

Mixing Time of Open Quantum Systems via Hypocoercivity

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Join work with
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Outline

- 1 Mixing time: state of the art and open question
- 2 The Idea of Hypocoercivity
- 3 Our Results – Statement and Understanding
- 4 Applications to Physical Examples

Mixing Time of Open Quantum Systems

Heisenberg Picture

$$\partial_t A = \mathcal{L}A = \underbrace{i[H, A]}_{=:\mathcal{H}} + \underbrace{\sum_j V_j^\dagger [A, V_j] + [V_j^\dagger, A] V_j}_{=:\mathcal{D}}.$$

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Why do we care?

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Algorithmic advancement employing Lindblad equations:

- Universal quantum computation, useful in **quantum field theories simulation**
 [Verstraete-Wolf-Cirac, Nature Physics 2009], [Osborne-Eisert-Verstraete PRL 2010], [Verstraete-Cirac PRL 2010]
- To prepare and sample from **thermal states**
 [Chen-Kastoryano-Gilyen 2023], [Chen-Kastoryano-Brandao-Gilyen 2023], [Rall-Wang-Wocjan Quantum 2023], [Ding-Li-Lin 2024], [Jiang-Irani 2024], etc
- **Ground states preparation**
 [Ding-Chen-Lin PRR 2024]
- To find **local minima in quantum systems**
 [Chen-Huang-Preskill-Zhou STOC 2024]
- **Quantum control**
 [Li-Wang ICML 2023]
- **Classical optimization**
 [Chen-Lu-Wang-Liu-Li 2023]

Mixing Time

Quantum Info (target)

Quantum Markov Semigroup

$$\partial_t A = \mathcal{L}A$$

$$t_{\text{mix}}(\epsilon) = \inf\{t \geq 0 : \|e^{s\mathcal{L}^*}(\rho) - \sigma\|_1 \leq \epsilon, \forall \rho, s \geq t\}.$$

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Probability Viewpoint

(Ergodicity, Detailed Balance, etc)

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Probability Viewpoint

(Ergodicity, Detailed Balance, etc)

Dynamical System /

Differential Equation Viewpoint

(Lyapunov functionals)

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Previous Works for Mixing Time Estimate

How to estimate the mixing time? Typical route:

- One starts with a Lindbladian that satisfies **detailed balance condition** under certain inner product. (If not, consider a symmetrization of \mathcal{L} , denote as \mathcal{L}_H .)

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- It implies exponential decay with rate g , namely,

$$\|A(t)\| \leq \|A(0)\| e^{-gt}.$$

Then by duality, one can get an estimate of the mixing time. In particular, $g \sim 1/\text{poly}(N)$ implies $t_{\text{mix}} \sim \text{poly}(N)$.

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- For some g , e.g., $g = \Omega(1)$, **modified logarithmic Sobolev inequality** can tighten the bound $\Rightarrow t_{\text{mix}} \sim \text{polylog}(N)$.²

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To estimate mixing time:

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Questions:

- Can we use information about the dissipative part \mathcal{D} and the Hamiltonian part \mathcal{H} **separately** to yield a mixing time estimation?
- What if \mathcal{L} is not detailed balance? Are there still some cases that we can estimate?

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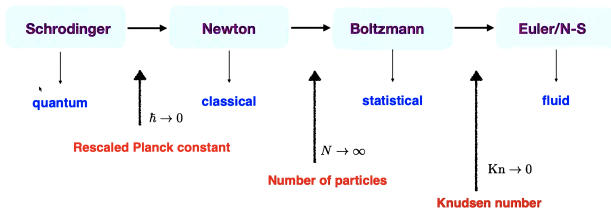
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- So what? Applications? We provide a number of physical examples where our conditions can be easily verified, including the **transverse field Ising model**, **Heisenberg model**, and **quantum walk**, with some Pauli noise.
- The technique is based on the construction of an energy functional inspired by the **hypocoercivity** of (classical) kinetic theory.

What is Hypocoercivity?

Some History:

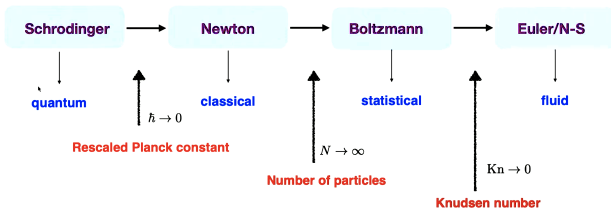
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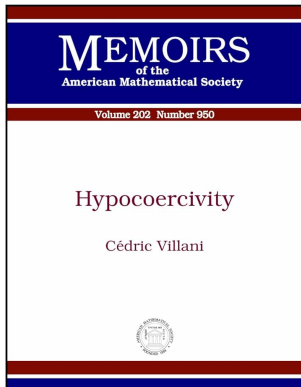
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Quantum!

