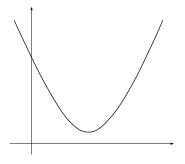
Convex Analysis at Infinity

An Introduction to Astral Space

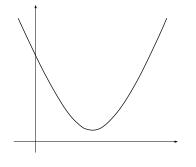
Miro Dudík Rob Schapire Matus Telgarsky

further reading at: aka.ms/astral

Convex functions

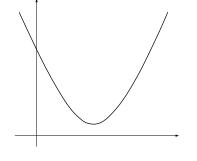


Convex functions

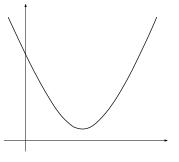


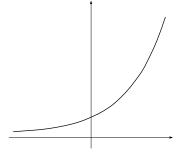
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 - e.g.: maximum likelihood, maximum entropy, linear regression, logistic regression, boosting, SVM's, ...

Convex functions

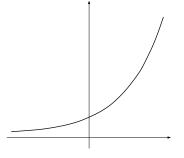


- minimizing convex functions is basis for many methods in machine learning and statistics (and other fields)
 - e.g.: maximum likelihood, maximum entropy, linear regression, logistic regression, boosting, SVM's, ...
- convex functions are really nice!
 - local minimum must be global minimum
 - if gradient = 0 then must be global minimum
 - usually easier to find and analyze minimization algorithms
 - beautiful properties

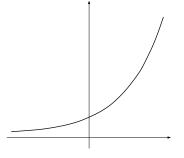




- problem: some convex functions have no finite minimizer
 - function then must be minimized by sequence heading "to infinity"

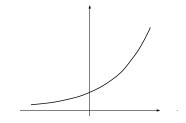


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 - analyzing convergence often requires carefully tailored techniques



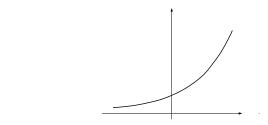
- problem: some convex functions have no finite minimizer
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 - analyzing convergence often requires carefully tailored techniques
- this talk: develop theory for studying such minimizers at infinity

Example: exponential function



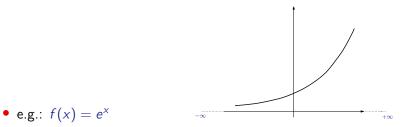
• e.g.:
$$f(x) = e^x$$

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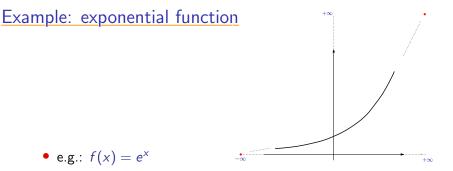
- e.g.: $f(x) = e^x$
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- can do by:
 - extending ℝ to include ±∞:

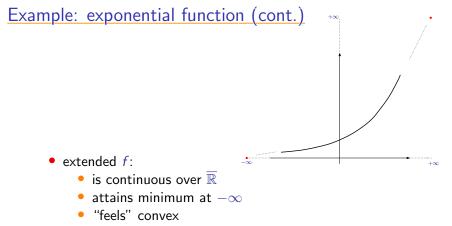
 $\overline{\mathbb{R}} = \mathbb{R} \cup \{-\infty, +\infty\} = [-\infty, +\infty]$



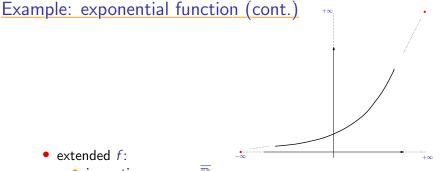
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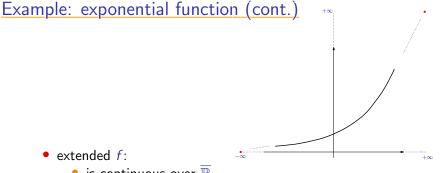
• extending f to $\overline{\mathbb{R}}$ by setting: $f(-\infty) = 0$ and $f(+\infty) = +\infty$



• maybe can extend derivatives so that $f'(-\infty) = 0$



- is continuous over $\overline{\mathbb{R}}$
- attains minimum at $-\infty$
- "feels" convex
- maybe can extend derivatives so that $f'(-\infty) = 0$
- in n = 1 dimensions, seems clear how to
 - add "points at infinity"
 - extend functions to enlarged space, capturing minimizers at infinity



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- what about in n ≥ 2 dimensions?



