



Optimal quantile estimation for streams

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Quantile estimation problem

x_1 x_2 x_3 \cdot \cdot \cdot x_n

Query: element x
Output: rank of x (up to $\pm \epsilon n$)

Input: Given parameters n , U , ϵ , receive a stream $x_1, x_2, x_3, \dots, x_n$ of numbers in $\{1, \dots, U\}$.

In memory: Store a running sketch of the data that uses as little memory as possible.

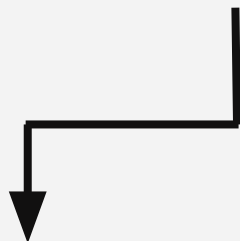
Answering queries: Receive an element x of $\{1, \dots, U\}$ and output its rank in the stream, that is, the number of elements that were less than x , up to additive error ϵn .

- Equivalently: receive a rank r as a query, and output the element whose rank is between $r - \epsilon n$ and $r + \epsilon n$



Quantile estimation problem

3 2 2 4 1 2



Query: $\text{rank}(3) = ?$

Output: ?

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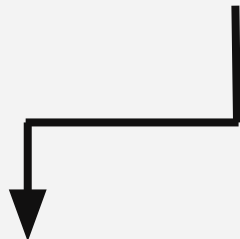
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Quantile estimation problem

3 2 2 4 1 2



Query: $\text{rank}(3) = ?$

Output: 4 ($\pm \epsilon n$)

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Applications of quantile estimation

- Estimating system reliability — for example, estimating the 99th percentile latency of a system.
- User analytics for websites/online content.
 - Median or 90th percentile time for watching a YouTube video.
 - Estimating time a typical user spends on different screens in the app.
 - Companies like  **Amplitude** exist for this very purpose.
- There are many libraries for quantile sketches: Spark-SQL, Apache DataSketches project, GoogleSQL, and XGBoost.



History of quantiles

n = length of stream
 U = size of universe
 ϵn = additive error

(1 word = $\log n + \log U$ bits)

	Space (in words)	Properties
MRL Sketch [1998]	$O(\epsilon^{-1} \log^2 n)$	comparison-based, deterministic
GK Sketch [2001]	$O(\epsilon^{-1} \log n)$	comparison-based, deterministic
Q-digest [2004]	$O(\epsilon^{-1} \log U)$	deterministic
KLL Sketch [2016]	$O(\epsilon^{-1} \log \log(1/\delta))$	comparison-based, randomized
This talk	$O(\epsilon^{-1})$	deterministic

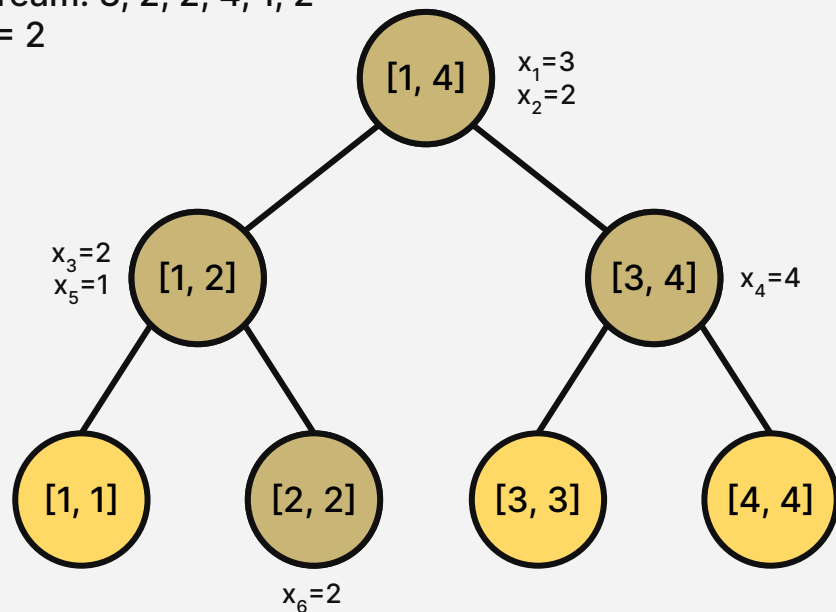
(This is optimal)



Q-digest sketch

n = length of stream
 U = size of universe
 ϵn = additive error
 $\alpha = \epsilon n / \log U$
= capacity of each node

Stream: 3, 2, 2, 4, 1, 2
 $\alpha = 2$



Structure: binary tree, where each node is a subinterval of $[1, U]$. Each node stores some subset of stream elements. Each node has a “capacity” $\alpha = \epsilon n / \log U$.

