

The long path to \sqrt{d} monotonicity testers

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Thanks to my teachers



Manindra Agrawal



Bernard Chazelle



Mike Saks



Tamara Kolda



Ali Pinar

Thanks to my collaborators



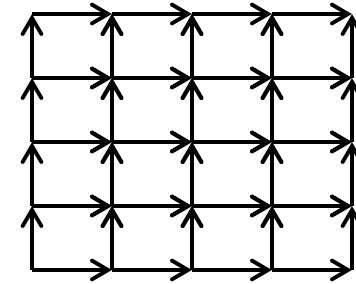
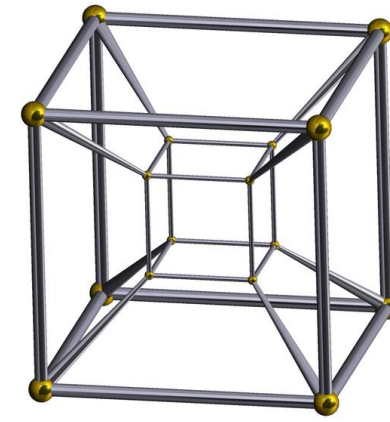
Hadley Black



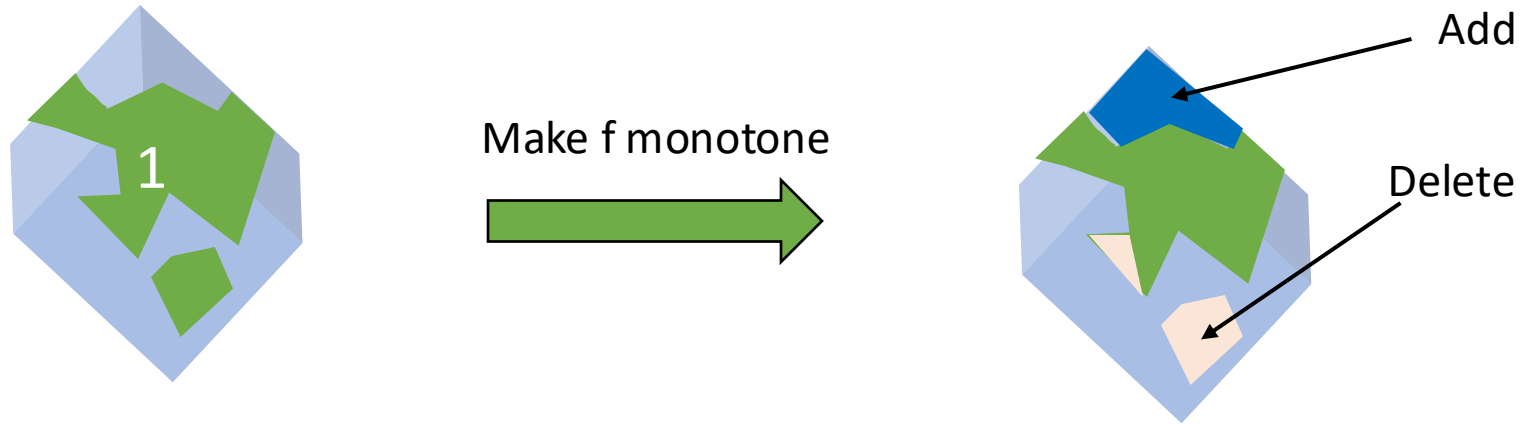
Deeparnab Chakrabarty

Monotone hypergrid functions

- $f: D \rightarrow \{0,1\}$
- **Hypergrid:** $[n]^d$
(includes line, tesseract, etc.)
- **$n = 2$, Boolean Hypercube:** $\{0,1\}^d$
- $x < y$ iff $x_i \leq y_i$ for all i
- f is monotone: if $x < y$, $f(x) \leq f(y)$
- Equivalently, think of f as indicator for set

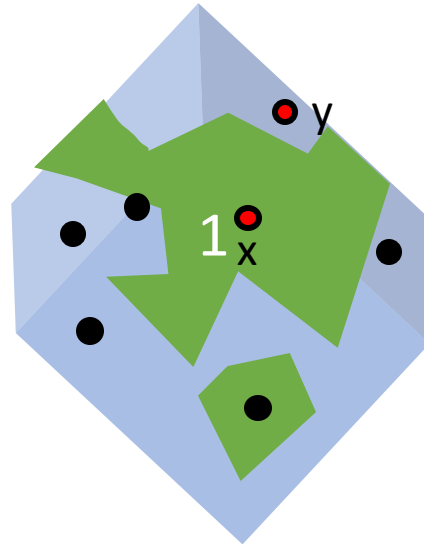


The distance to monotonicity



- Distance to monotonicity = (min changes to make set monotone)/ n^d
- ϵ_f in $[0,1)$
 - Amen
- $\epsilon_f = \min_{g \text{ monotone}} |f - g|_0 / n^d$

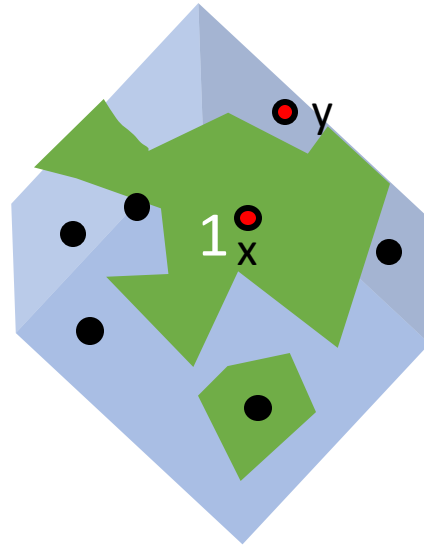
Monotonicity testing



$$\begin{aligned}x &< y \\ f(x) &= 1 \\ f(y) &= 0\end{aligned}$$

- [\[Bshouty-Tamon96, Lange-Vasilyan23\]](#) Learning monotone functions needs $> \exp(\sqrt{d})$
- Given ϵ and query access to f :
 - Distinguish monotone ($\epsilon_f = 0$) vs far from monotone ($\epsilon_f > \epsilon$) whp
- One-sided tester: given f such that $\epsilon_f > \epsilon$, discover a “violation” whp
- Non-adaptive: all queries are made in advance

Big question



$$\begin{aligned}x &< y \\ f(x) &= 1 \\ f(y) &= 0\end{aligned}$$

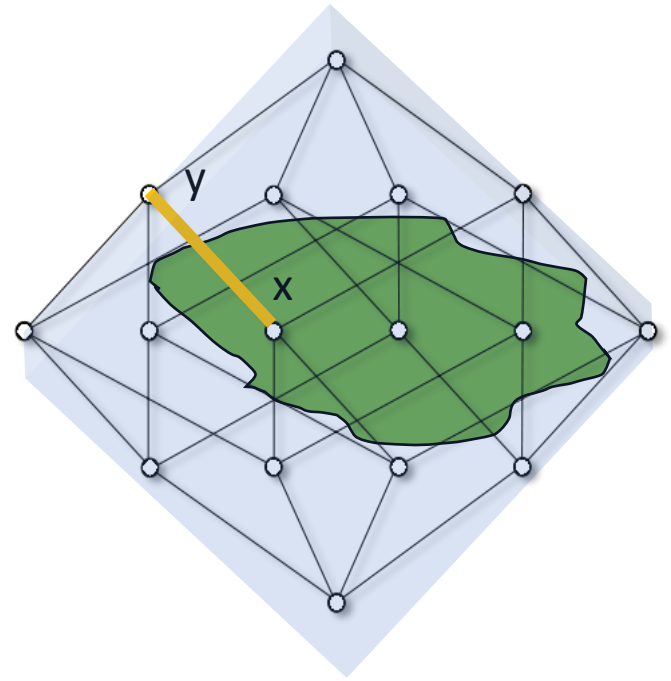
- [Goldreich-Goldwasser-Lehman-Ron-Samorodnitsky 00, Raskhonikova 99, Dodis-Goldreich-Lehman-Raskhodnikova-Ron-Samorodnitsky 99]

What is the (non-adaptive) complexity of monotonicity testing?

- Hypergrid domain, Boolean range
- > 20 papers and two decades of history

The Edge Tester

- [GGLRS00, DGGLRS00]
- Sample an edge of hypercube (x, y) u.a.r
- Query $f(x), f(y)$
- Reject if violation



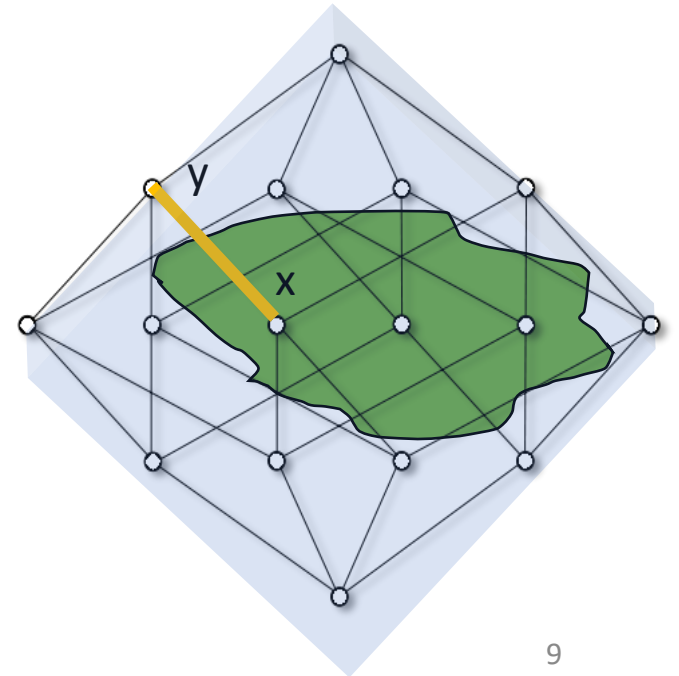
Theorem: the probability of finding violation is $> \epsilon_f / d$

So if $\epsilon_f > \epsilon$, $O(d/\epsilon)$ samples suffice to detect violation whp

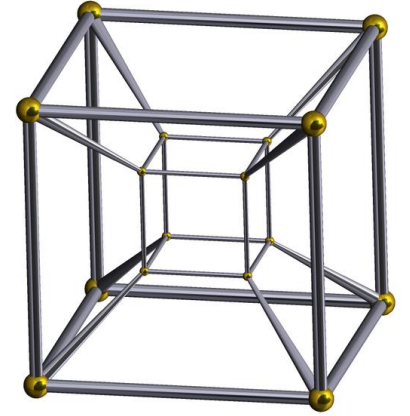
- [DGGLRS00] $O(d \log^2 d / \epsilon)$ monotonicity tester for hypergrids

Can we beat d ?

- [Blais-Brody-Matulef 12] $\Omega(d)$ lower bound when range is real
- [Chakrabarty-S 13a, Chakrabarty-S 13b]
Hypergrid domain, arbitrary range, the complexity is $\Theta(d \log n / \epsilon)$
- Non-adaptive, one-sided upper bound. Adaptive, two-sided lower bound
 - Finis. End of story
 - Optimal tester for hypercube is edge tester
- **Does Boolean range make complexity lower?**
 - [Fischer-Lehman-Newman-Raskhodnikova-Rubinfeld 02]
 $\Omega(\sqrt{d})$ one-sided lower bound
 - **Can one get $o(d)$ complexities?**



The mystery of root d , for hypercubes



- [Chakrabarty-S 13] $d^{7/8}$ query tester
- [Chen-Servedio-Tan 14] $d^{5/6}$ query tester

- [Khot-Minzer-Safra 15] \sqrt{d} query tester
 - Essentially, same tester as before. All in the analysis

- [Chen-De-Servedio-Tan 15, Chen-Waingarten-Xie 17] $\Omega(\sqrt{d})$ two-sided non-adaptive lower bound

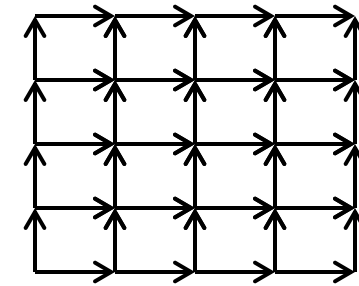
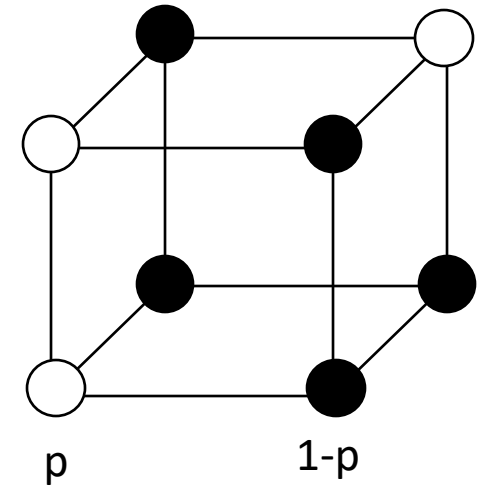
- The theory of **Directed Isoperimetric Theorems**
 - Seemingly hypercube specific; can they generalize?

Getting to root d , for hypergrids

- [DGGLRS00] $O(d \log^2 d / \epsilon)$ monotonicity tester for hypergrid
- [Berman-Raskhodnikova-Yaroslavtsev 17] $O(d \log d)$
- [Black-Chakrabarty-S 18, BCS 20] $d^{5/6}$ query tester
- [Braverman-Khot-Kindler-Minzer 23, BCS 23] $\text{poly}(n) \sqrt{d}$ query tester
- [BCS 24] $d^{1/2 + o(1)}$ query tester
 - All results have different testers!

The generality of hypergrids

- **Hypergrid:** $[n]^d$
Results for uniform distribution automatically translate to any product distribution
 - Otherwise uniform distribution on hypercube looks like special case
- Can even set $n = \infty$, so domain is \mathbb{R}^d
 - Monotonicity testing for measurable functions over product distributions



n-1,n-1, ...



00...

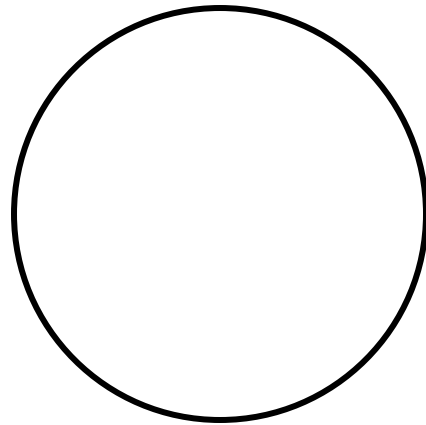
Why did the baby grid not
get any sugar?

Because it would become a hypergrid.