• extend \mathbb{R}^n to include points at infinity



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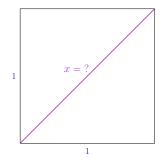
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 - e.g., so every convex function, when extended to new space, has a minimizer
- want compatible with key notions of convex analysis

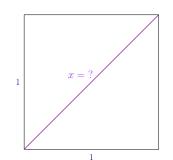
<u>Analogy</u>

 if only working in Q = rationals, then no number equals length of diagonal of a unit square



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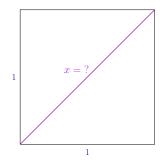
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• can approach value with sequences in \mathbb{Q} : $\frac{1}{1}, \frac{3}{2}, \frac{7}{5}, \frac{17}{12}, \frac{41}{29}, \frac{99}{70}, \frac{239}{169}, \ldots \rightarrow \sqrt{2}$ 1, 1.4, 1.41, 1.414, 1.4142, 1.41421, $\ldots \rightarrow \sqrt{2}$

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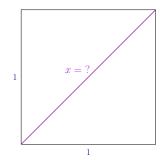
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- so don't "need" reals (can just work over sequences of rationals)
- far preferable to extend \mathbb{Q} to \mathbb{R}
 - much more complete, regular, well-structured

Analogy (cont.)

- in same way, can continue to use sequences to study minimizers of convex functions
 - might be much nicer to study minimizers at infinity as mathematical objects in their own right
 - can hope larger space would be more complete, regular, and revealing of structure

This work

- introduce astral space, extension of \mathbb{R}^n with points at infinity
- extend functions on \mathbb{R}^n to astral space
- study key properties and topics extended to astral space, especially from convex analysis

<u>Outline</u>

- what can minimizers at infinity look like?
- constructing astral space
- what are astral points like?
- extending functions to astral space
- convergence of iterative algorithms

Notation

- *n* = dimension
- scalars (in \mathbb{R}): x, y, \ldots
- vectors (in \mathbb{R}^n): $\mathbf{x}, \mathbf{u}, \mathbf{v}, \dots$
 - as tuple: $x = (x_1, ..., x_n)$

Notation

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- vectors (in ℝⁿ): **x**, **u**, **v**, ...
 - as tuple: $x = (x_1, ..., x_n)$
- all sequences indexed by $t = 1, 2, \dots$
- limits and convergence always as $t \to +\infty$
- (\mathbf{x}_t) is sequence $\mathbf{x}_1, \mathbf{x}_2, \ldots$

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Minimizers at infinity

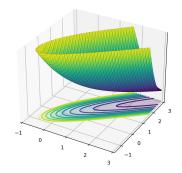
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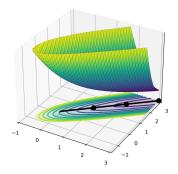
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- in n=1 dimensions, can only converge to $\pm\infty$
- in $n \ge 2$ dimensions, many possibilities
 - for example...



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$$\mathbb{R}^2$$
, say

$$f(\mathbf{x}) = f(x_1, x_2) = \underbrace{e^{-x_1}}_{+ \underbrace{(x_2 - x_1)^2}}$$

Example: Diagonal valley



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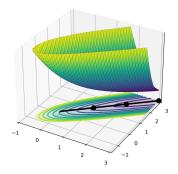
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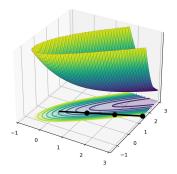
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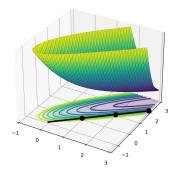
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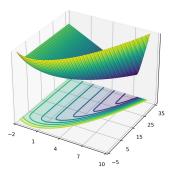
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 - direction matters
 - offset also matters

• can every convex function be minimized along a ray?