Insertion: insert each element into the tree into the top-most node whose interval contains it, that is not yet at its capacity.

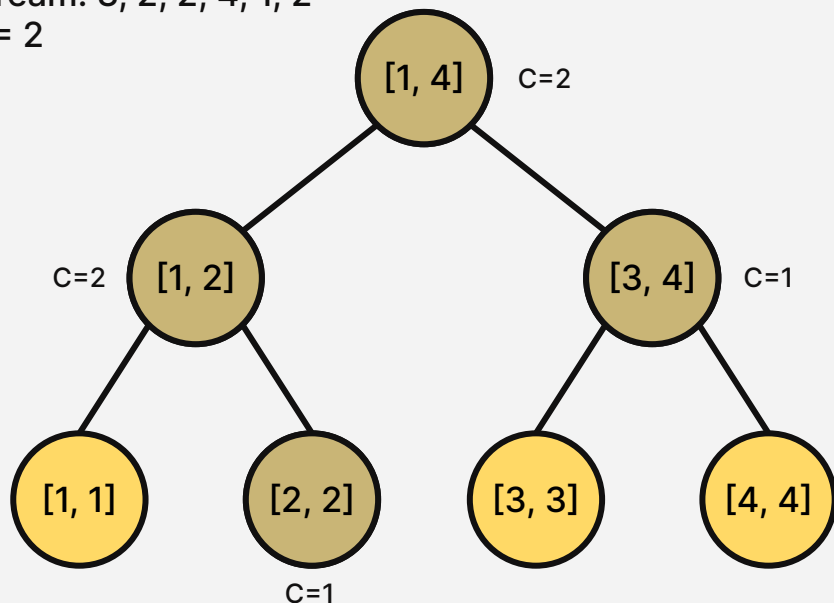
Storage: for each node, only store the number of elements it has.



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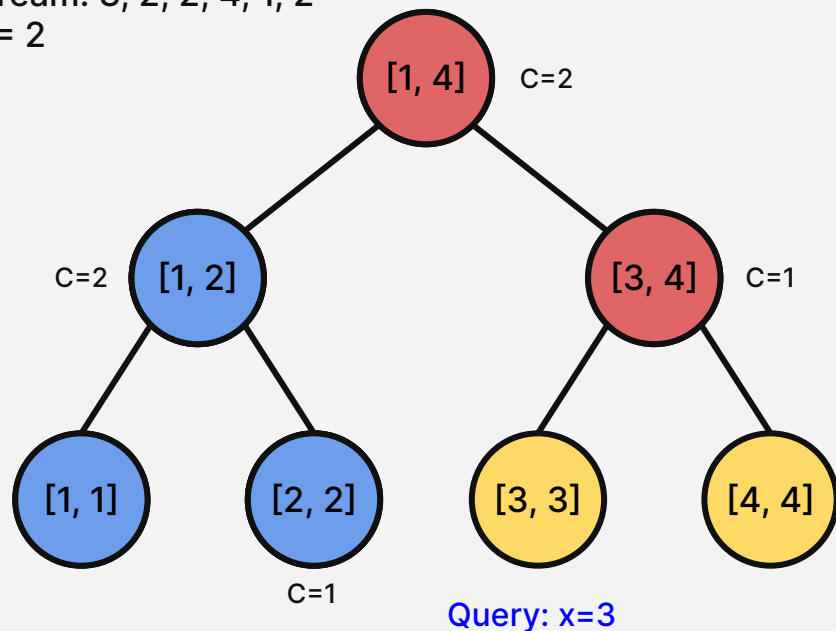
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Answering queries: To find the rank of x , add up the counts of **all nodes** whose intervals contain only elements less than x .