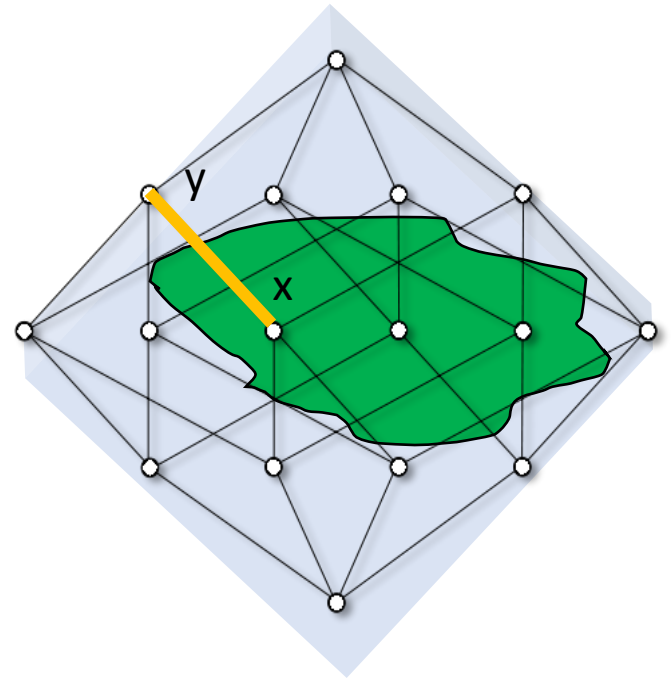
Directed Isoperimetry

Surfaces, volumes, and why $o(d)$ is possible



The Edge Tester

- [GGLRS00, DGLRRS99]
- Sample an edge of hypercube (x, y) u.a.r
- Query $f(x), f(y)$
- Reject if violation



Theorem: the probability of finding violation is $> \varepsilon_f / d$

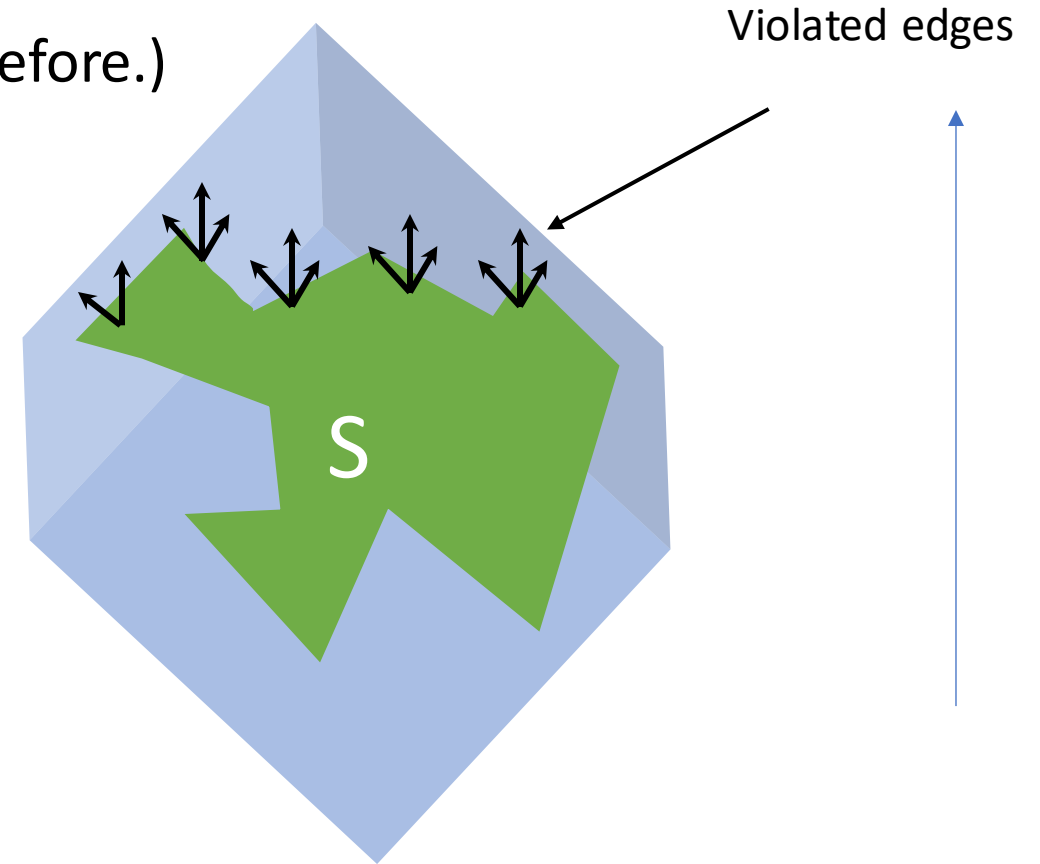
A Geometric Interpretation

Abusing notation, S is the set of 1s. (We still use ε_f as before.)

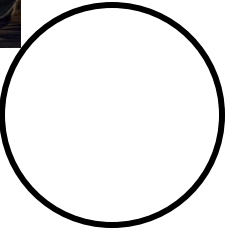
Theorem: The number of **violated** hypercube edges is $\Omega(\varepsilon_f \cdot 2^d)$

$$\text{Inf}_f^+ = \frac{|\vec{E}(S, S^c)|}{2^d}$$

Theorem: $\text{Inf}_f^+ = \Omega(\varepsilon_f)$



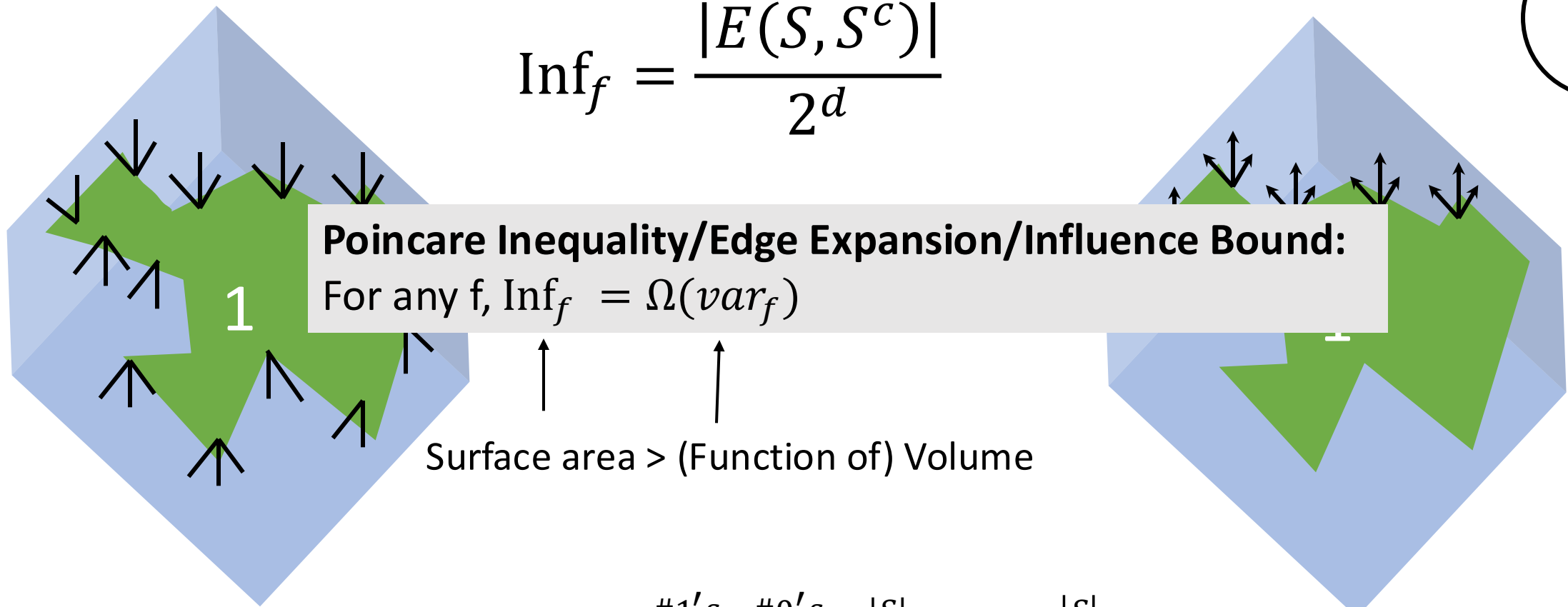
A far from monotone function



Undirected Isoperimetry: Poincare

$$\text{Inf}_f = \frac{|E(S, S^c)|}{2^d}$$

Poincare Inequality/Edge Expansion/Influence Bound:
For any f , $\text{Inf}_f = \Omega(\text{var}_f)$



Surface area > (Function of) Volume

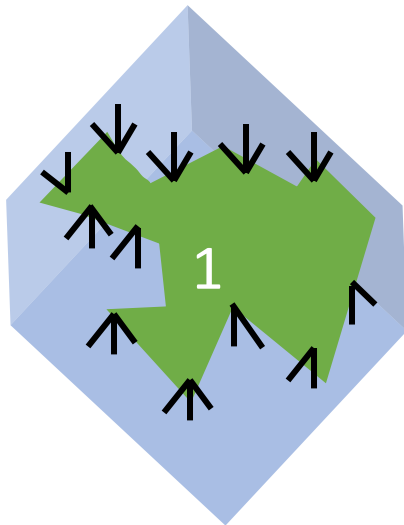
Influential Edges

$$\text{var}_f = \frac{\#1's}{2^d} \cdot \frac{\#0's}{2^d} = \frac{|S|}{2^d} \cdot \left(1 - \frac{|S|}{2^d}\right)$$

GGLRS = Directed Poincare

Undirected Hypercube

- Poincare: $\text{Inf}_f = \Omega(\text{var}_f)$

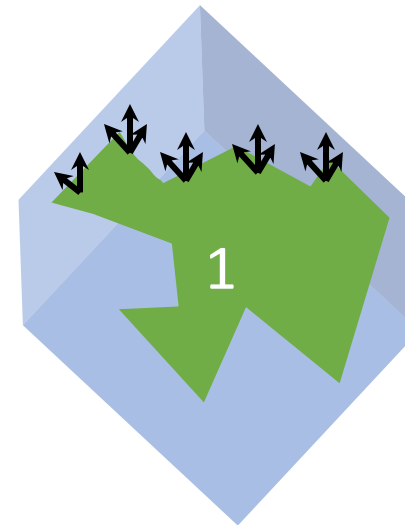


Directed Hypercube

- GGLRS: $\text{Inf}_f^+ = \Omega(\varepsilon_f)$

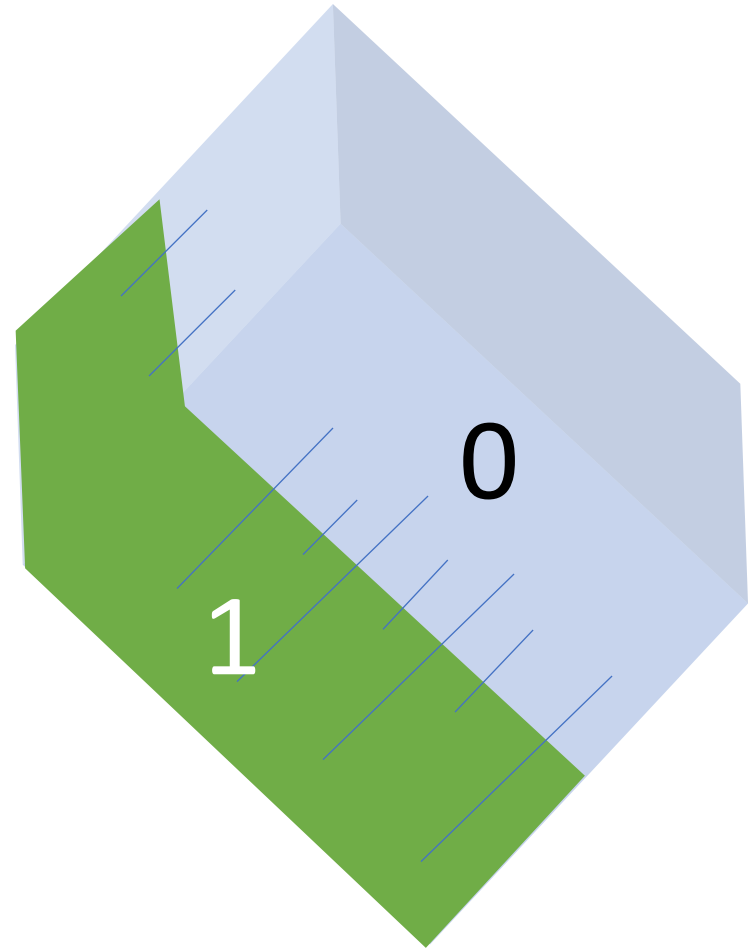
Directed expansion/
surface area

Directed volume...?



(Directed) Poincare is tight

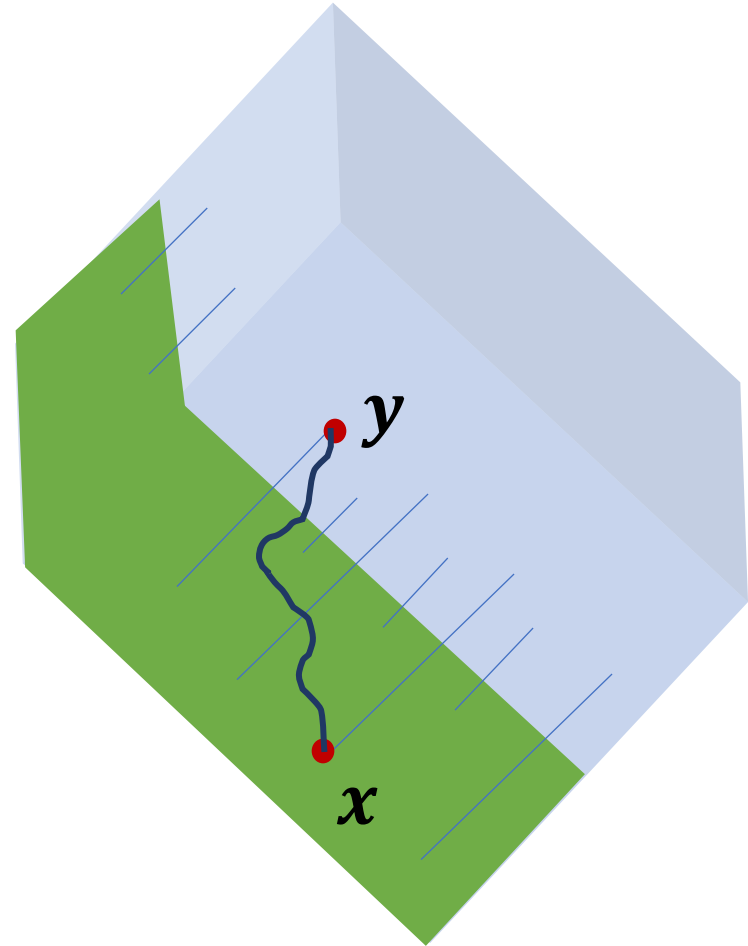
- Distance = $\frac{1}{2}$
- Number of viol edges = 2^{d-1}
 - Total edges = $d \cdot 2^{d-1}$
- Edge tester needs $\Omega(d)$ queries to catch violation



Bypassing the (anti)-Dictator

- Sample x
- Walk “up” to get y
- Query $f(x)$, $f(y)$ and Test.

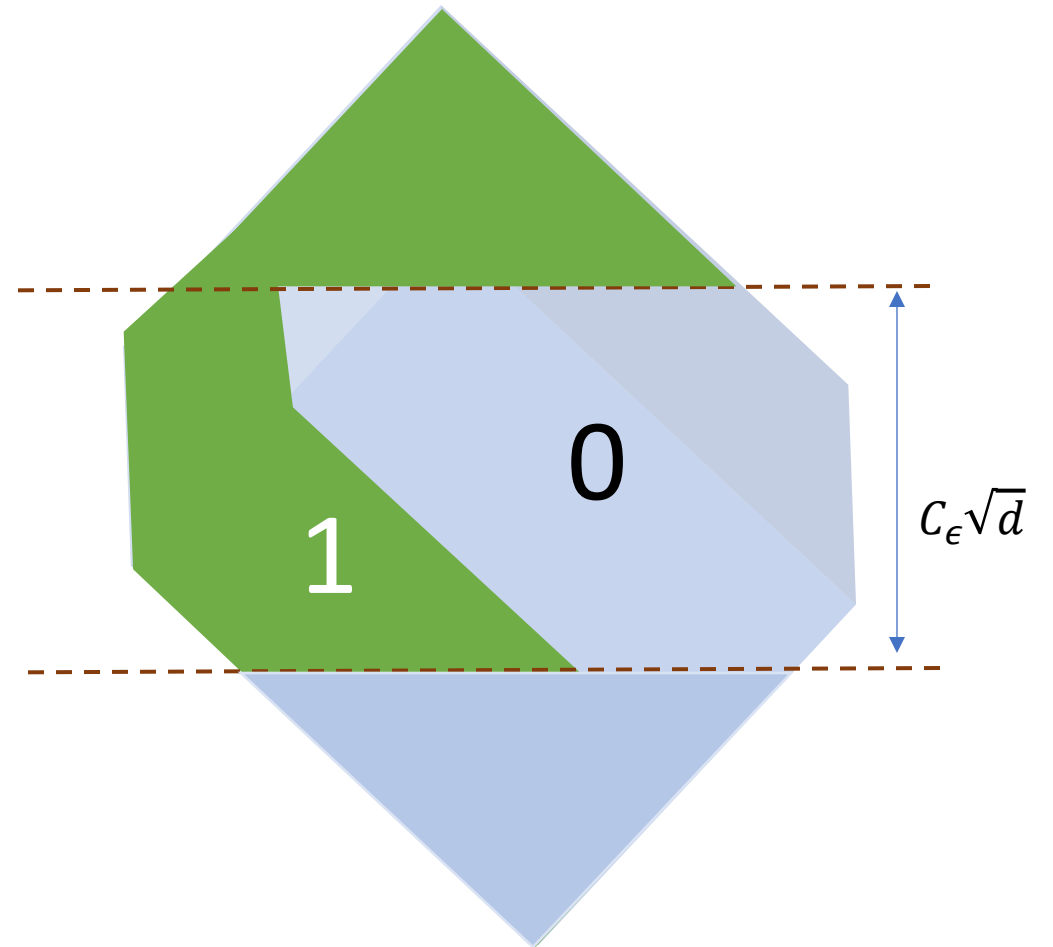
How long should we walk?