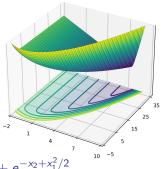


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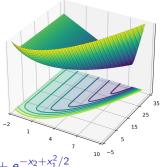
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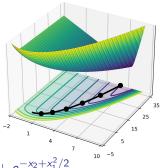
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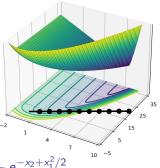
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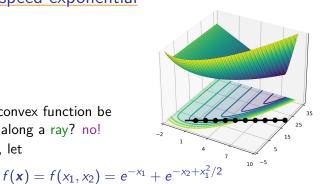
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Basic idea

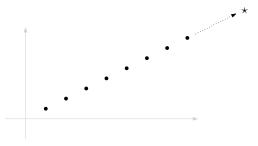
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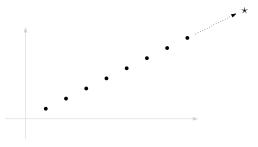
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- key questions:
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- once answered, can construct space:
 - add "new" points to be limits of each group of sequences that should all have same limit



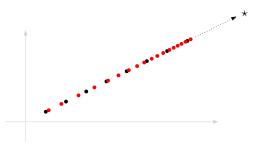
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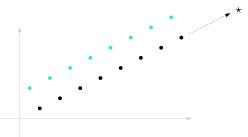
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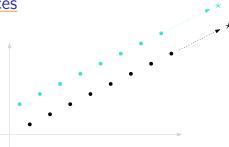
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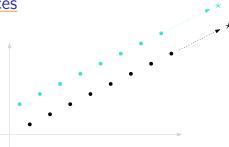
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- what sequences should have same limit?
 - e.g., if change rate converging to infinity



- say shift sequence by fixed offset
- $x_t = (2t, t) = tv$ where v = (2, 1) $x'_t = (2t - 1, t + 2) = tv + w$ where w = (-1, 2)



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- should two sequences have same limit?
- we believe no because:
 - offset matters for minimization
 - in applications, often care about such offsets, not just overall direction of minimization

A basic principle

• how to capture these intuitions?

A basic principle

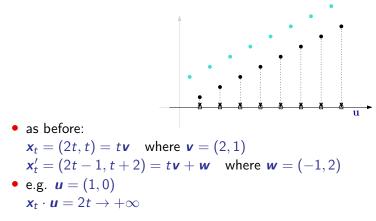
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- basic principle: focus on limits in every direction *u* ∈ ℝⁿ i.e., along one-dimensional projections of the sequence

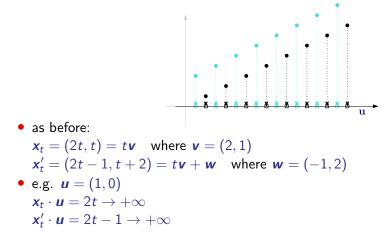
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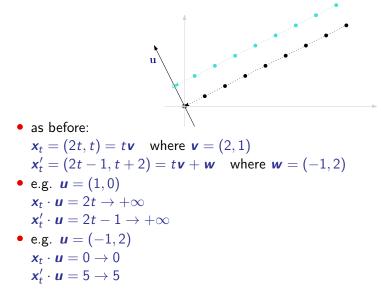
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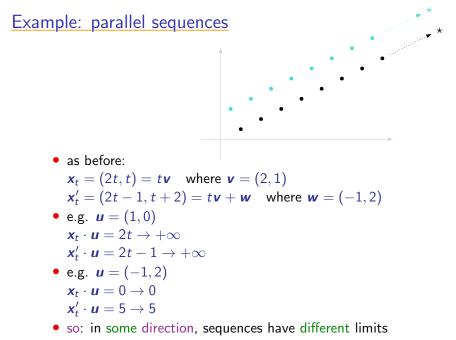






Example: parallel sequences u • as before: $x_t = (2t, t) = tv$ where v = (2, 1) $x'_{t} = (2t - 1, t + 2) = tv + w$ where w = (-1, 2)• e.g. u = (1, 0) $\mathbf{x}_t \cdot \mathbf{u} = 2t \rightarrow +\infty$ $\mathbf{x}'_t \cdot \mathbf{u} = 2t - 1 \rightarrow +\infty$ • e.g. u = (-1, 2) $\mathbf{x}_t \cdot \mathbf{u} = 0 \rightarrow 0$ $\mathbf{x}'_t \cdot \mathbf{u} = 5 \rightarrow 5$

• so: in some direction, sequences have different limits



• therefore: require (\mathbf{x}_t) and (\mathbf{x}'_t) to have different limits



• which sequences (x_t) should have limits?