Minimal Example – Coercivity v.s. Hypocoercivity

Consider a n -dimensional real-valued ODE of:

$$\frac{d}{dt}x = -Ax, \quad t \geq 0.$$

From **Arnold's** talk that DF attended in 2017. Similar ODE examples, see standard ODE textbook, e.g., [Teschl Page 203], [Brauer-Nohel Page194]

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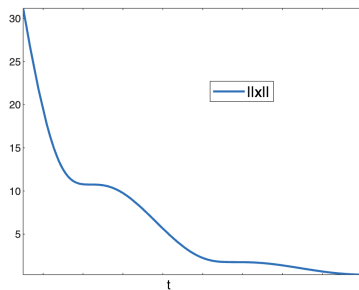
$$A = \begin{pmatrix} 0 & -1 \\ 1 & 1 \end{pmatrix} \rightarrow \text{e-vals are } \frac{1}{2} \pm i \frac{\sqrt{3}}{2}.$$

From ODE basics, the solution decays with a rate $\frac{1}{2}$. But the vanilla energy method no longer works! $\frac{d}{dt} \|x(t)\| \leq 0$ (instead of $-g \|x(t)\|$).

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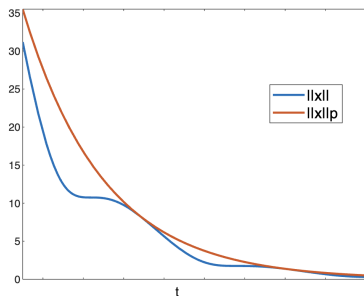
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Instead of $x^2 + y^2$, the Lyapunov function is now $x^2 + y^2 + xy \propto \|x\|_P^2$.

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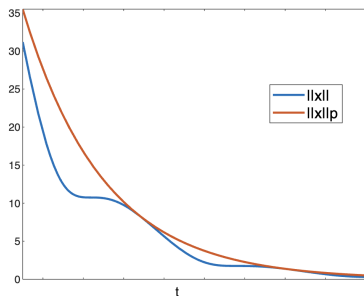
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For e^{-tA} that decays yet A not coercive, it is “**hypocoercive**”.

Our Results – Preparation

For Lindblad Equation (Heisenberg picture)

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Denote the global equilib. state as σ . We consider GNS inner product

$$\langle A, B \rangle = \text{tr}(\sigma A^\dagger B).$$

Remark: Other inner products $\langle A, B \rangle_\alpha = \text{tr}(\sigma^\alpha A^\dagger \sigma^{1-\alpha} B)$ are also ok.

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Lindblad equation is linear \Rightarrow consider the “**difference**” between a Hermitian A and the fixed point of \mathcal{L} starting from A , i.e. the fluctuation around the global equilibrium, can be defined as

$$A - \frac{\langle I, A \rangle}{\langle I, I \rangle} I = A - \text{tr}[\sigma A] I,$$

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Suppose σ is maximally mixed state. We will only see the contribution from the part \mathcal{D} !

If \mathcal{D} is degenerate, $\dim \ker D > 1$. The energy method fails!

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Consider Trotterization viewpoint:

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Any matrix A can be decomposed into

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where \mathcal{P} is the projection onto the **kernel of \mathcal{D}** .

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where \mathcal{P} is the projection onto the **kernel of \mathcal{D}** .

By dissipative nature of $\mathcal{D} \Rightarrow$ dynamics $\exp.$ damps $(\mathcal{I} - \mathcal{P})A$.

Our Results – Intuition

Consider Trotterization viewpoint:

$$e^{t\mathcal{L}} = e^{t\mathcal{H}+t\mathcal{D}} \approx \left(e^{t\mathcal{H}/L} e^{t\mathcal{D}/L} \right)^L$$

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For $\mathcal{P}A$, we observe that

$$\begin{aligned} e^{t\mathcal{H}/L}\mathcal{P}A &= \mathcal{P}A + \mathcal{H}\mathcal{P}A t/L + \mathcal{O}(t^2/L^2) \\ &= \mathcal{P}A + (\mathcal{I} - \mathcal{P})\mathcal{H}\mathcal{P}A t/L + \mathcal{P}\mathcal{H}\mathcal{P}A t/L + \mathcal{O}(t^2/L^2) \end{aligned}$$

If $\mathcal{P}\mathcal{H}\mathcal{P} = 0$, the $\mathcal{P}A$ part is being driven to the image of $\mathcal{I} - \mathcal{P}$, i.e., the orthogonal complement of $\ker \mathcal{D}$, which will then be damped by \mathcal{D} in the next step.