Square Root of Dimension

- Sample x
- Walk “up” to get y
- Query $f(x)$, $f(y)$ and Test.

Can't walk more than $\approx \sqrt{d}$



Analysis for the (capped) Anti-Dic

The root to root d is taking a longer root.

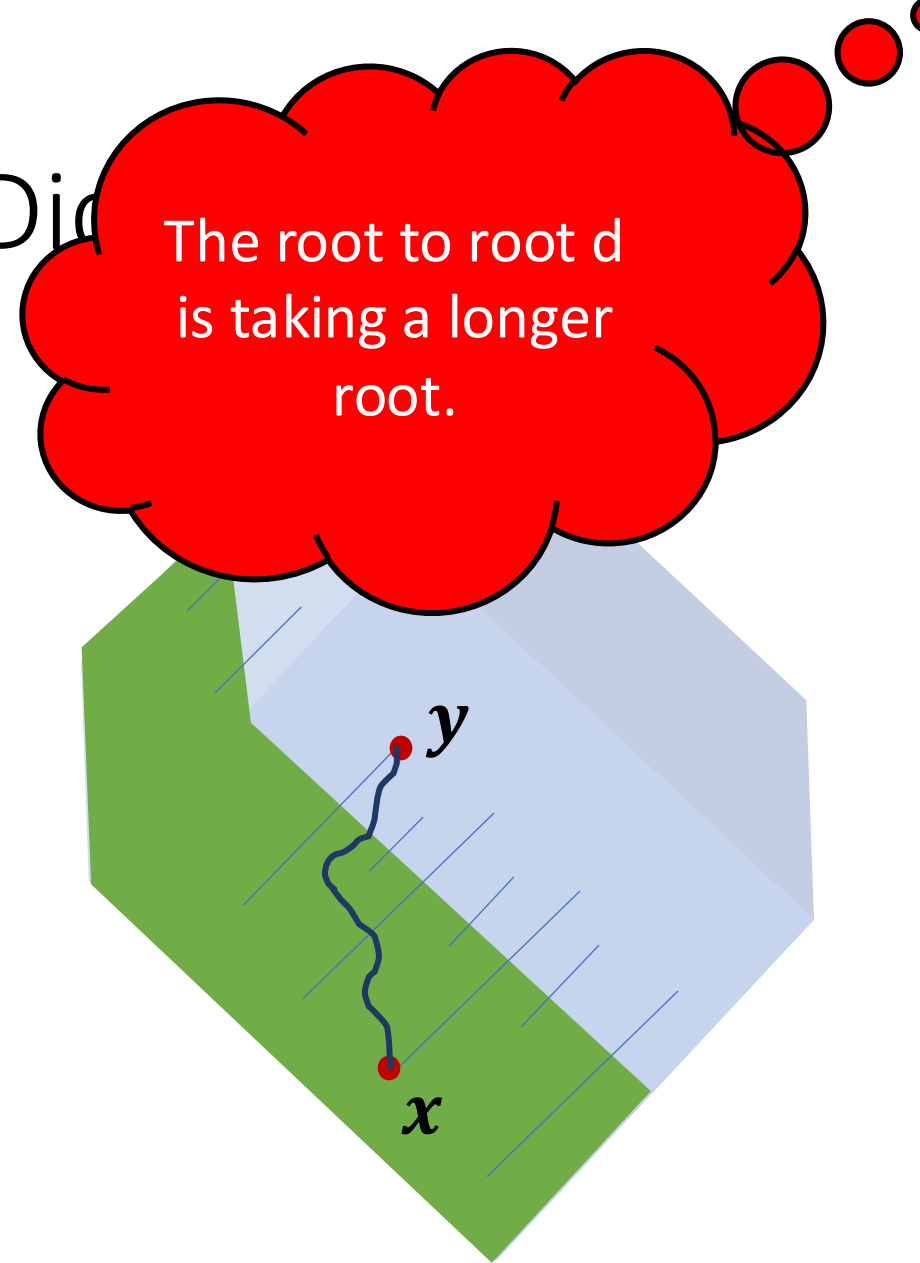
- Sample x
- Walk “up” to get y
- Query $f(x), f(y)$ and Test.

- $\text{Prob}[x \text{ is green}] \approx 1/2$

- $\text{Prob}[\text{crossing}] \approx \sqrt{d} \cdot \frac{1}{d} \approx \frac{1}{\sqrt{d}}$

Number of steps

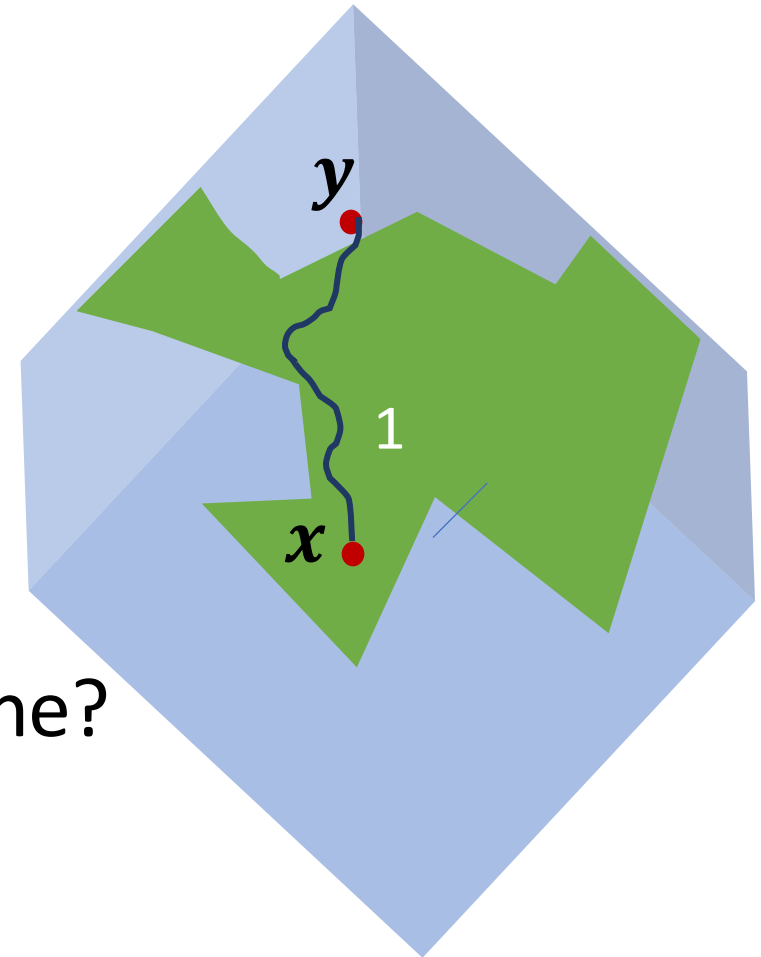
Chance of crossing in each step



How to analyze the “path tester”

Need structural insight
“far from monotone” functions/sets

How to “escape” S that is far from monotone?



Directed Isoperimetric Theorems

Undirected Hypercube

- Poincare: $\text{Inf}_f = \Omega(\text{var}_f)$
- [Margulis74]:
 $\text{Inf}_f \cdot \Gamma_f = \Omega(\text{var}_f^2)$
- [Talagrand 92]:
 $\mathbb{E}[\sqrt{\text{Inf}(x)}] = \Omega(\text{var}_f)$

Directed Hypercube

- [DGLRRS00, GGLRS00]:
 $\text{Inf}_f^+ = \Omega(\varepsilon_f)$
- [Chakrabarty-S 13]:
 $\text{Inf}_f^+ \cdot \Gamma_f^+ = \Omega(\varepsilon_f^2)$
- [Khot-Minzer-Safra 15]:
 $\mathbb{E}[\sqrt{\text{Inf}^+(x)}] = \Omega(\varepsilon_f)$

Query

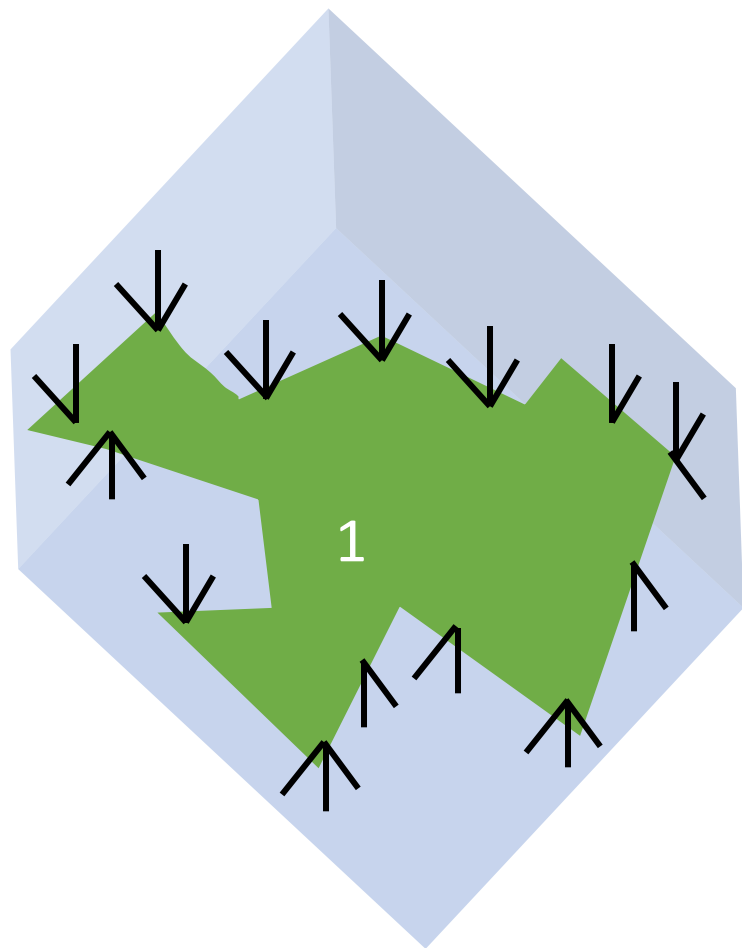
d

$d^{5/6}$

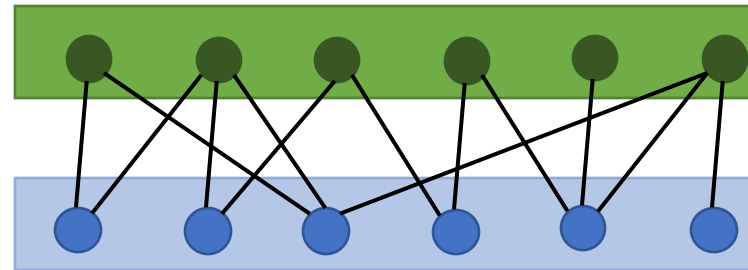
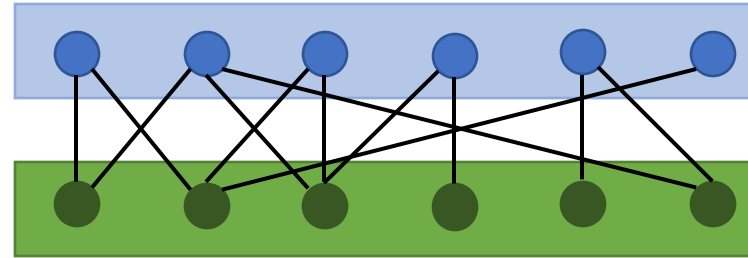
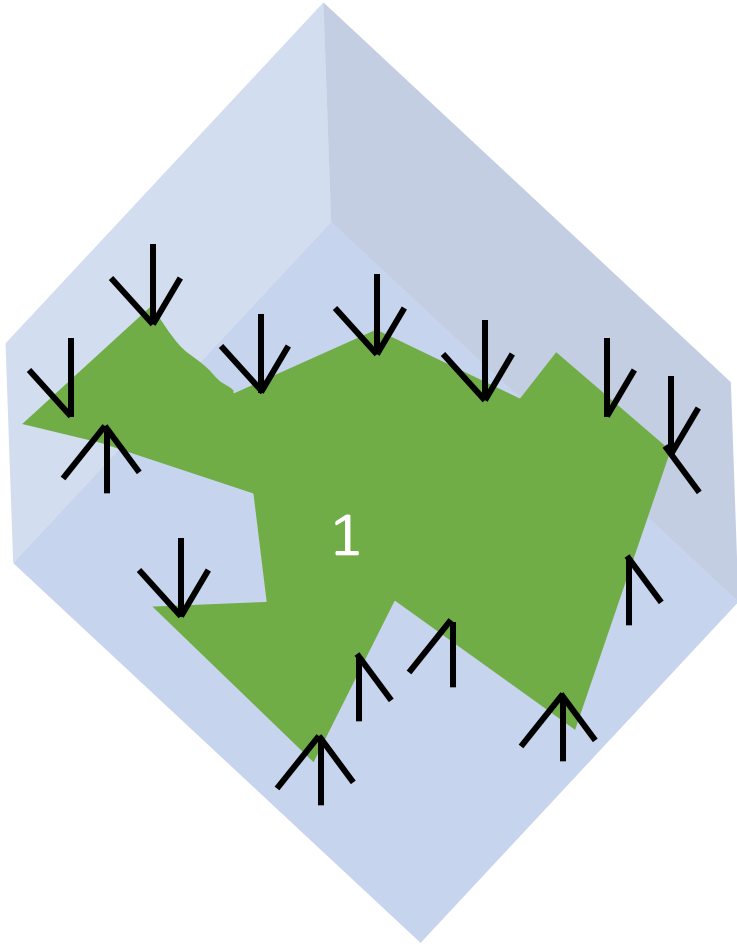
\sqrt{d}

How to measure the
boundary?

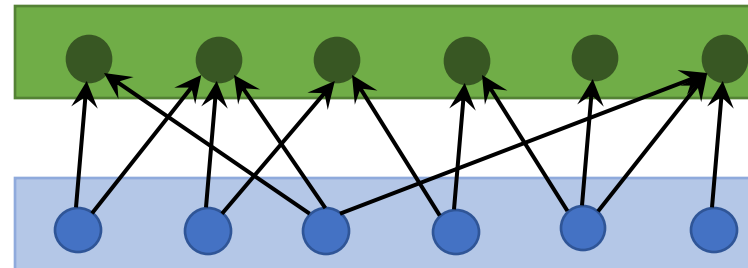
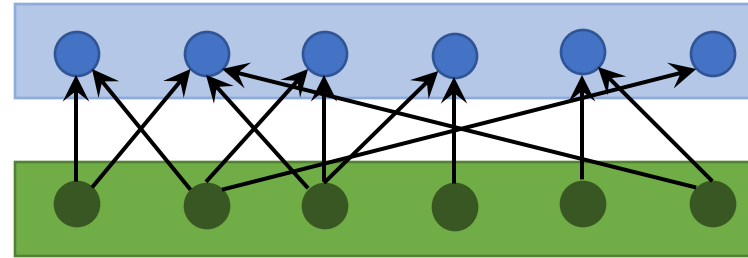
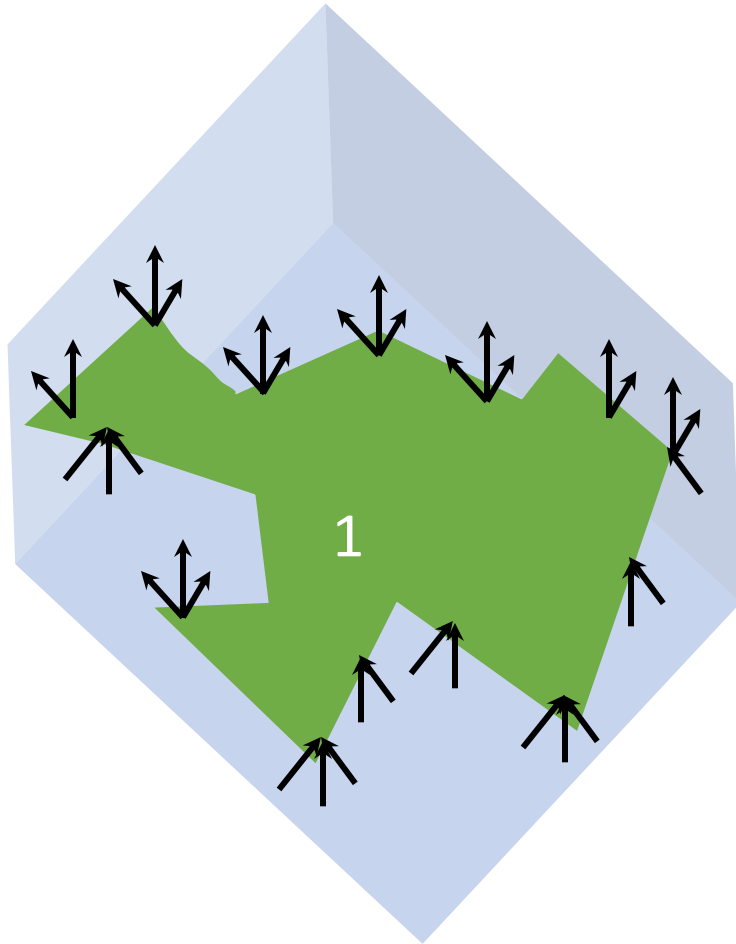
Boundary as bipartite graph