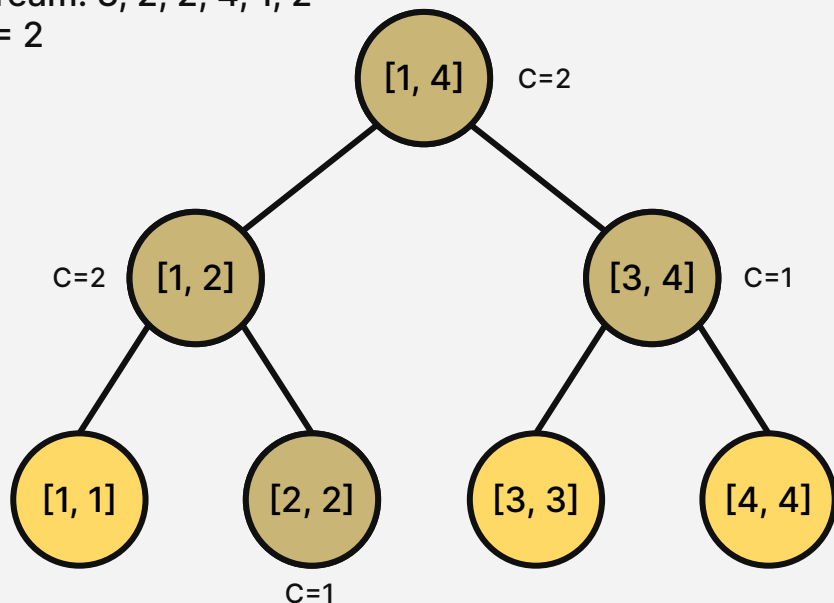
- The only possible **missed elements** are in ancestors of x
- $\log U$ ancestors, so total error in rank is at most $\alpha \log U = \epsilon n$



Q-digest sketch

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 $\alpha = 2$



Space complexity: need to store list of all nonempty nodes and their counts.

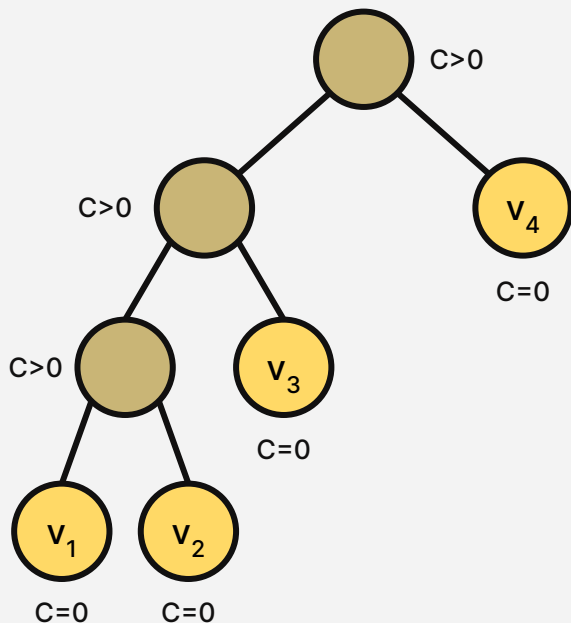
- Number of nonempty nodes: $O(n/\alpha)$
= $O(\epsilon^{-1} \log U)$
- List of all nodes: only need to store tree topology, so **1 bit per node**
- Counts: $\log \alpha \approx O(\log n)$ bits per node
- Total storage: **$O(\epsilon^{-1} \log U \log n)$ bits**

Goal of our algorithm: reduce the space needed to store counts



Reducing memory of counts

n = length of stream
 U = size of universe
 ϵn = additive error
 $\alpha = \epsilon n / \log U$
= capacity of each node



Idea: Only store approximate counts of nodes

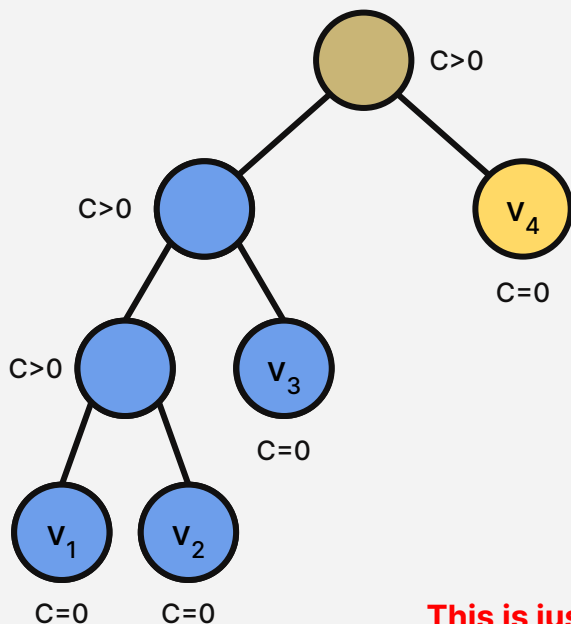
How do we insert an element if we only have approximate counts?