- which sequences (x_t) should have limits?
 - exactly those that converge in all directions
 - meaning: $\lim(\mathbf{x}_t \cdot \mathbf{u})$ exists for all $\mathbf{u} \in \mathbb{R}^n$

Our approach

- which sequences (*x*_t) should have limits?
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• when should two sequences (\mathbf{x}_t) and (\mathbf{x}'_t) have same limit?

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- which sequences (*x*_t) should have limits?
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 - meaning: $\lim(\mathbf{x}_t \cdot \mathbf{u})$ exists for all $\mathbf{u} \in \mathbb{R}^n$
- when should two sequences (\mathbf{x}_t) and (\mathbf{x}'_t) have same limit?
 - exactly when they are all-directions equivalent, i.e., have same limit in every direction
 - meaning: $\lim(\mathbf{x}_t \cdot \mathbf{u}) = \lim(\mathbf{x}'_t \cdot \mathbf{u})$ for all $\mathbf{u} \in \mathbb{R}^n$

Our approach

- which sequences (*x*_t) should have limits?
 - exactly those that converge in all directions
 - meaning: $\lim(\mathbf{x}_t \cdot \mathbf{u})$ exists for all $\mathbf{u} \in \mathbb{R}^n$
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• note that limits can be in $\overline{\mathbb{R}}$



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• in n = 1 dimensions, only add $\pm \infty$ so $\overline{\mathbb{R}^1}$ same as $\overline{\mathbb{R}}$

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 - very powerful property
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Outline

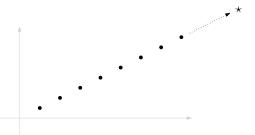
- what can minimizers at infinity look like?
- constructing astral space
- what are astral points like?
- extending functions to astral space
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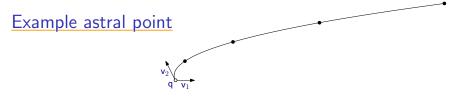
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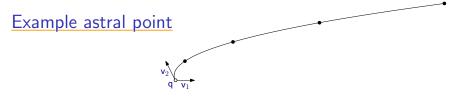
• turn out to be building blocks for all astral points



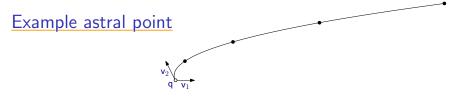
• say $\mathbf{x}_t = t^2 \mathbf{v}_1 + t \mathbf{v}_2 + \mathbf{q}$ for some $\mathbf{v}_1, \mathbf{v}_2, \mathbf{q} \in \mathbb{R}^n$



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- turns out, can write in form:

$$\overline{\boldsymbol{x}} = \underbrace{\boldsymbol{\omega} \, \boldsymbol{v}_1 + \boldsymbol{\omega} \, \boldsymbol{v}_2}_{\text{astrons}} + \boldsymbol{q}$$

- operation ++ is leftward addition:
 - similar to vector addition but not commutative
 - gives kind of "dominance" to term on left

Representing astral points

• in general: every astral point \overline{x} can be written in form

$$\overline{\mathbf{x}} = \underbrace{\omega \mathbf{v}_1 + \dots + \omega \mathbf{v}_k}_{\text{astrons}} + \underbrace{\mathbf{q}}_{\text{finite}}$$

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- astral rank = k (number of astrons in \overline{x} 's representation)
 - astral rank = $0 \Rightarrow \overline{\mathbf{x}} \in \mathbb{R}^n$
 - astral rank = $1 \Rightarrow \overline{\mathbf{x}}$ is limit of sequence along ray

Outline

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Extending a function to astral space

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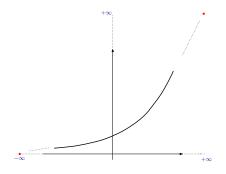
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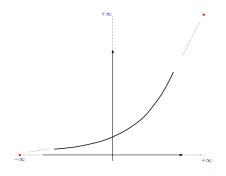
• how to define?