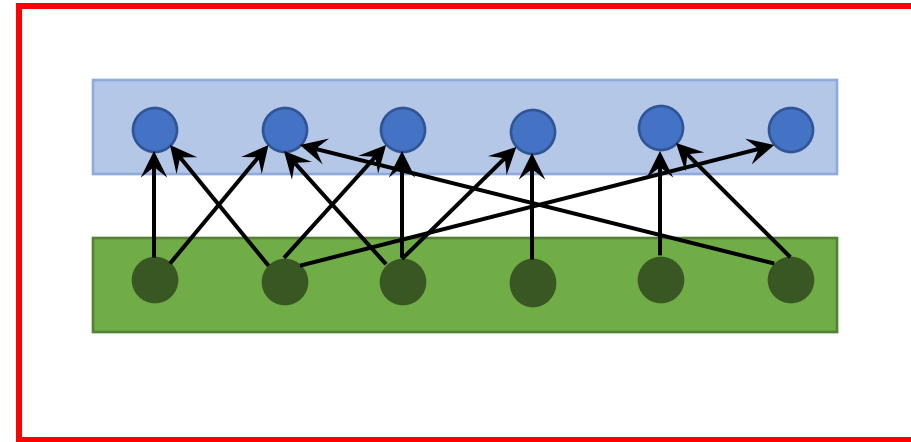
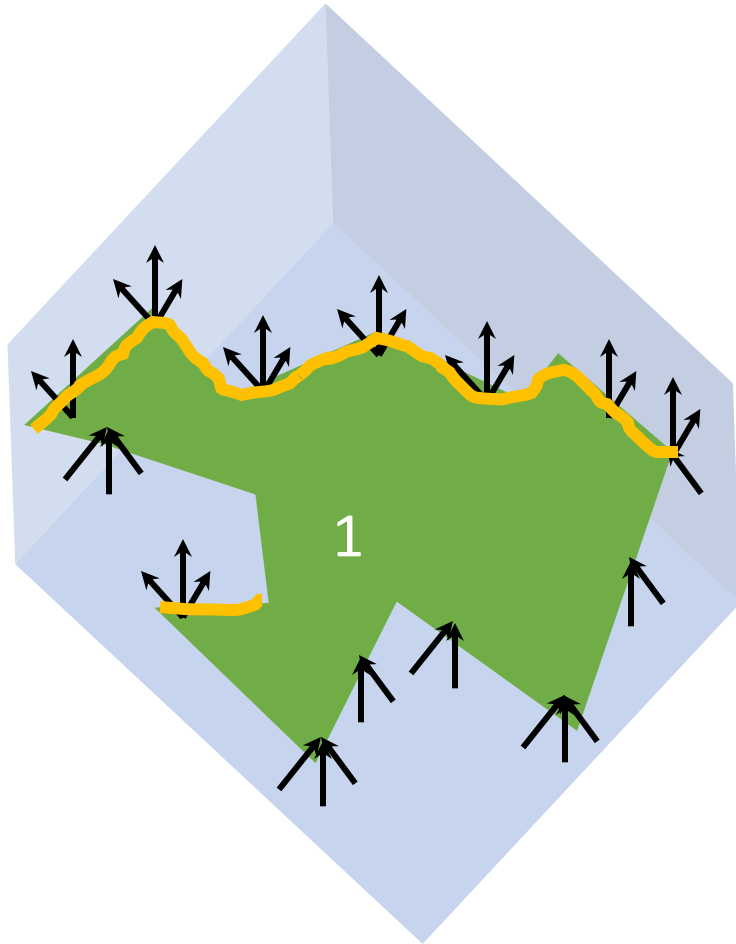
Boundary as bipartite graph



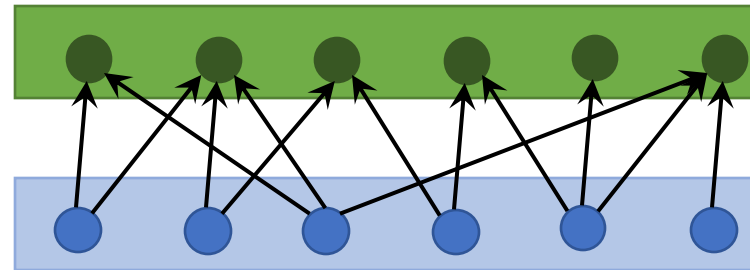
Directed boundary



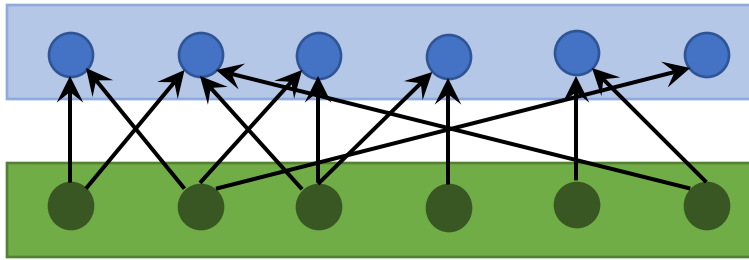
Directed boundary



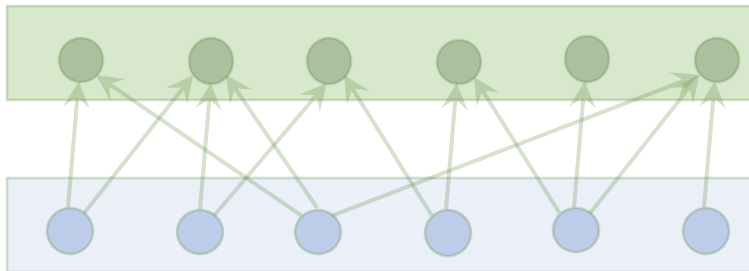
G^+
Violating Edges



Directed Influence



$$\text{Inf}^+(x) = \text{out-degree of } x \text{ in directed } G^+$$

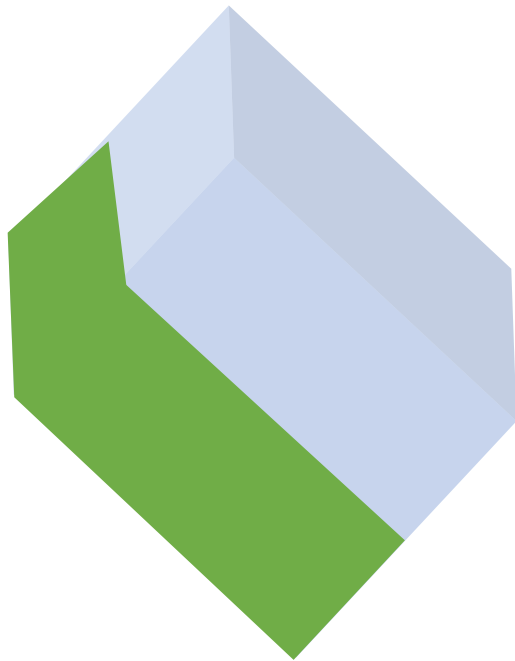


$$\text{Exp}_{x:\mathbf{1}}[\text{Inf}^+(x)] = \frac{E^+(S, S^c)}{2^d} = I_f^+$$

$$\text{Exp}_{x:\mathbf{1}}[\text{Inf}(x)] = I_f$$

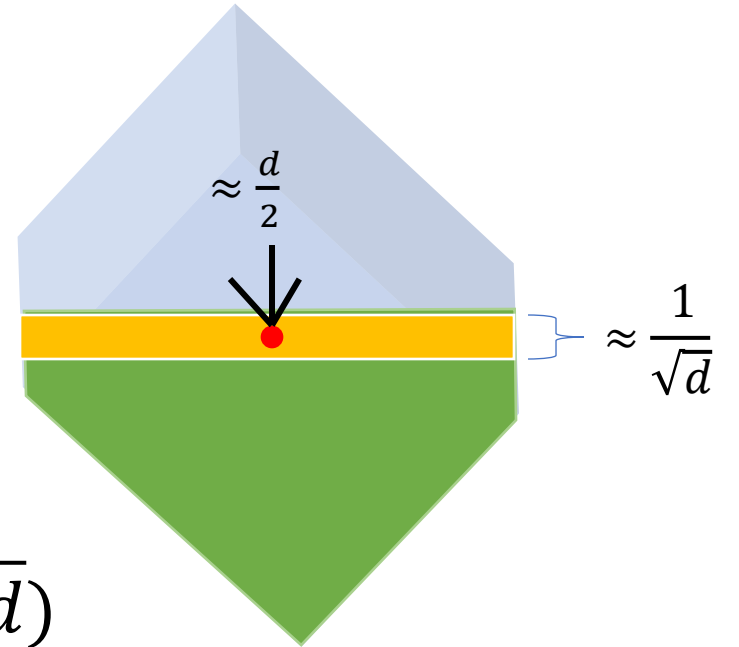
A careful look into influence

Poincare: $I_f := \text{Exp}_{x:\mathbf{1}}[\text{Inf}(x)] = \Omega(\text{var}_f)$



$$I_f = \Theta(1)$$

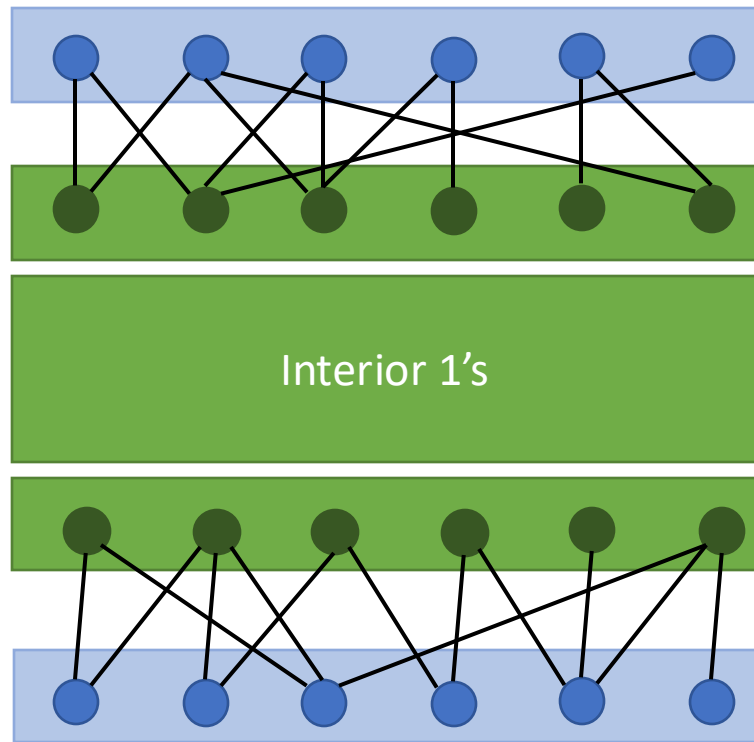
anti-dictator



$$I_f = \Theta(\sqrt{d})$$

anti-majority

Consider the Vertex Boundary

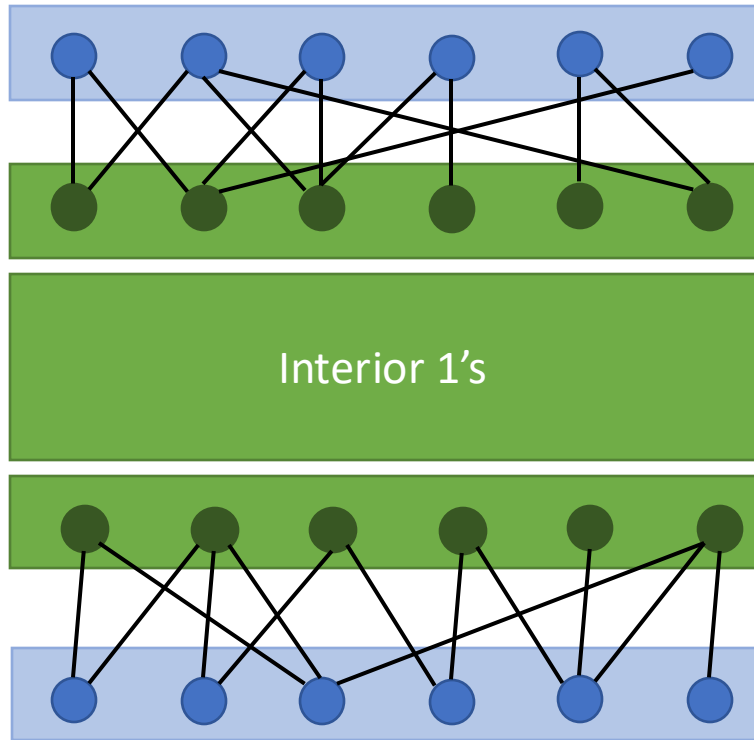


$$I_f := \text{Exp}_{x:1}[\text{Inf}(x)]$$

"Edge boundary"

"Vertex Boundary"

Consider the Vertex Boundary



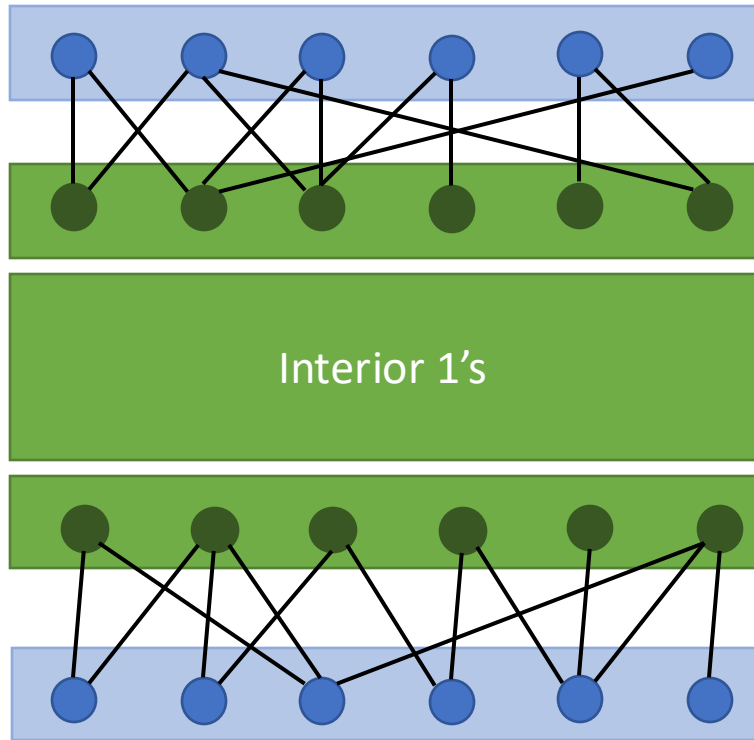
$$I_f := \text{Exp}_{x:\mathbf{1}}[\text{Inf}(x)]$$

"Edge boundary"

"Vertex Boundary"

$$\frac{1}{2d} \cdot \{x: \mathbf{1} \text{ such that it has at least one influential edge incident on it}\}$$

Consider the Vertex Boundary



$$I_f := \text{Exp}_{x:1} [\text{Inf}(x)]$$

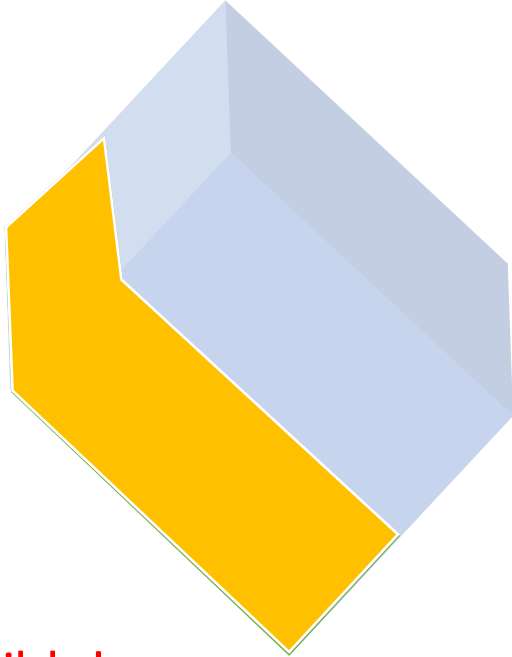
“Edge boundary”

