

Theoretical limits of 1UIP Learning

Marc Vinyals

Waipapa Taumata Rau – University of Auckland

joint work with Noah Fleming, Vijay Ganesh, Antonina Kolokolova, and Ian Li

DPLL

$$y \vee z \quad y \vee \bar{z} \quad x \vee \bar{y} \vee z \quad x \vee \bar{y} \vee \bar{z} \quad \bar{x} \vee \bar{y}$$

Algorithm 1: DPLL

while *not solved* **do**

if *conflict* **then** backtrack()

else if *unit* **then** propagate()

else branch()

State: partial assignment

DPLL

Algorithm 1: DPLL

while *not solved* **do**

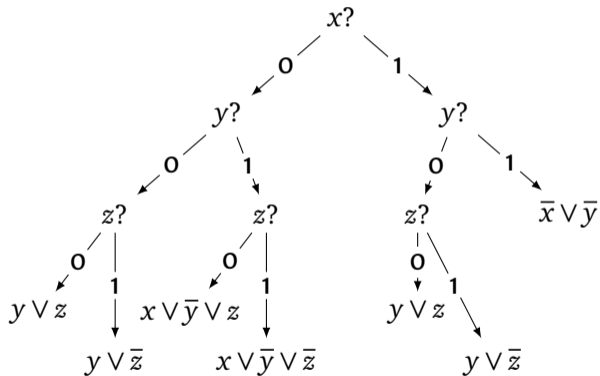
if *conflict* **then** backtrack()

else if *unit* **then** propagate()

else branch()

State: partial assignment

$$y \vee z \quad y \vee \bar{z} \quad x \vee \bar{y} \vee z \quad x \vee \bar{y} \vee \bar{z} \quad \bar{x} \vee \bar{y}$$

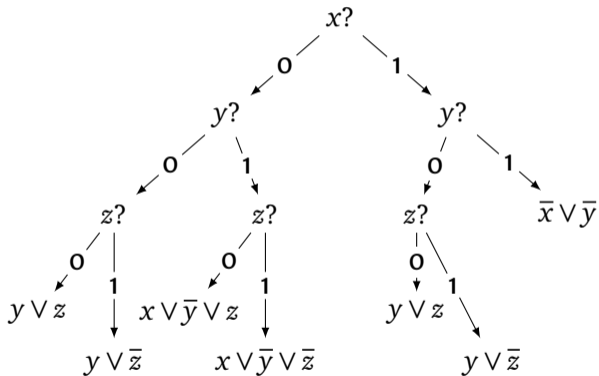


Resolution

- ▶ Search tree \rightsquigarrow resolution proof

$$\frac{C \vee v \quad D \vee \bar{v}}{C \vee D}$$

$$y \vee z \quad y \vee \bar{z} \quad x \vee \bar{y} \vee z \quad x \vee \bar{y} \vee \bar{z} \quad \bar{x} \vee \bar{y}$$



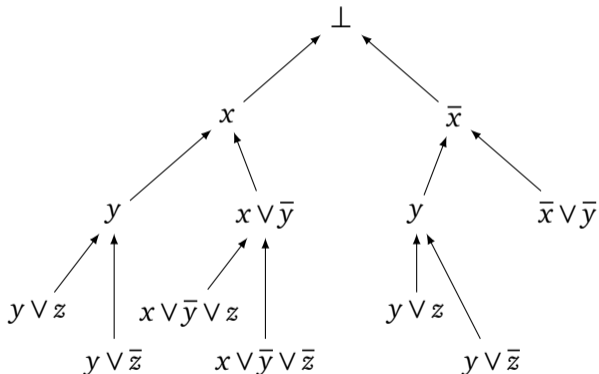
Resolution

- ▶ Search tree \rightsquigarrow resolution proof

$$\frac{C \vee v \quad D \vee \bar{v}}{C \vee D}$$

- ▶ Resolution lower bounds \implies DPLL lower bounds

$$y \vee z \quad y \vee \bar{z} \quad x \vee \bar{y} \vee z \quad x \vee \bar{y} \vee \bar{z} \quad \bar{x} \vee \bar{y}$$