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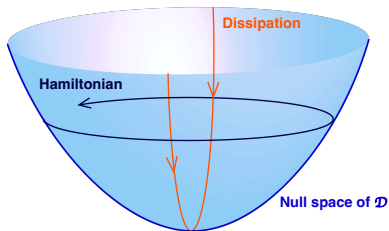
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Note that \mathcal{H} transforms a diagonal matrix into an off-diagonal one, so that $\mathcal{P}\mathcal{H}\mathcal{P} = 0$. We can also compute that

$$e^{t\mathcal{D}} A = \begin{pmatrix} a & e^{-t}b \\ e^{-t}c & d \end{pmatrix},$$

where everything outside of $\ker \mathcal{D}$ is damped exponentially, while the dynamics governed by \mathcal{H} mixes the terms.

Our Results – Conditions

Condition 1: The operator \mathcal{D} is symmetric and satisfies

$$-\langle \mathcal{D}A, A \rangle \geq \lambda_m \|\mathcal{I} - \mathcal{P}\|A\|^2,$$

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Condition 4: $\|\mathcal{H}(\mathcal{I} - \mathcal{P})A\| + \|\mathcal{D}A\| \leq C'_M \|(\mathcal{I} - \mathcal{P})A\|$, for all Hermitian A .

Our Results

Theorem (Main result)

Under conditions 1-4, there exist positive constants λ and C , explicitly computable in terms of λ_m , λ_M and C_M such that

$$\left\| e^{t(\mathcal{H}+\mathcal{D})} A \right\| \leq C e^{-\lambda t} \|A\|, \quad \forall t \geq 0.$$

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$$C = \left(\frac{1+\varepsilon}{1-\varepsilon} \right)^{1/2}, \quad \lambda = \min \left\{ \frac{1}{4} \frac{\lambda_m}{1+\varepsilon}, \frac{1}{3} \frac{\varepsilon}{1+\varepsilon} \frac{\lambda_M}{\alpha + \lambda_M} \right\},$$

where ε are defined in

$$\varepsilon = \frac{1}{2} \min \left\{ \frac{\lambda_m \lambda_M}{(\alpha + \lambda_M)(1 + C'_M/(2\sqrt{\alpha}))^2}, 1 \right\}.$$

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Corollary (Mixing time estimate)

Under conditions 1-4, for $\lambda_m, \lambda_M \leq \mathcal{O}(1)$, $C'_M \geq \Omega(1)$, if σ is full-rank, the mixing time $t_{\text{mix}}(\epsilon)$ satisfies

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- Remark: 1. \mathcal{L} does NOT need to satisfy detailed balanced conditions.
 2. Take-home message: **Hamiltonian enhances mixing**.

Applications to Physical Examples – Single Qutrit

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$$V_1 = \sqrt{\gamma}\sigma^-, \quad V_2 = \sqrt{\gamma}\sigma^+,$$

where $\sigma^- = |0\rangle\langle 1|$ is the lowering operator, and $\sigma^+ = |1\rangle\langle 0|$ is the raising operator. $\mathcal{H}A = i[H, A]$, $\mathcal{D}A = \sum_j V_j^\dagger [A, V_j] + [V_j^\dagger, A]V_j$.

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$$\sigma = \frac{1}{2} |0\rangle\langle 0| + \frac{1}{4} |1\rangle\langle 1| + \frac{1}{4} |2\rangle\langle 2|.$$

One can verify all conditions with $\lambda_m = (3/2)\gamma$, $\lambda_M = \omega^2$, and $C'_M = \mathcal{O}(|\omega| + \gamma)$. Our theorem yields:

$$t_{\text{mix}}(\epsilon) = \mathcal{O}((\omega^2 + \gamma^2)\omega^{-2}\gamma^{-1} \log(1/\epsilon))$$

Applications to Physical Examples – N-body systems

Dephasing noise:

$$\mathcal{D}A = \gamma \sum_i (Z_i A Z_i - A).$$

The kernel of \mathcal{D} is spanned by $\{Z^{\otimes \vec{b}} : \vec{b} \in \{0, 1\}^N\}$.
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$$t_{\text{mix}}(\epsilon) = \mathcal{O}\left(\frac{N^2(1+\gamma)^2}{\gamma h^2}(N + \log(1/\epsilon))\right).$$

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Example 4: **Quantum Walk Under Dephasing Noise.**

On a d -regular connected graph $G = (V, E)$, denote its adjacency matrix as

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The smallest eigenvalue of the graph Laplacian $L = dI - H$ is 0. The second smallest eigenvalue is denoted as Δ (i.e. the spectral gap).