“Vertex Boundary”

$$\frac{1}{2d} \cdot \{x: \mathbf{1} \text{ such that it has at least one influential edge incident on it}\}$$

$$\text{Exp}_{x:1} [\mathbb{I}\{\text{Inf}(x) > 0\}]$$

Vertex Boundaries



Lowest possible!
(By Poincare)

anti-dictator

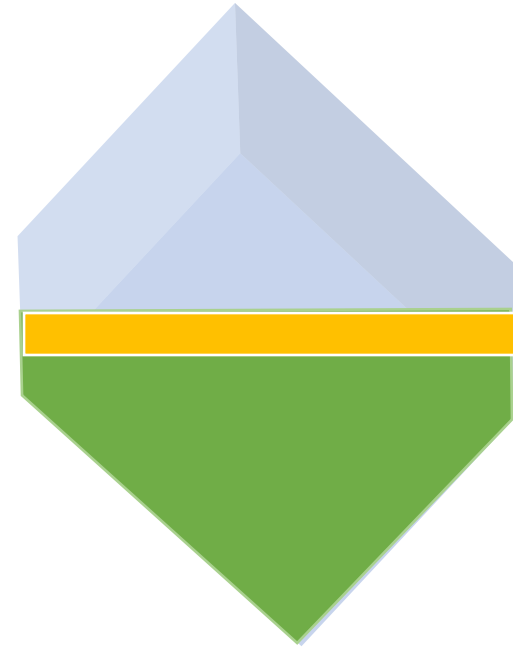
Small

Edge boundary = $\Theta(1)$

Every vertex in the boundary

Large

Vertex boundary = $\Theta(1)$



anti-majority

Large

Edge boundary = $\Theta(\sqrt{d})$

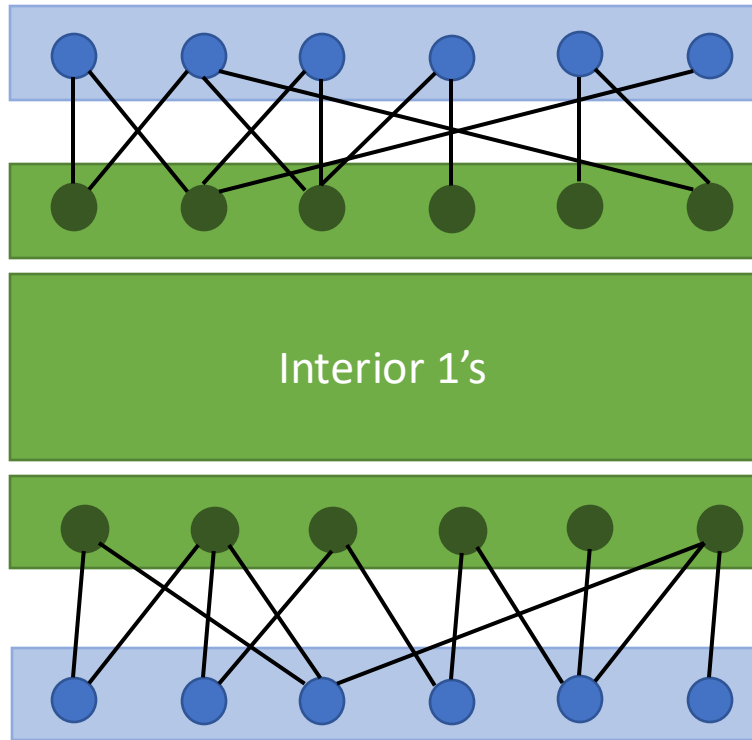
Only $1/\sqrt{d}$ fraction in boundary

Small

Vertex boundary = $\Theta(1/\sqrt{d})$

Lowest possible!
(By Harper)

Margulis



$$I_f := \text{Exp}_{x:1}[\text{Inf}(x)] \quad \text{"Edge boundary"}$$

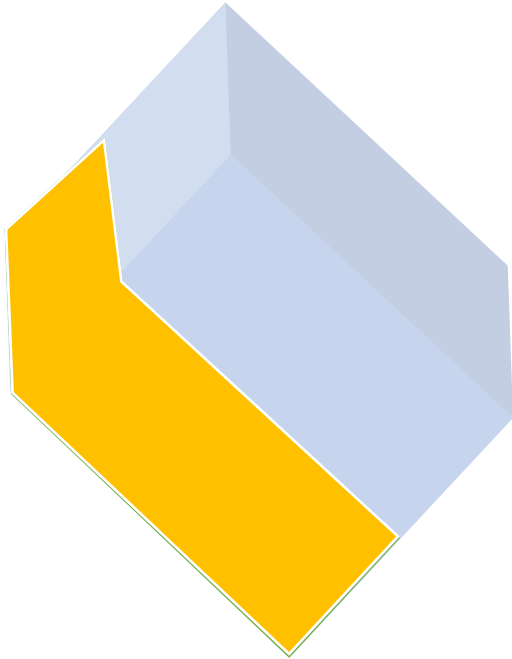
$$\Gamma_f := \text{Exp}_{x:1}[\mathbb{I}\{\text{Inf}(x) > 0\}] \quad \text{"Vertex Boundary"}$$

Margulis 1974:

$$I_f \cdot \Gamma_f = \Omega(\text{var}_f^2)$$

Both cannot be simultaneously small!

Vertex Boundaries



anti-dictator

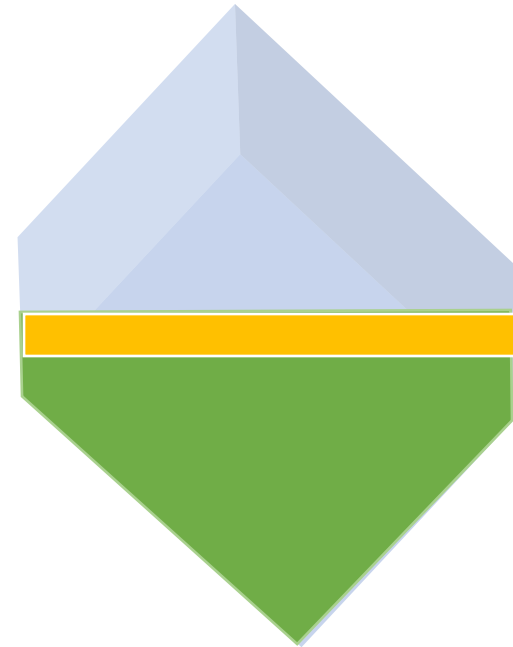
Small

$$\text{Exp}_{x:1}[\text{Inf}(x)] = 1$$

Every vertex in the boundary

Large

$$\text{Exp}_{x:1}[\mathbb{I}\{\text{Inf}(x) > 0\}] = 1$$



anti-majority

Large

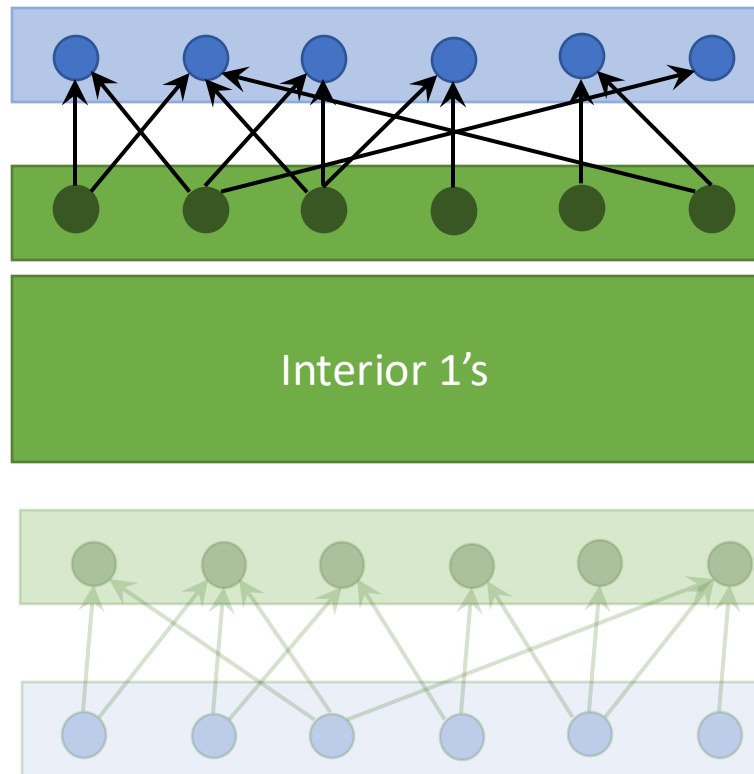
$$\text{Exp}_{x:1}[\text{Inf}(x)] = \Theta(\sqrt{d})$$

Only $1/\sqrt{d}$ fraction in boundary

Small

$$\text{Exp}_{x:1}[\mathbb{I}\{\text{Inf}(x) > 0\}] = \Theta(1/\sqrt{d})$$

Directed Margulis



$$\Gamma_f^+ := \text{Exp}_{x:\mathbf{1}}[\text{Inf}^+(x)] \quad \text{“Directed Edge boundary”}$$

$$\Gamma_f^+ := \text{Exp}_{x:\mathbf{1}}[\mathbb{I}\{\text{Inf}^+(x) > 0\}] \quad \text{“Dir. Vrtx. boundary”}$$

[Chakrabarty-S 13]:

$$\Gamma_f^+ \cdot \Gamma_f^+ = \Omega(\varepsilon_f^2)$$

Analysis for the Anti-Dictator

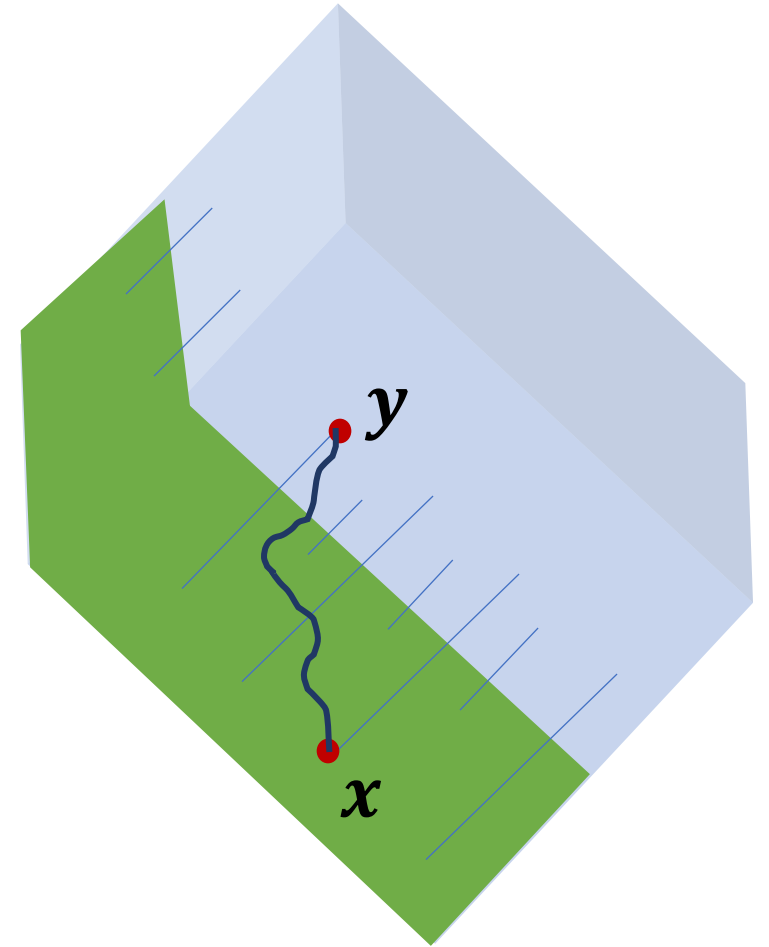
By directed Margulis, if $I_f^+ = O(1)$,
constant fraction of vertices on
directed boundary.

Analysis like this should work?

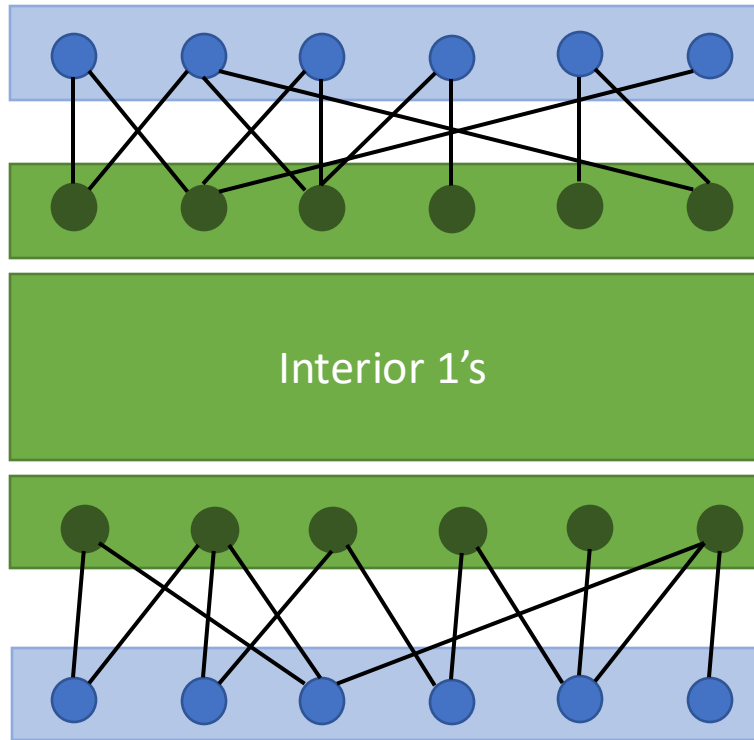
- $\text{Prob}[x \text{ is green}] \approx 1/2$
- $\text{Prob}[\text{crossing}] \approx \underbrace{\sqrt{d}}_{\text{Number of steps}} \cdot \underbrace{\frac{1}{d}}_{\text{Chance of crossing in each step}} \approx \frac{1}{\sqrt{d}}$

Number of steps

Chance of crossing in
each step



The Talagrand theorem



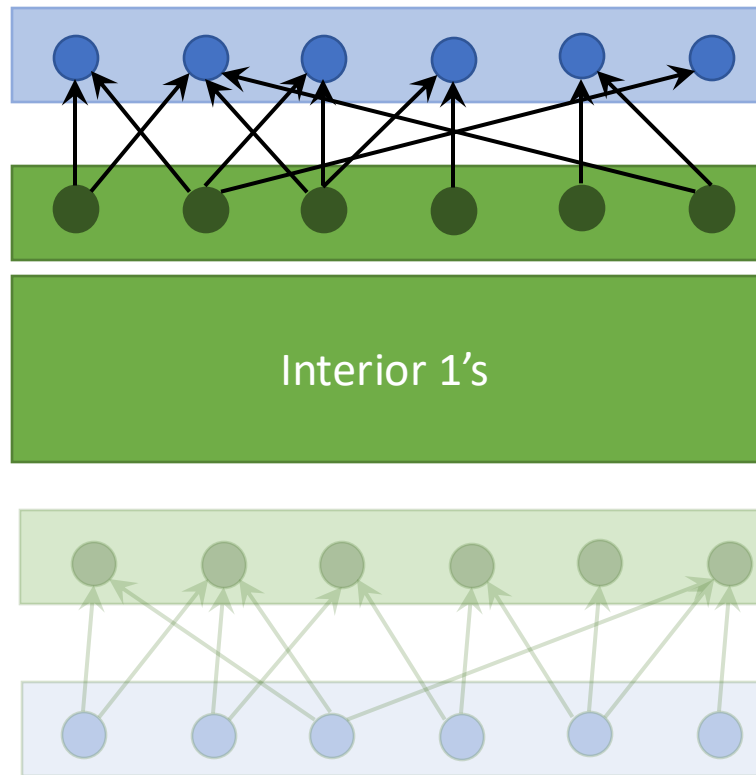
Talagrand 1993: *"Notion of Surface Area"*

$$\text{Tal}_f := \text{Exp}_{x:1} [\sqrt{\text{Inf}(x)}]$$

$$\text{Tal}_f = \Omega(\text{var}_f)$$

Implies Margulis (by Cauchy-Schwartz),
which also implies Poincare

Khot-Minzer-Safra



$$\begin{aligned}\text{Tal}_f^+ &:= \text{Exp}_{x:\mathbf{1}}[\sqrt{\text{Inf}^+(x)}] \\ &= \Omega(\varepsilon_f)\end{aligned}$$