Example: exponential function



• say
$$f(x) = e^x$$
 for $x \in \mathbb{R}$

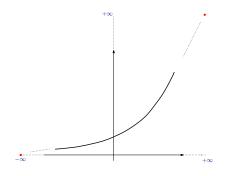
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- want to define \overline{f} = extension of f to $\overline{\mathbb{R}} = \overline{\mathbb{R}^1}$:
 - $\overline{f}(-\infty) = 0$ because: if $x_t \to -\infty$ then $f(x_t) \to 0$
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• only way to extend to $\overline{\mathbb{R}}$ continuously

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• if holds for all $\overline{\mathbf{x}} \in \overline{\mathbb{R}^n}$ then

 \overline{f} is (unique) continuous extension of f to $\overline{\mathbb{R}^n}$

• say
$$f(\mathbf{x}) = \mathbf{x} \cdot \mathbf{u}$$
 for some $\mathbf{u} \in \mathbb{R}^n$ [e.g., $f(x_1, x_2) = 2x_1 - x_2$]

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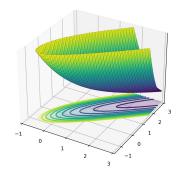
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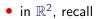
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 Rⁿ

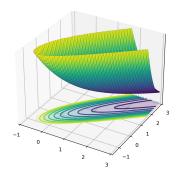
Example: Diagonal valley





$$f(x_1, x_2) = e^{-x_1} + (x_2 - x_1)^2$$



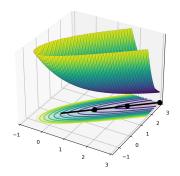




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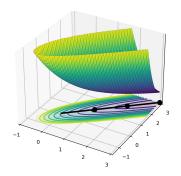




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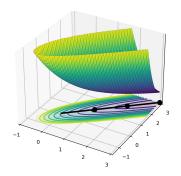




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- since continuous, f also minimized by any sequence $\mathbf{x}'_t \rightarrow \omega \mathbf{v}$

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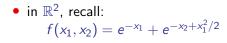
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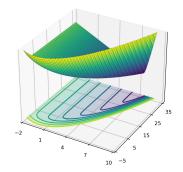
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there exists sequence $x_t \rightarrow \overline{x}$ minimizing f

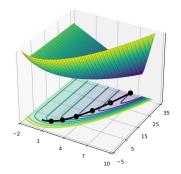




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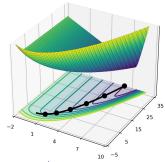
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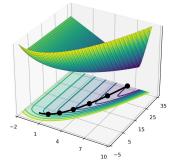


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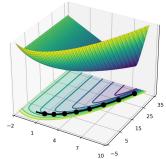
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- \overline{f} not continuous at \overline{x} : e.g.:

 $\begin{aligned} \mathbf{x}'_t &= (t, \frac{1}{2}t^2) = \frac{1}{2}t^2\mathbf{e}_2 + t\mathbf{e}_1 \rightarrow \overline{\mathbf{x}} \\ \text{but } f(\mathbf{x}'_t) \rightarrow 1 \neq \overline{f}(\overline{\mathbf{x}}) \end{aligned}$



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reveals structure and regularity not otherwise apparent

Convergence and astral continuity (cont.)

- can use to prove convergence of standard iterative methods applied to various ML/statistical settings
 - e.g.: gradient descent, coordinate descent, steepest descent
 - e.g.: logistic regression, boosting, maximum likelihood (which all have continuous extensions)

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- can use to prove convergence of standard iterative methods applied to various ML/statistical settings
 - e.g.: gradient descent, coordinate descent, steepest descent
 - e.g.: logistic regression, boosting, maximum likelihood (which all have continuous extensions)
- don't require finite minimizer
- algorithms operate in \mathbb{R}^n , but use astral methods in proofs
 - rely on astral continuity properties (without which results do not hold, in general)

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- e.g. AdaBoost minimizes exponential loss
 - finds solution with large-margin property, implying generalization
 - really an astral property of minimizer at infinity (namely, of first astron in representation)

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- far more not covered
 - details at: aka.ms/astral [or arxiv.org/abs/2205.03260] (will eventually be published as a book)