- Consider intermediate stage of q -digest tree, and let v_1, \dots, v_m be children of nonempty nodes. Each insertion will increment the count of some v_i (or its parent).
- Process insertions in **batches** of size α . After each batch, increment counts of v_i .



Reducing memory of counts

n = length of stream
 U = size of universe
 ϵn = additive error
 $\alpha = \epsilon n / \log U$
 $=$ capacity of each node



**This is just a
quantile sketch!**



Process insertions in **batches** of size α . After each batch, increment counts of v_i .

How to process a batch?

- Each stream element will go into v_i for some i .
- Need to obtain approximate counts C'_i which are close to the true counts C_i .
- **Rank query** adds up C_1 to C_k for some k , so additional error introduced to rank query is

$$C'_1 + \dots + C'_k - (C_1 + \dots + C_k).$$

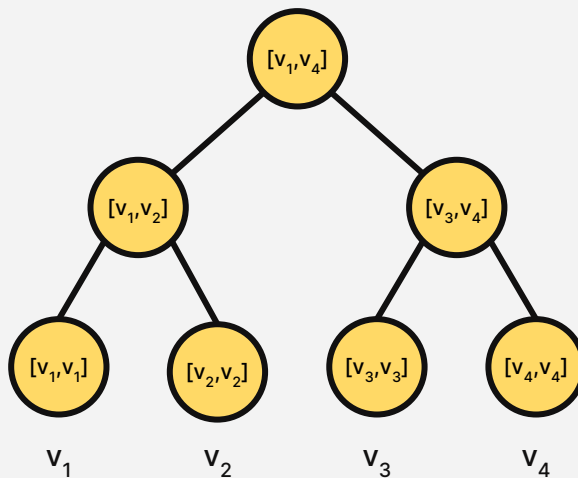
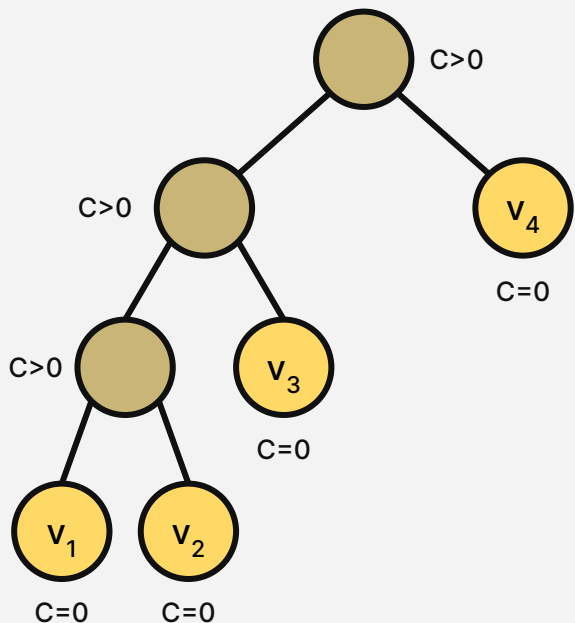
- In other words, need an approximation to $C_1 + \dots + C_k$ for each k (must be accurate within $\epsilon\alpha$).

- (Can recover C_1, \dots, C_m from their prefix sums.)