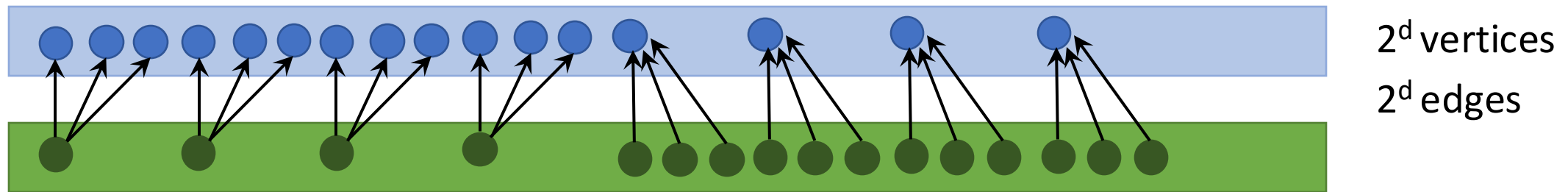
Actually, for any edge bicoloring ψ ,

$$\text{Tal}_f^+ := \min_{\psi} \mathbb{E}_x[\sqrt{\text{Inf}_{\psi}^+(x)}]$$

KMS lost a log factor, which [\[Pallavoor-Raskhodnikova-Waingarten 22\]](#) removed

Robustness

$$\text{Tal}_f^+ := \text{Exp}_{x:1} \left[\sqrt{\text{Inf}^+(x)} \right] = \Omega(1) \quad \text{Tal}_f^+ := \text{Exp}_{x:0} \left[\sqrt{\text{Inf}^+(x)} \right] = \Omega(1)$$

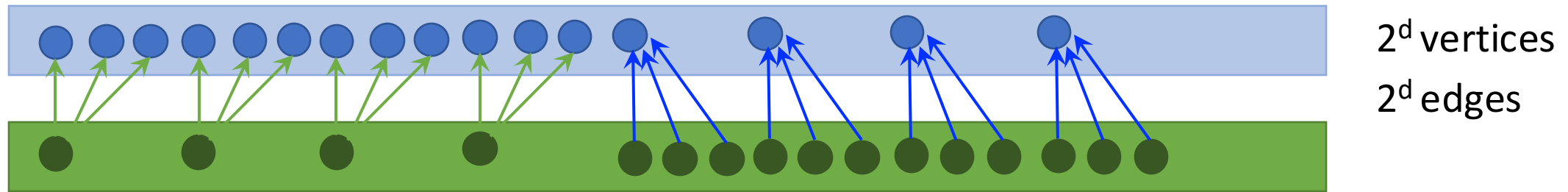


Adversary ψ assigns each edge to 0 or 1, to minimize Talagrand “surface area”

$$\text{Tal}_f^+ := \min_{\psi} \mathbb{E}_x \left[\sqrt{\text{Inf}_{\psi}^+(x)} \right]$$

Robustness

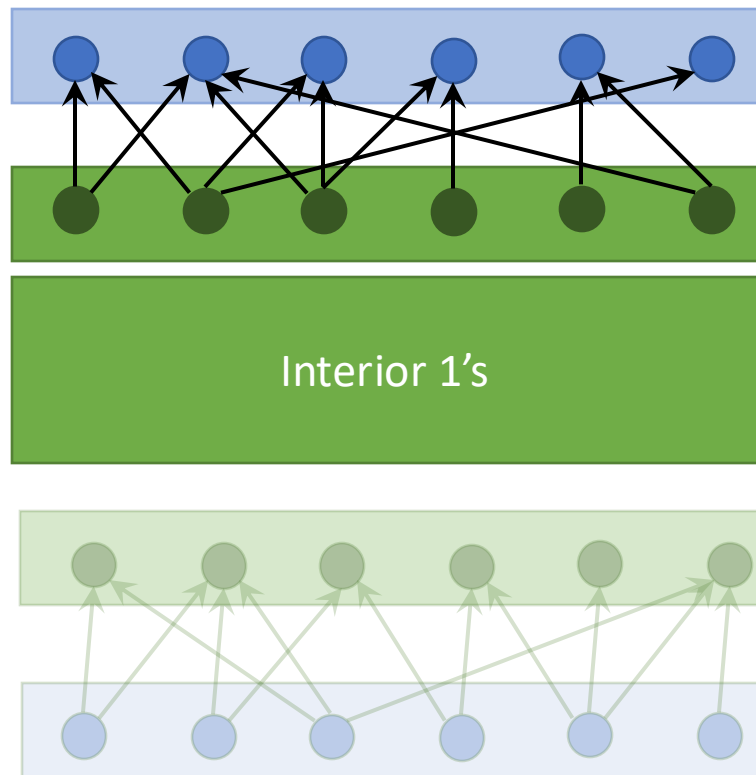
$$\text{Tal}_f^+ := \text{Exp}_{x:1} \left[\sqrt{\text{Inf}^+(x)} \right] = \Omega(1) \quad \text{Tal}_f^+ := \text{Exp}_{x:0} \left[\sqrt{\text{Inf}^+(x)} \right] = \Omega(1)$$



Adversary ψ assigns each edge to 0 or 1, to minimize Talagrand “surface area”

$$\text{Tal}_f^+ := \min_{\psi} \mathbb{E}_x \left[\sqrt{\text{Inf}_{\psi}^+(x)} \right] = \frac{2^d}{d} \cdot \sqrt{d} = O(1/\sqrt{d})$$

Khot-Minzer-Safra



Actually, for any edge bicoloring ψ ,

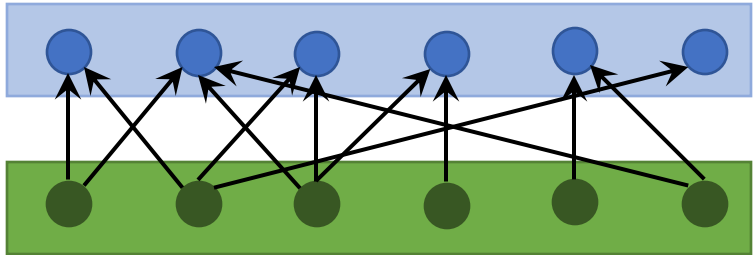
$$\text{Tal}_f^+ := \min_{\psi} \mathbb{E}_x \left[\sqrt{\text{Inf}_{\psi}^+(x)} \right] = \Omega(\varepsilon_f)$$

KMS lost a log factor, which [\[Pallavoor-Raskhodnikova-Waingarten 22\]](#) removed

But what does it mean?

$$\text{Tal}_f^+ := \min_{\psi} \mathbb{E}_x \left[\sqrt{\text{Inf}_{\psi}^+(x)} \right] = \Omega(\varepsilon_f)$$

Assume $\varepsilon_f = \Omega(1)$



vertices = $r \cdot 2^d$

$$I_f^+ \cdot \Gamma_f^+ = \Omega(1)$$

Dir. Margulis

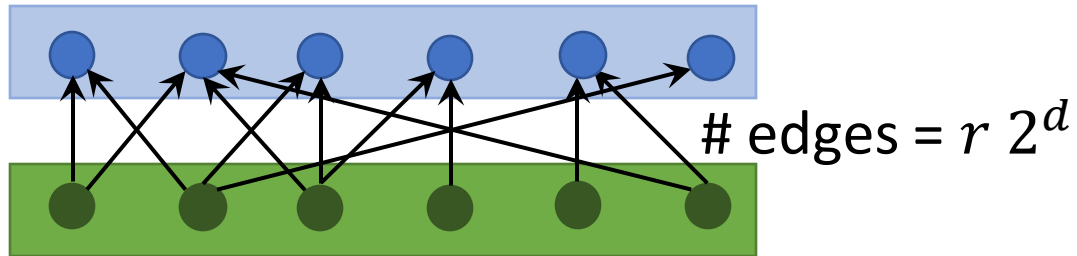
$$I_f^+ = \Omega(1)$$

Dir. Poincare

vertices = $2^d / r$

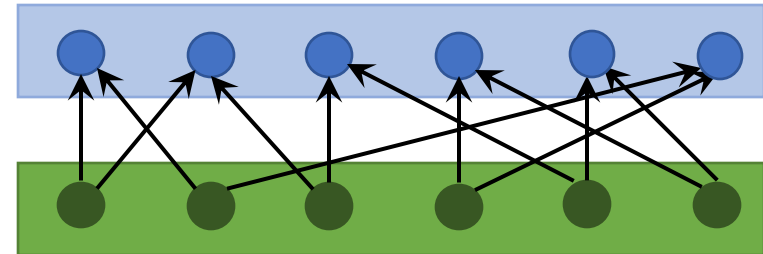
For some $r > 1$, $I_f^+ = r$ and $\Gamma_f^+ = 1/r$

The most regular boundary



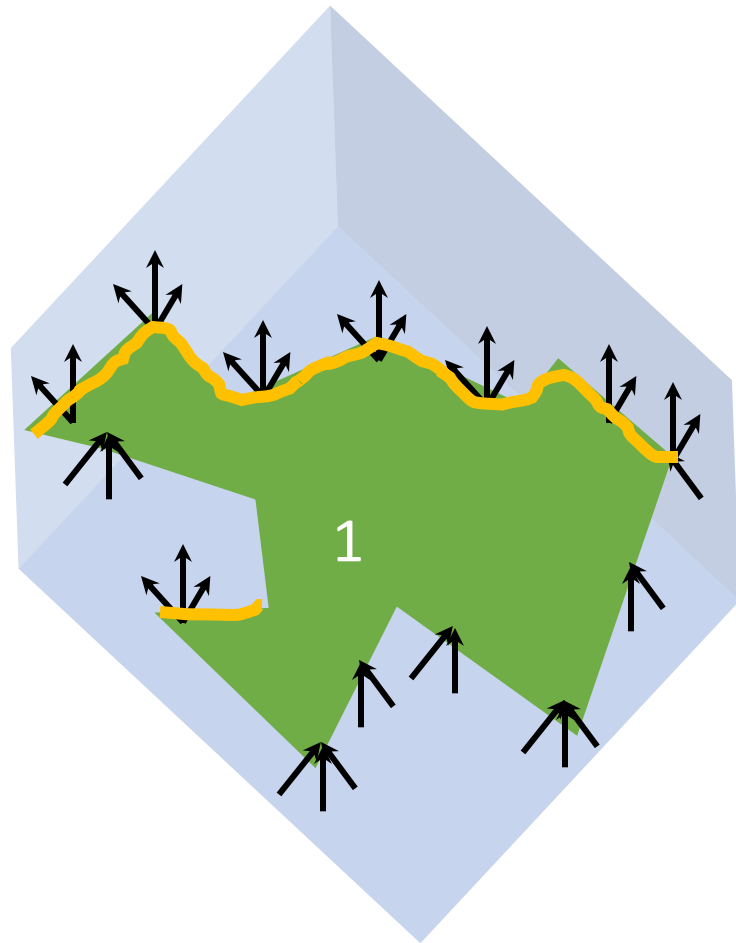
$$\# \text{ vertices} = 2^d / r$$

“Nicest case”
→



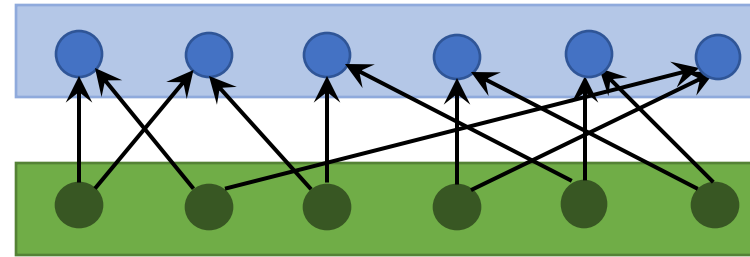
- Robust Talagrand theorem of KMS implies that's exactly what happens!

Boundaries are always regular!



Assume $\varepsilon_f = \Omega(1)$

“Nicest case”



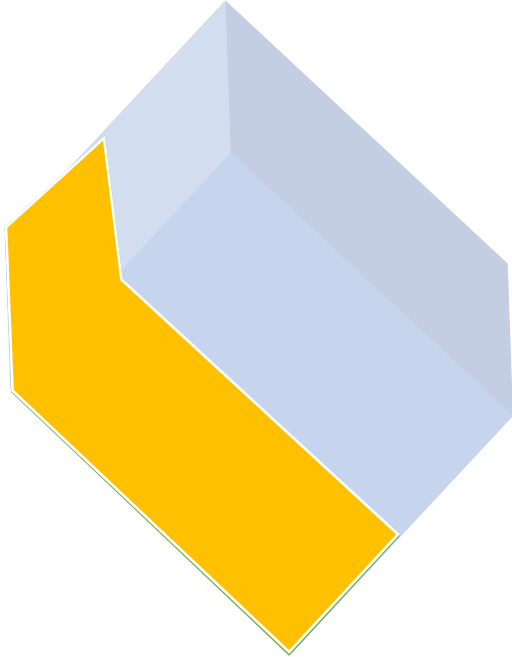
vertices = $2^d / r$

All degrees = r^2

There exists $r > 1$ such that boundary contains regular bipartite graph with these parameters.

- (Up to $d^{o(1)}$ factors)

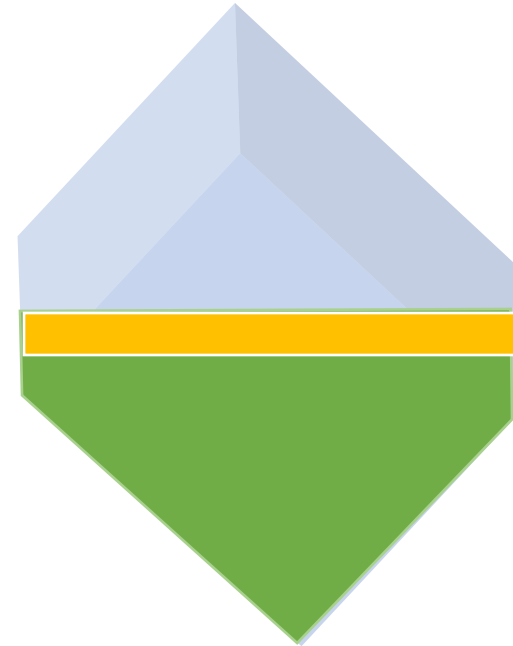
Our usual examples



anti-dictator

2^d vertices on boundary,
each with degree 1

Boundary size = $2^d / r$
All degrees = r^2



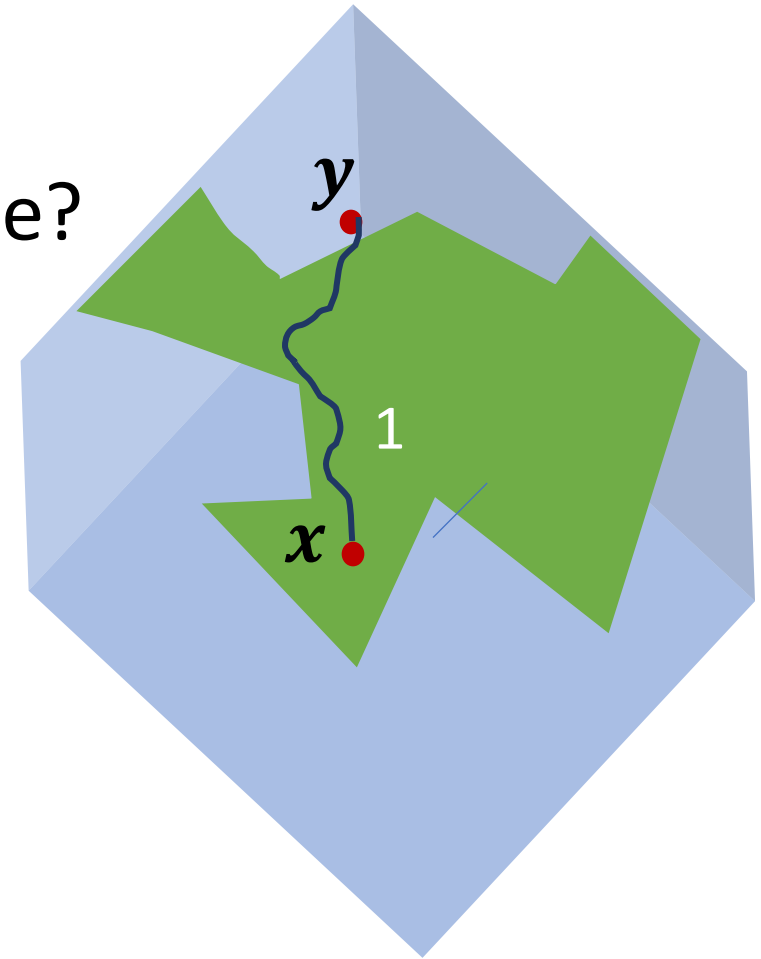
anti-majority

$2^d / \sqrt{d}$ vertices on
boundary,
each with degree d

But what about
monotonicity testing?