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$\lambda_M = 2\Delta$ and $C'_M = \mathcal{O}(d + \gamma N)$. Our theorem yields:

$$t_{\text{mix}}(\epsilon) = \mathcal{O} \left(\frac{(d + \gamma N)^2}{\gamma \Delta} (N + \log(1/\epsilon)) \right).$$

Our results – Proof Idea

If we consider a naive energy estimate using $\|A\|^2$,

$$\partial_t A = (\mathcal{H} + \mathcal{D})A, \quad \langle A, B \rangle = \text{tr}(\sigma A^\dagger B).$$

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To characterize the convergence we construct a **twisted norm**, which serves as a Lyapunov functional of the system, as

$$\mathfrak{L}[A] := \frac{1}{2} \|A\|^2 - \varepsilon \Re \langle \mathcal{A}A, A \rangle,$$

with some $\varepsilon \in (0, 1)$ to be fixed and

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for some $\alpha > 0$. Importantly, this Lyapunov functional can be shown equivalent to $\|A\|$, namely,

$$\frac{1}{2} (1 - \varepsilon) \|A\|^2 \leq \mathfrak{L}[A] \leq \frac{1}{2} (1 + \varepsilon) \|A\|^2.$$

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Remark. In fact Condition 4, i.e.

$$\|\mathcal{H}(\mathcal{I} - \mathcal{P})A\| + \|\mathcal{D}A\| \leq C'_M \|(\mathcal{I} - \mathcal{P})A\|,$$

for all Hermitian A , can be relaxed to

$$\|\mathcal{A}\mathcal{H}(\mathcal{I} - \mathcal{P})A\| + \|\mathcal{A}\mathcal{D}A\| \leq C_M(\alpha) \|(\mathcal{I} - \mathcal{P})A\|$$

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Conclusion

We propose a new theoretical framework to estimate the mixing time of the Lindblad Equation that **treats \mathcal{H} and \mathcal{D} separately** via hypocoercivity. It

- thus *circumvents* the need for a priori estimation of the **spectral gap of the full Lindbladian** generator;
- does *not* require the Lindbladian to satisfy the **detailed balance condition**;
- can be applied to various physical examples, include Transverse Field Ising Model, Heisenberg Model, and quantum walk.

Future Directions

- More applications?
- Relax the condition of $PHP = 0$?
- There are various different frameworks of hypocoercivity for kinetic theory. What are their quantum analog? Can they yield tighter estimate?

Thank you for your attention!

Reference:

Mixing Time of Open Quantum Systems via Hypocoercivity
Di Fang, Jianfeng Lu, Yu Tong [arXiv:2404.11503]



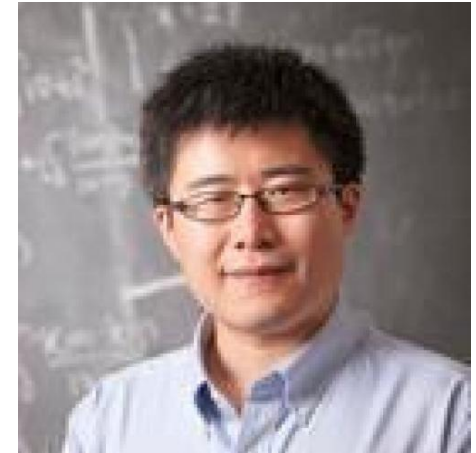
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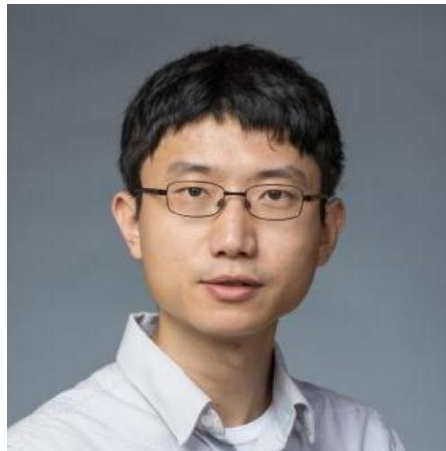
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