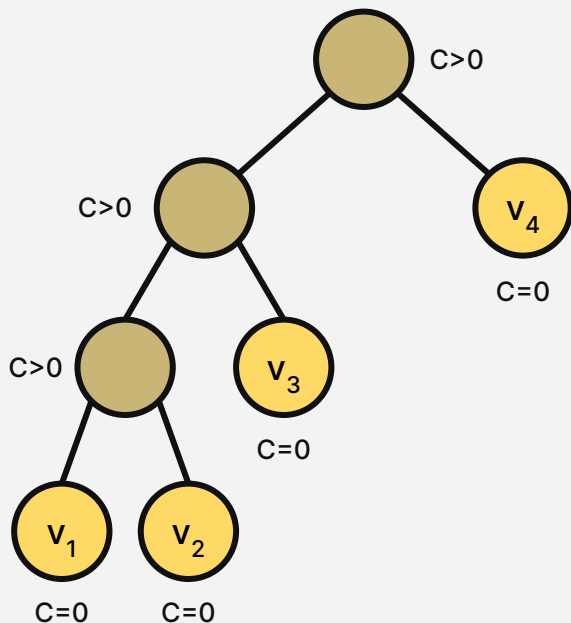
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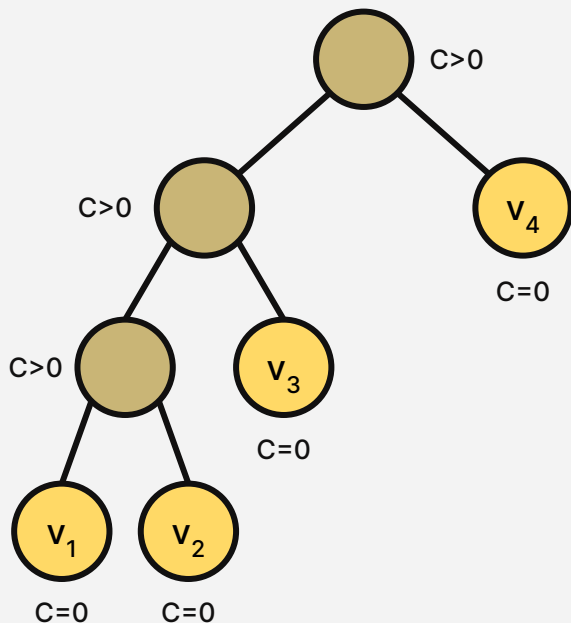
Process insertions in **batches** of size $n' = \alpha$. After each batch, increment counts of v_i .

- Obtain approximate counts from a smaller q -digest on v_1, \dots, v_m
- Parameters of inner q -digest:
 - $n' = \alpha \leq n$
 - $U' \leq n / \alpha = O(\epsilon^{-1} \log U)$
 - $\epsilon' = \epsilon$
 - Total space: $O((\epsilon')^{-1} \log n' \log U') = \tilde{O}(\epsilon^{-1} \log n \log \log U)$ bits
- Outer q -digest stores counts in multiples of $\epsilon \alpha$ up to α , so $O(\log \epsilon^{-1}) = \tilde{O}(1)$ bits per node
 - Total space: $\tilde{O}(\epsilon^{-1} \log U)$ bits
- Overall space: $\tilde{O}(\epsilon^{-1} \log \log U)$ words



Reducing memory of counts

n = length of stream
 U = size of universe
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 $\alpha = \epsilon n / \log U$
= capacity of each node



Process insertions in **batches** of size $n' = \alpha$. After each batch, increment counts of v_i .

Overall space: $\tilde{O}(\epsilon^{-1} \log \log U)$ words

Can recursively replace inner q -digest with another instance of our algorithm

- Can do this roughly $\log^* U$ times, but need to reduce error parameter ϵ to $\epsilon / \log^* U$ per recursive layer
- Total space: $\tilde{O}(\epsilon^{-1} \log^* U)$ words



Getting optimal space

n = length of stream
 U = size of universe
 ϵn = additive error
 $\alpha = \epsilon n / \log U$
= capacity of each node

- To get rid of $\log^* U$ term, give each recursive layer a different error parameter ϵ : the top and bottom layers get $O(\epsilon)$ and the rest are slightly smaller
- Losing the $\text{polylog}(\epsilon^{-1})$ term is harder
 - In order to have $O(1)$ space per node instead of $O(\log \epsilon^{-1})$, can only store approximate values of $C=0$ and $C=\alpha$
 - Batches will then need to be much larger than α , so will need to keep track of the descendants of v_i as well in case v_i fills up during a batch
 - Finally, also need to change shape of q -digest from one tree of height $\log(U)$ to $1/\epsilon$ trees of height $\log(\epsilon U)$; will need this for the deeper layers of recursion.



Lower bounds

n = length of stream
 U = size of universe
 ϵn = additive error
 $\alpha = \epsilon n / \log U$
= capacity of each node

More precisely, our algorithm uses $O(\epsilon^{-1} (\log(\epsilon U) + \log(\epsilon n)))$ bits.

Easy lower bound of $\Omega(\epsilon^{-1} \log(\epsilon U))$ bits, since if algorithm receives ϵn copies each of $1/\epsilon$ elements, it must remember them all.

Theorem [Wang, preprint via private communication]: Deterministic quantile sketches require $\Omega(\epsilon^{-1} \log(\epsilon n))$ bits.