How to analyze the “path tester”

How to “escape” S that is far from monotone?



Be persistent!

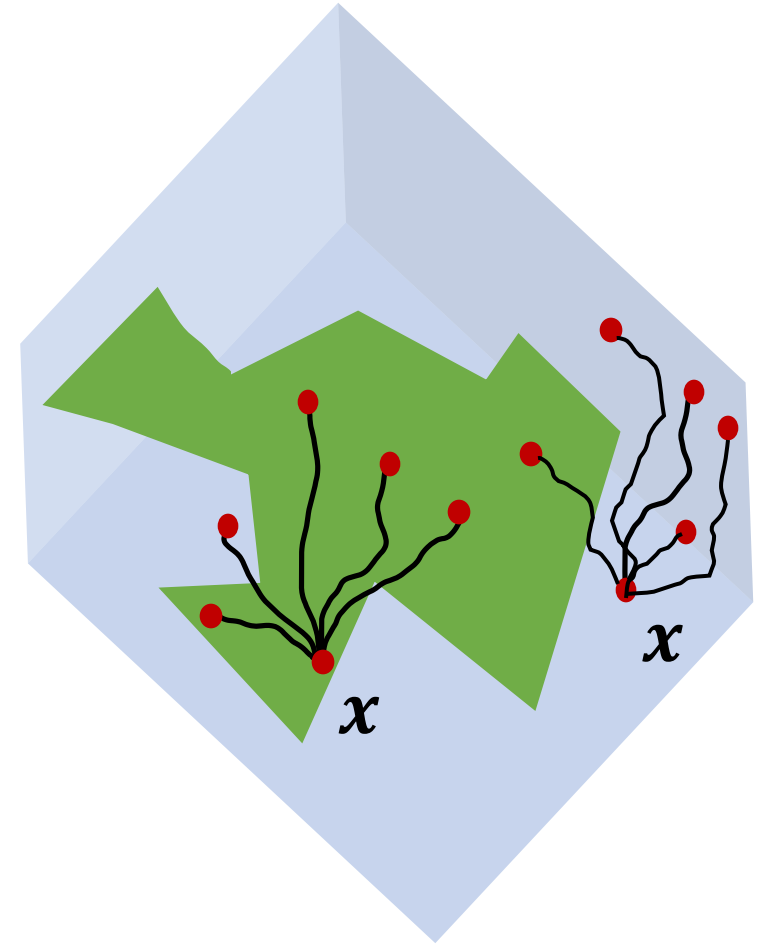
- x is ℓ -persistent, if ℓ -length (directed walk) stays within $f(x)$ -region whp

$$\Pr[\text{single step changes value}] = \frac{I_f}{d}$$

$$\Pr[\text{one of } \ell\text{-steps changes value}] \leq \ell \cdot \frac{I_f}{d}$$

$$\text{Fraction of NON } \ell\text{-persistent vertices} = O\left(\ell \cdot \frac{I_f}{d}\right)$$

$$\xrightarrow{I_f = O(\sqrt{d})} O\left(\frac{\ell}{\sqrt{d}}\right)$$



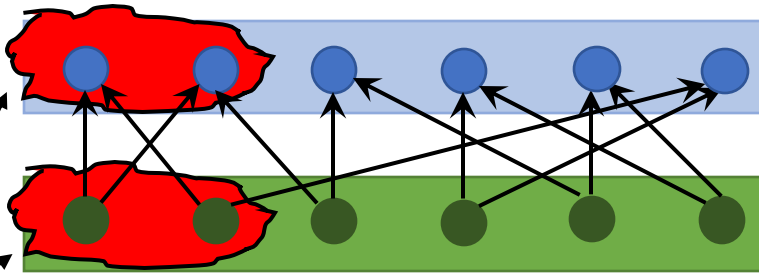
$$\text{If } I_f \gg \sqrt{d} \text{ then } I_f^+ \gg \sqrt{d}$$

Edge tester itself good

The analysis, in one slide

By (robust) Directed Talagrand, boundary is

Non- ℓ -persistent

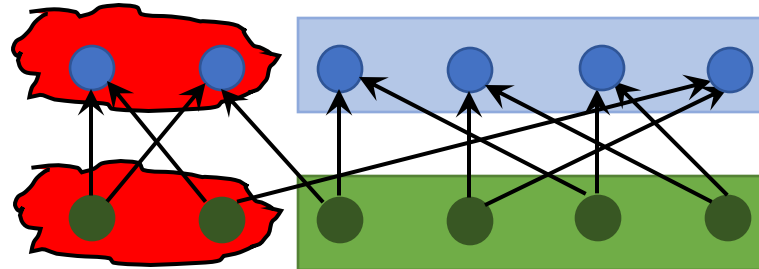


vertices = $2^d / r$

All degrees = r^2

Frac. non-persistent = $O\left(\frac{\ell}{\sqrt{d}}\right)$

Set $\ell \ll \sqrt{d}/r$
so frac. $\ll 1/r$



By regularity
of boundary

vertices $\approx 2^d / r$

All degrees $\approx r^2$

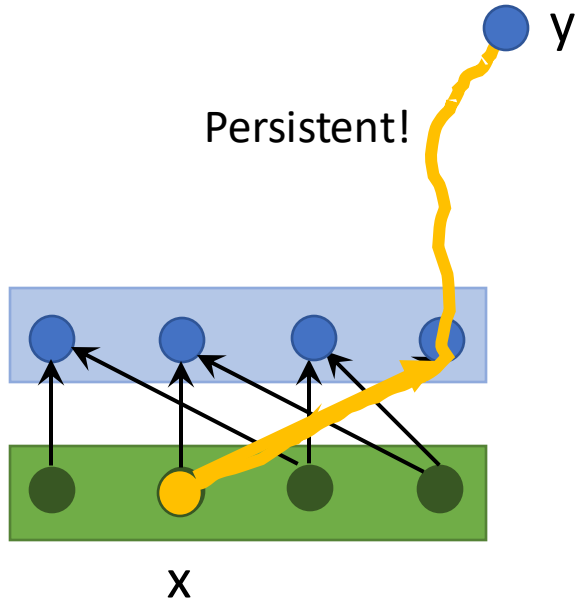
All ℓ -persistent

The analysis, in ~~one~~ two slides

With prob $\approx 1/r$, start with $f(x) = 1$ in this part

With prob $\approx r^2/\ell = r/\sqrt{d}$, relevant bit is flipped

When both happen, $f(y) = 0$



By regularity of boundary

vertices $\approx 2^d/r$

All degrees $\approx r^2$

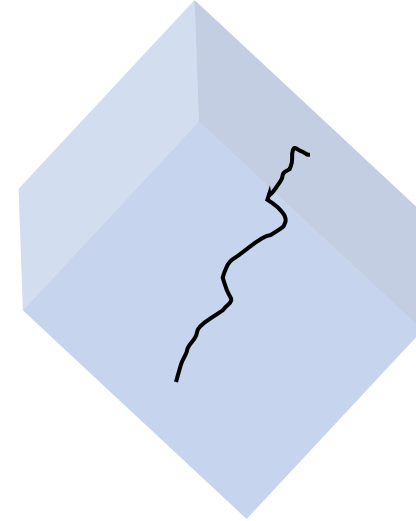
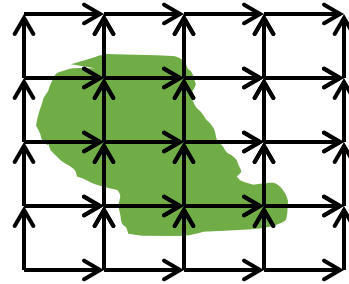
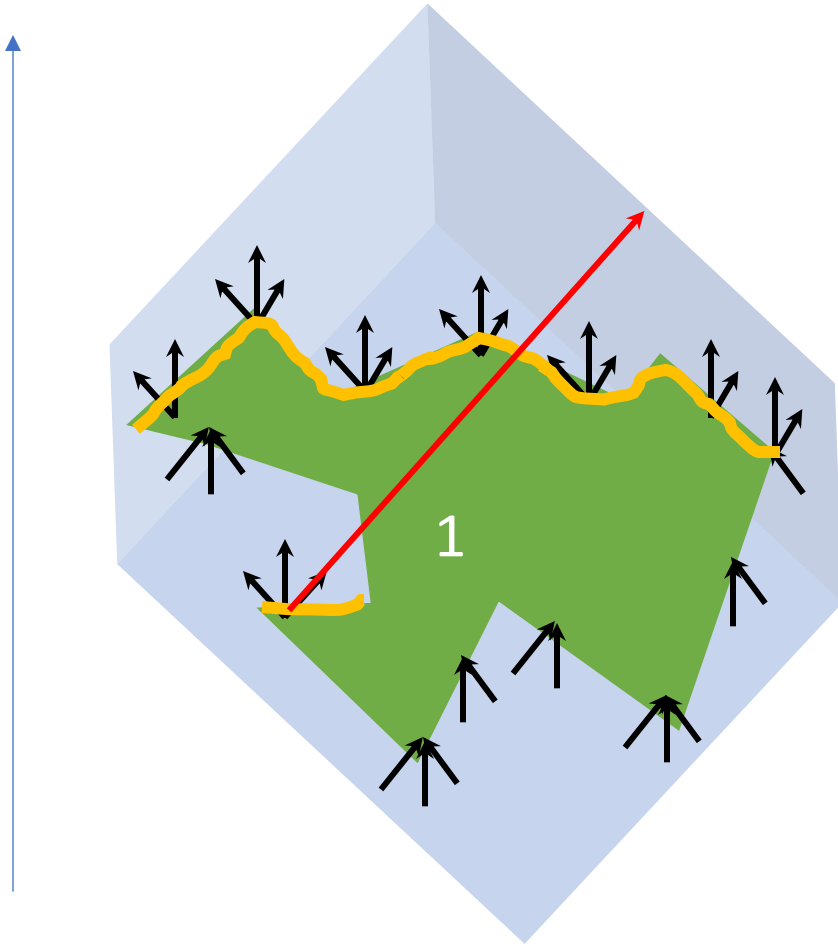
All ℓ -persistent

$\ell = o(\sqrt{d}/r)$

$$\text{Total prob} \approx \frac{1}{r} \cdot \frac{r}{\sqrt{d}} = \frac{1}{\sqrt{d}}$$

The challenge of hypergrids

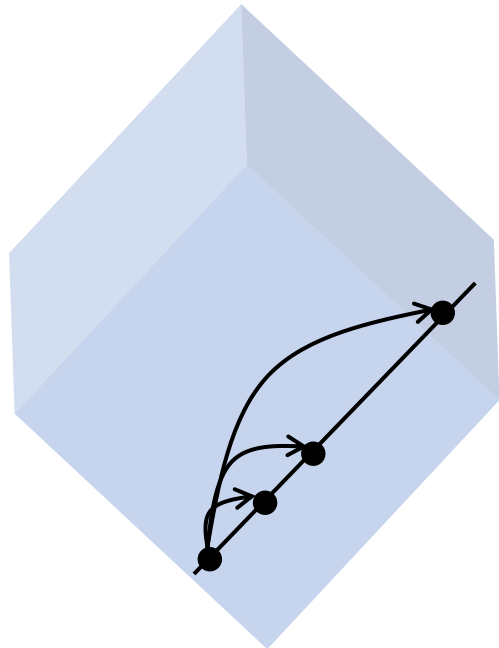
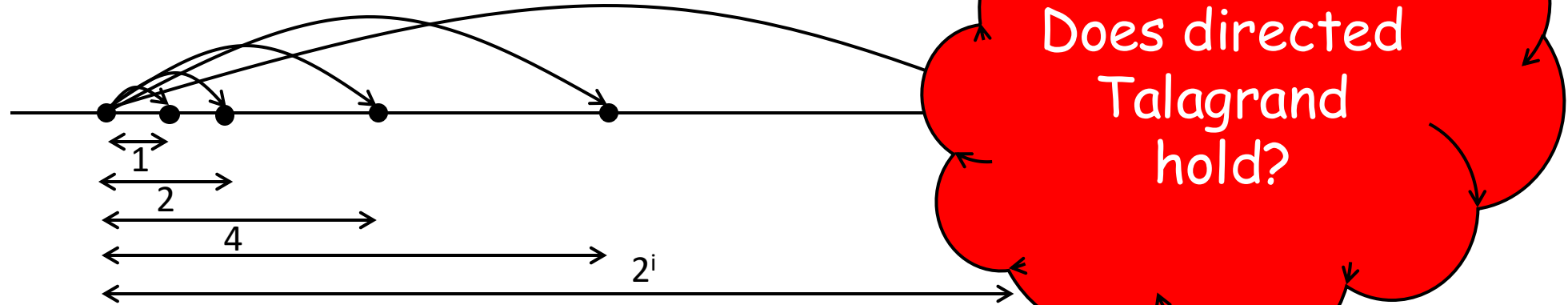
What is a boundary?



Move in a direction. But for “how much”?
What is influence?

How to define a path tester? What are upward
random walks?

The augmentation view

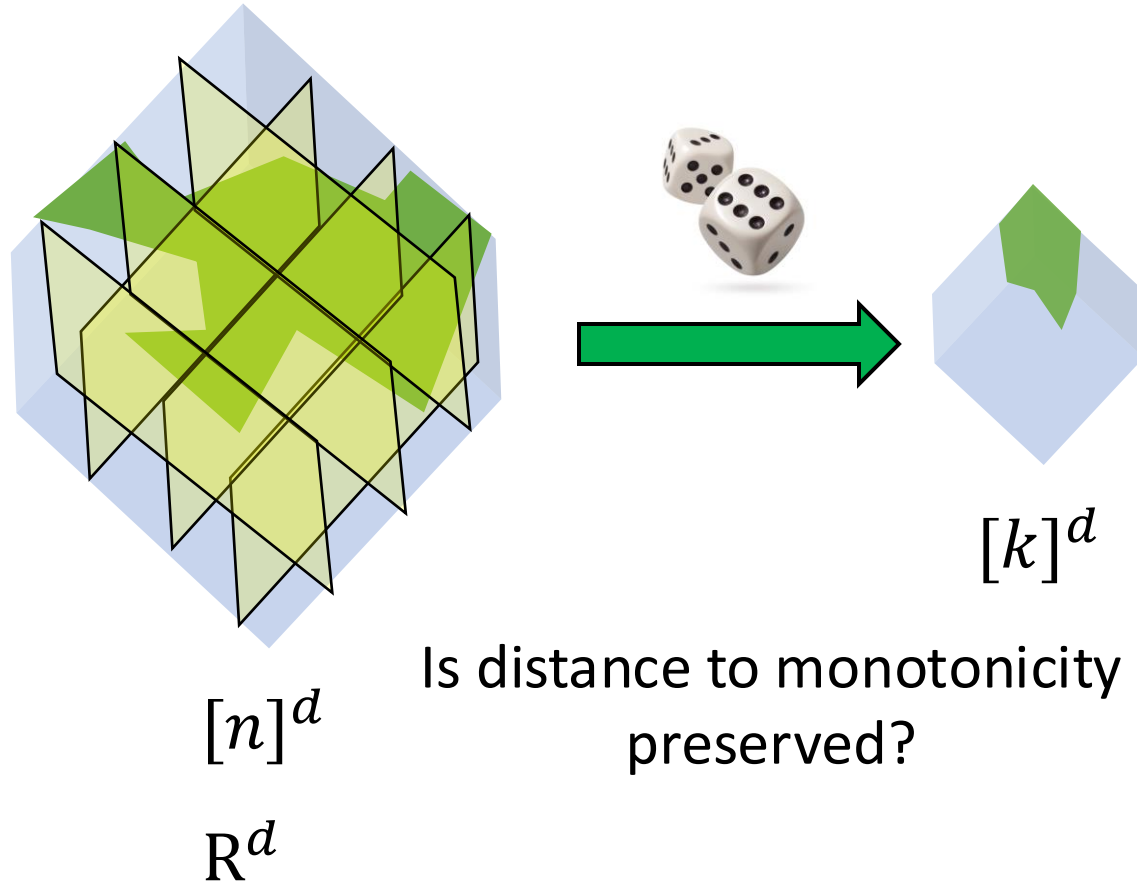


- Degree is now $d \log n$
 - Can we treat it a hypercube/product structure?
- [BCS18] Directed Margulis holds
 - Define boundaries in the graph theoretic way
 - $d^{5/6} \log n$ query tester, using path tester

Directed Margulis proofs more amenable to alternate domains.