DPLL

Algorithm 1: DPLL

while *not solved* **do**

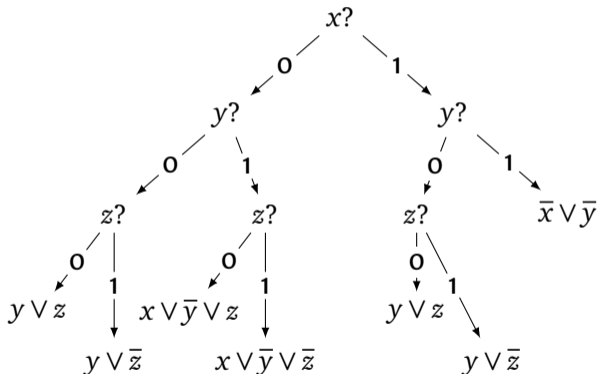
if *conflict* **then** backtrack()

else if *unit* **then** propagate()

else branch()

State: partial assignment

$$y \vee z \quad y \vee \bar{z} \quad x \vee \bar{y} \vee z \quad x \vee \bar{y} \vee \bar{z} \quad \bar{x} \vee \bar{y}$$



CDCL

Algorithm 2: CDCL

while *not solved* **do**

if *conflict* **then** **learn**()

else if *unit* **then** propagate()

else

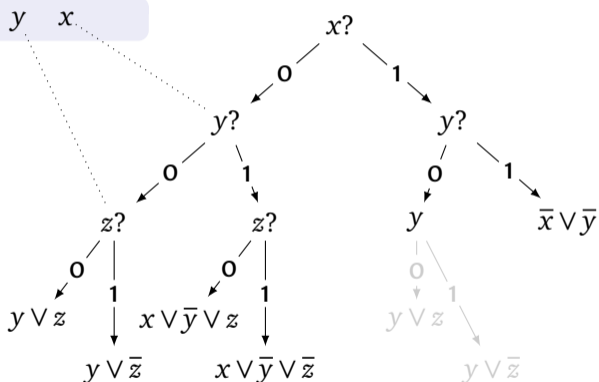
 maybe forget()

 maybe restart()

 branch()

State: partial assignment
& learned clauses

$y \vee z$ $y \vee \bar{z}$ $x \vee \bar{y} \vee z$ $x \vee \bar{y} \vee \bar{z}$ $\bar{x} \vee \bar{y}$



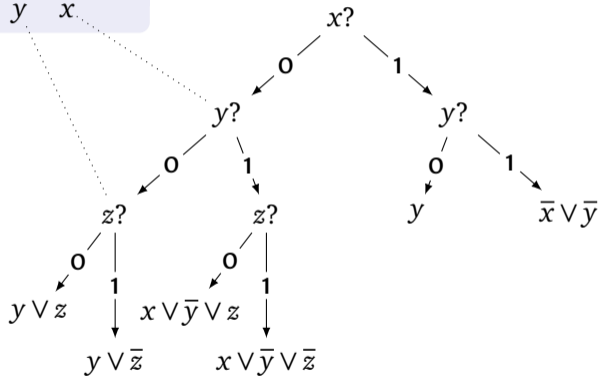
Resolution

- ▶ Search tree \rightsquigarrow resolution proof

$$\frac{C \vee v \quad D \vee \bar{v}}{C \vee D}$$

$$y \vee z \quad y \vee \bar{z} \quad x \vee \bar{y} \vee z \quad x \vee \bar{y} \vee \bar{z} \quad \bar{x} \vee \bar{y}$$

