_D(w) \leq \frac{1}{2^{k-1}}$, so $\theta(w, w^*) \leq 2^{-k+1}$

Also $\theta(w_{k-1}, w^*) \leq 2^{-k+1}$

For $\gamma_k = O\left(\frac{c}{2^k}\right)$

$$\text{err}(w) = \underbrace{\Pr(w \text{ errs on } x, |w_{k-1} \cdot x| \geq \gamma_{k-1})}_{\leq 1/2^{k+1}} +$$

$$\Pr(w \text{ errs on } x, |w_{k-1} \cdot x| \leq \gamma_{k-1})$$



Proof Idea

By induction $\text{err}_D(w) \leq \frac{1}{2^{k-1}}$, so $\theta(w, w^*) \leq 2^{-k+1}$

Also $\theta(w_{k-1}, w^*) \leq 2^{-k+1}$

For $\gamma_k = O\left(\frac{c}{2^k}\right)$

$$\text{err}(w) = \Pr(w \text{ errs on } x, |w_{k-1} \cdot x| \geq \gamma_{k-1}) +$$

$$\Pr(w \text{ errs on } x \mid |w_{k-1} \cdot x| \leq \gamma_{k-1}) \Pr(|w_{k-1} \cdot x| \leq \gamma_{k-1})$$

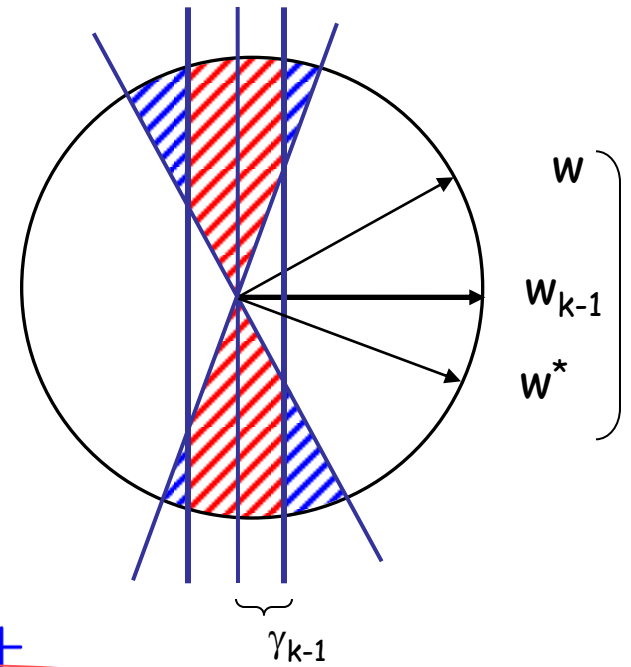
By assumption

$$\leq C$$

$$\leq C\gamma_{k-1}$$

$$\leq 1/2^{k+1}$$

So $\text{err}_D(w) \leq \frac{1}{2^k}$, as desired.



Active SQ Learning of Linear Separators

Theorem D log-concave in \mathbb{R}^d .

If $\gamma_k = O\left(\frac{c}{2^k}\right)$ then after $s = \log\left(\frac{1}{\epsilon}\right)$ iterations $\text{err}(w_s) \leq \epsilon$

Total number of labeled examples $\text{poly}\left(d, \log\left(\frac{1}{\epsilon}\right)\right)$

Label complexity:

- Round k , **passive SQ** over $D_{|X_k}$, get $\text{err}_{D_{|X_k}}(w_k) \leq \epsilon' = \frac{c}{k}$.
- Only $\text{poly}(d, \epsilon')$ passive SQs over $D_{|X_k}$ with $\tau = 1/\text{poly}(d, \epsilon')$
[can be implemented as active SQs with $\tau = 1/\text{poly}(d, \epsilon')$, $\tau_f = C\epsilon$].

Active Differential Privacy

Learner has full access to unlabeled portion of database S .
For every element of S can request the label.

Goal: 1. Do learning while minimize # label request

2. Ensure differential privacy [modifying a record in S does not affect much prob. that any h is output]

x_1	
...	
x_i	
...	
x_n	

Active Differential Privacy

A is α -differentially private if for any two neighbor datasets S , S' (differ in just one element $(x_i, y_i) \rightarrow (x_i', y_i')$).

X_1	
...	
x_i	y_i
...	
x_n	

X_1	
...	
x_i'	y_i'
...	
x_n	

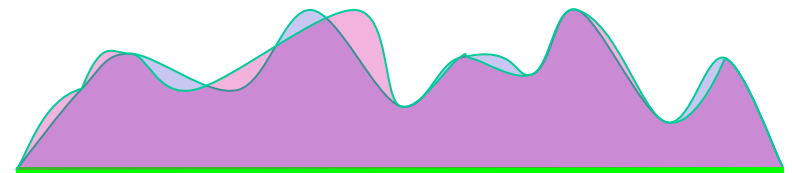
For all outcomes v ,

$$e^{-\alpha} \leq \frac{\Pr(A(S) = v)}{\Pr(A(S') = v)} \leq e^{\alpha}$$

$\approx 1 - \alpha$

$\approx 1 + \alpha$

Prob. over randomness in A



Active Differential Privacy

Theorem Any active SQ alg with M queries of tolerance τ , filter-tolerance τ_f , can be made to preserve α -Diff Privacy using $O\left(\left(\frac{M}{\alpha\tau} + \frac{M}{\tau^2}\right) \log(M)\right)$ label requests, $O\left(\left(\frac{M}{\alpha\tau\tau_f} + \frac{M}{\tau^2\tau_f}\right) \log(M)\right)$ unlabeled examples.

Privacy cost

original

Privacy cost

original

Implications:

- For $\alpha \geq \tau$, privacy “for free” in terms of # of labeled requests.
- For lin. sep. & thresholds, can learn and preserve DP with much fewer label requests than non-private passive as long as α is large compared to ϵ .

Active Differential Privacy

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Privacy cost

original

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Proof sketch:

- Answer each query using disjoint set of $O\left(\left(\frac{1}{\alpha\tau\tau_f} + \frac{1}{\tau^2\tau_f}\right) \log(M)\right)$ unlabeled exs.
- Will query the T examples that pass the filter and add Laplace noise.
- Sets are disjoint so suffices to satisfy α -DP per query.
- Query sensitivity is $\frac{1}{T}$, so suffices to add $\frac{1}{\alpha T}$ Laplace noise per query.
- Sample size large enough so that whp, noise added is $\leq \tau/2$. Combine with $\tau/2$ from sample size to get whp overall error $\leq \tau$ per query.

Discussion

Model for designing Statistical Active Learning (AL) algos

- Poly time statistical AL algos \rightarrow poly time algos tolerant to random classification noise.
- Naturally lead to differentially private AL algorithms.

Open questions

Deal with more general types of noise [ABL'13].

Practical Implications?