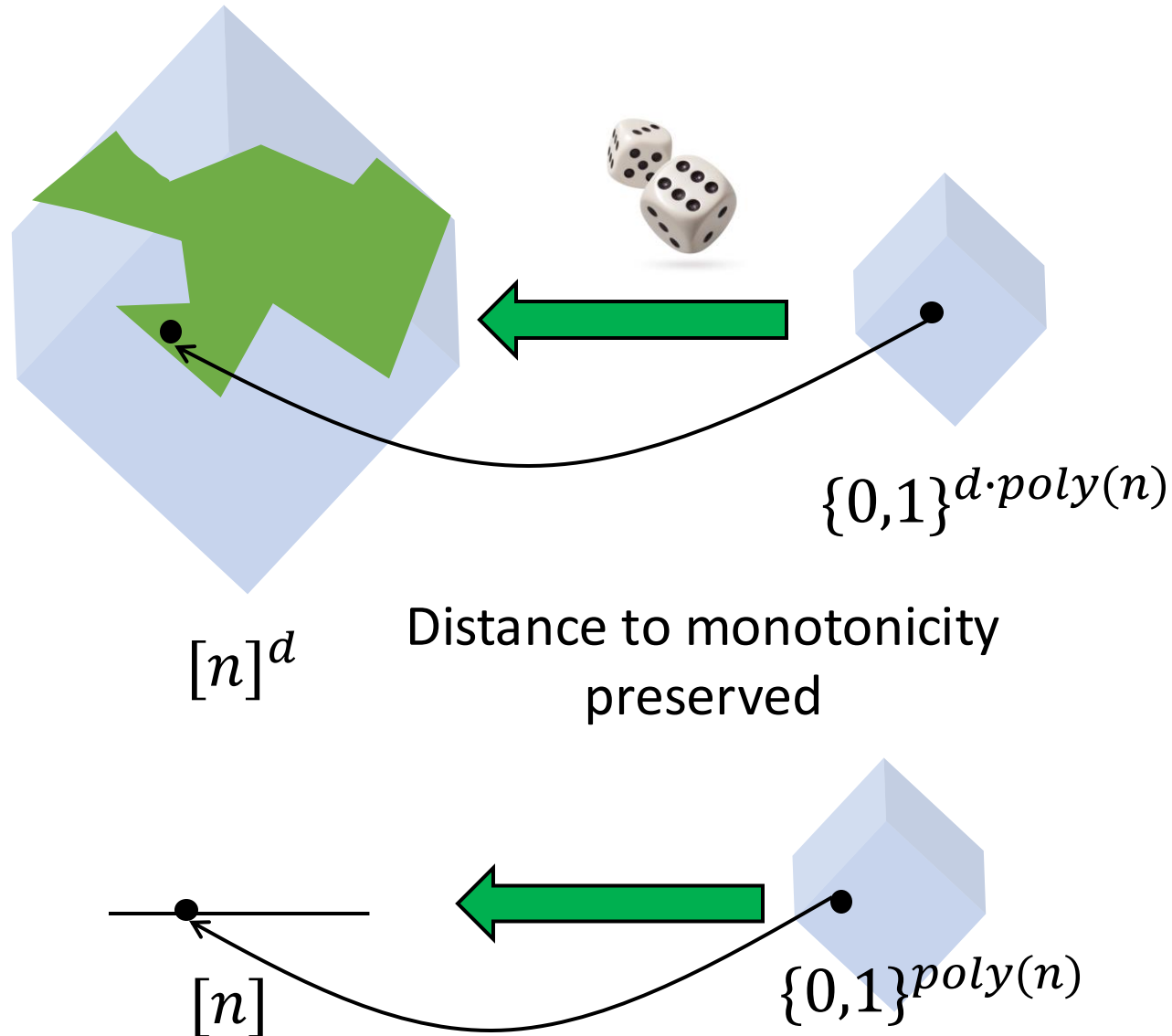
[KMS15] very intricate proof; doesn't seem to generalize

Domain reduction



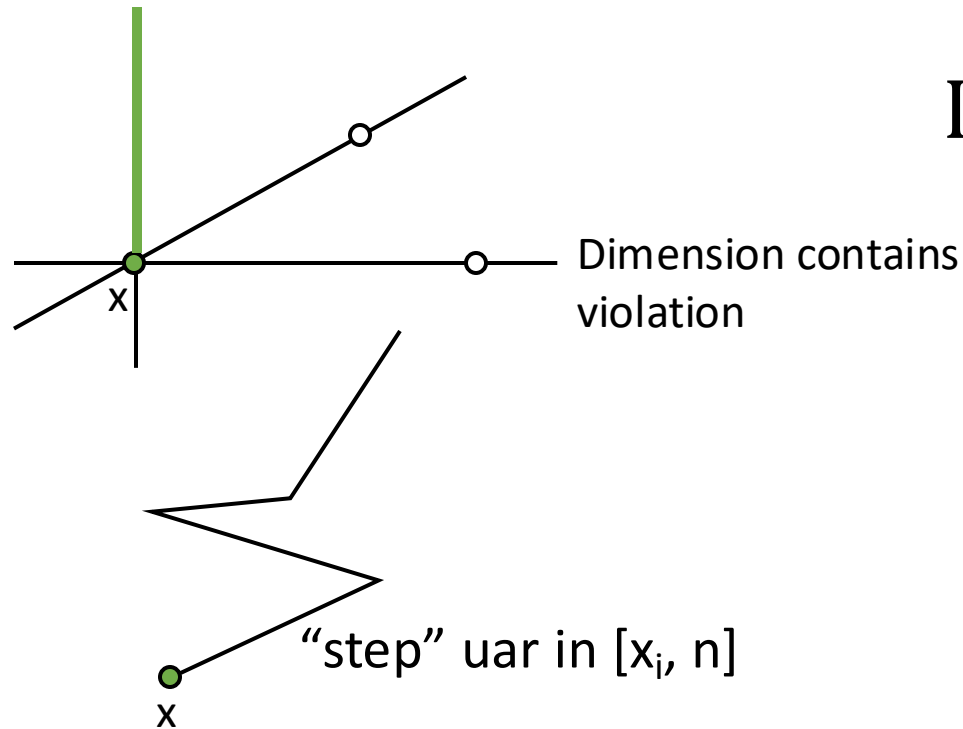
- Set $k=2$, and reduce to hypercubes...?
- [BCS20] If $k \ll d$, sampled function can be close to monotone
- [BCS20] If $k = \text{poly}(d)$, distance is preserved
 - So we can assume $n = \text{poly}(d)$
 - Even reduces from continuous
- [Harms-Yoshida 22] Downsampling

The embedding method



- Embedding $[n]$ into hypercube
- [Braverman-Kindler-Khot-Minzer 23]
- First \sqrt{d} tester for any $n > 2$
 - $\text{poly}(n)$ dependence necessary

Doing isoperimetry



$\text{Inf}^+(x) =$ # dimensions where x is in violation

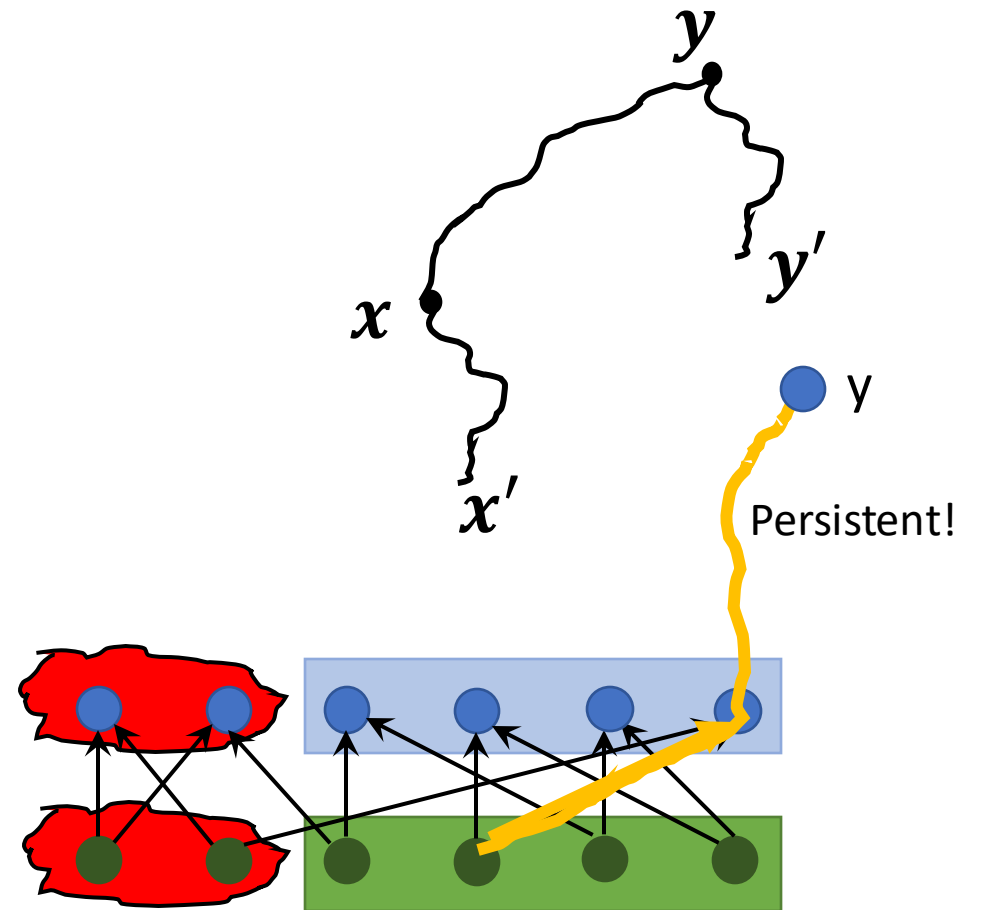
$$[\text{BCS23-1}] \text{Tal}_f^+ \\ := \underline{\text{Exp}}_{\Omega(\epsilon_f / \text{Mog } n)} \left[\sqrt{\text{Inf}^+(x)} \right]$$

- Also prove the robust version
- Direct tester analysis leads to $n\sqrt{d}$ query tester
 - Path picks uniform random step in each direction

The final step

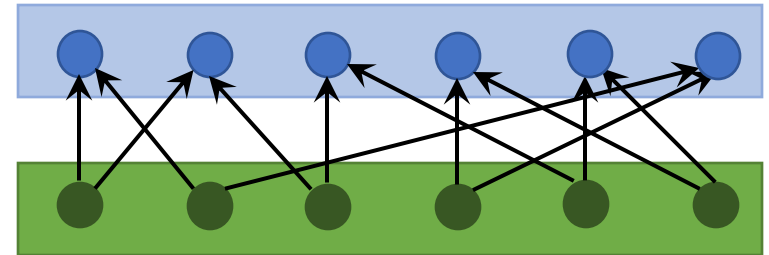
[BCS 23-2] Getting $d^{\frac{1}{2} + o(1)}$ query tester

- Tester does correlated walks
 - Heavily used in analysis
 - Standard tester probably works
- How to perform this analysis and not lose n factor?
 - New combinatorial tools to analyze the walk using the [BCS23-1] Talagrand theorem



(Mostly) end of story

$$\min_{\psi} \mathbb{E}_x \left[\sqrt{\text{Inf}_{\psi}^+(x)} \right] = \Omega(\varepsilon_f / \log n)$$



vertices = $2^d / r$
All degrees = r^2

- $d^{o(1)}$ loss annoying, comes from one specific calculation
- $d^{\frac{1}{2} + o(1)}$ **non-adaptive** one-sided monotonicity tester
 - Ends a 24 year odyssey
- Nearly matching (two-sided) lower bound

Some odds and ends

- Get rid of the $d^{o(1)}$ factor
- Are hypergrids strictly harder than hypercubes?
 - Only $(\log d)$ factors apart
- [\[Black-Kalemaj-Raskhodnikova 23\]](#) Tester for larger ranges, for hypercube
 - We can probably apply the methods for hypergrids

The big question

What is the adaptive complexity of monotonicity testing for hypercubes/grids?

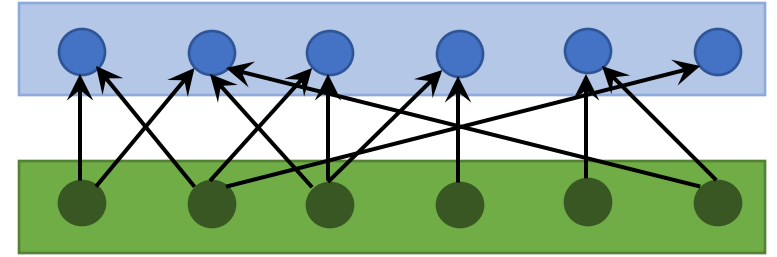
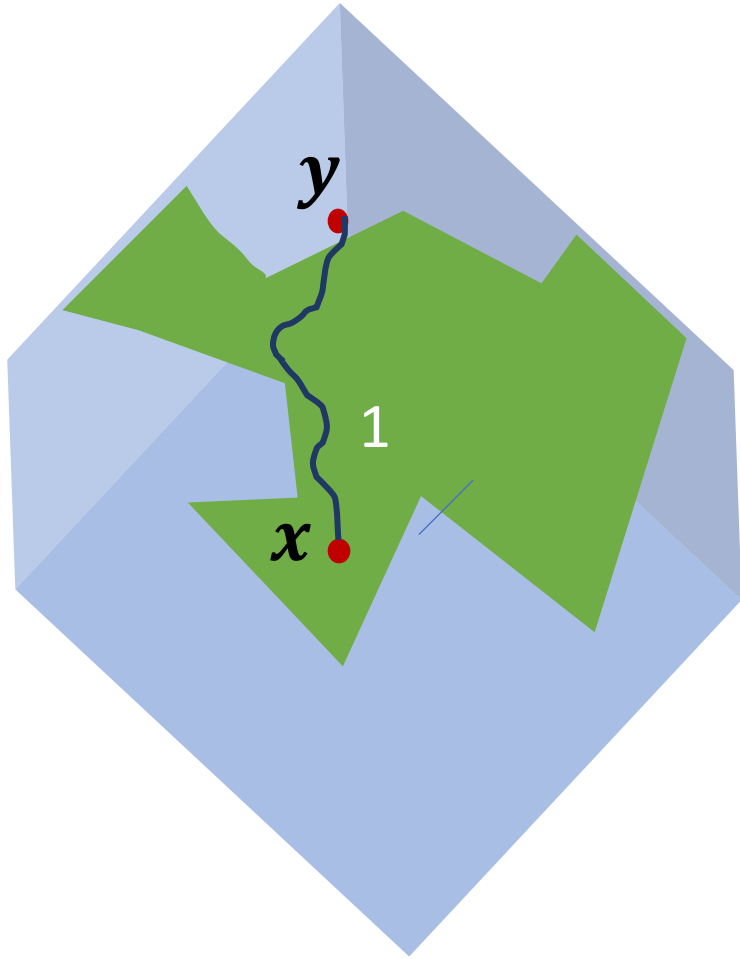
- [Blais-Belovs 16] $\Omega(d^{1/4})$ lower bound
- [Chen-Waingarten-Xie 18] $\Omega(d^{1/3})$ lower bound
 - Every example has matching adaptive upper bound
- [Chakrabarty-S 16] $O(I_f)$ query adaptive tester
 - Proves adaptivity gap, for natural families

More on directed isoperimetry

- [Black-Kalemaj-Raskhodnikova 23] Directed Talagrand for real-range
- [Pinto 23, Pinto 24] Differential functions $f: [0,1]^d \rightarrow [0,1]$, with access to derivatives
 - Draws connections to optimal transport theory, based on undirected Poincare/Talagrand inequalities
- [Canonne-Chen-Levi-Kamath-Waingarten 21] Applications of robustness concept to distribution testing
- [Yoshida 24] Directed isoperimetry for general posets

Generalizing hypercube results

- [Pallavoor-Raskhodnikova-Waingarten 20] Estimating distance to monotonicity, \sqrt{d} -approximations in poly(d) time for hypercube
 - Can we get results for hypergrids? Also implies results for product distributions...?
- [Berman-Raskhodnikova-Yaroslavtsev 14] L_p testing



Thank you!

Here, no bad pun