$$y \quad x$$

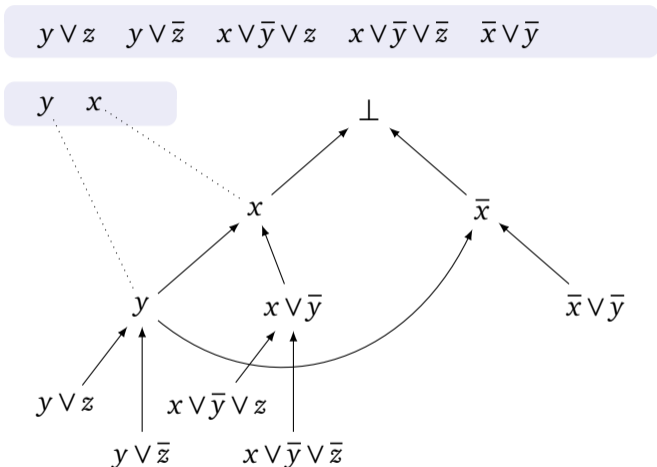


Resolution

- ▶ Search tree \rightsquigarrow resolution proof

$$\frac{C \vee v \quad D \vee \bar{v}}{C \vee D}$$

- ▶ Resolution lower bounds \implies CDCL lower bounds



CDCL vs Resolution

- ▶ CDCL proofs are in (general) resolution form
- ▶ DPLL proofs are in weaker “tree-like” form
 - ▶ There are formulas with polynomial resolution proofs but all tree-like proofs are exponential
- ▶ Is CDCL as powerful as general resolution?

CDCL vs Resolution

- ▶ CDCL proofs are in (general) resolution form
- ▶ DPLL proofs are in weaker “tree-like” form
 - ▶ There are formulas with polynomial resolution proofs but all tree-like proofs are exponential
- ▶ Is CDCL as powerful as general resolution?

- ▶ Partial results in 2000s
 - [Beame, Kautz, Sabharwal '04]
 - [Van Gelder '05]
 - [Hertel, Bacchus, Pitassi, Van Gelder '08]
 - [Buss, Hoffmann, Johannsen '08]

CDCL vs Resolution

- ▶ CDCL proofs are in (general) resolution form
- ▶ DPLL proofs are in weaker “tree-like” form
 - ▶ There are formulas with polynomial resolution proofs but all tree-like proofs are exponential
- ▶ Is CDCL as powerful as general resolution?

- ▶ Partial results in 2000s
 - [Beame, Kautz, Sabharwal '04]
 - [Van Gelder '05]
 - [Hertel, Bacchus, Pitassi, Van Gelder '08]
 - [Buss, Hoffmann, Johannsen '08]

- ▶ Yes (under natural model)
 - [Pipatsrisawat, Darwiche '09]
 - [Atserias, Fichte, Thurley '09]
 - [Beyersdorff, Böhm '21]

CDCL equivalent to Resolution: Statement

Theorem

[Pipatsrisawat, Darwiche '09]

With **non-deterministic** variable decisions,
CDCL can efficiently find resolution proofs

Theorem

[Atserias, Fichte, Thurley '09]

With **random** variable decisions,
CDCL can efficiently find **bounded-width** resolution proofs

CDCL equivalent to Resolution: Statement

Theorem

[Pipatsrisawat, Darwiche '09]

With **non-deterministic** variable decisions,
CDCL can efficiently ~~find~~ reproduce resolution proofs

Theorem

[Atserias, Fichte, Thurley '09]

With **random** variable decisions,
CDCL can efficiently find **bounded-width** resolution proofs

CDCL equivalent to Resolution: Simulation

- ▶ Derivation $\pi = C_1, \dots, C_t$.
- ▶ Goal: learn every clause $C_i \in \pi$.

CDCL equivalent to Resolution: Simulation

- ▶ Derivation $\pi = C_1, \dots, C_t$.
- ▶ Goal: learn every clause $C_i \in \pi$.

Algorithm 3: Simulation

for $C_i \in \pi$ **do**

while C_i not learned **do**

if conflict **then**

 learn()

 restart()

else if unit **then** propagate()

else assign a literal in C_i to false

CDCL equivalent to Resolution: Simulation

- ▶ Derivation $\pi = C_1, \dots, C_t$.
- ▶ Goal: ~~learn~~ absorb every clause $C_i \in \pi$.
- ▶ C **absorbed** if learning C does not enable more unit propagations.

Algorithm 3: Simulation

for $C_i \in \pi$ **do**

while C_i *not absorbed* **do**

if *conflict* **then**

 learn()

 restart()

else if *unit* **then** propagate()

else assign a literal in C_i to false

CDCL equivalent to Resolution: Assumptions

```
for  $C_i \in \pi$  do  
  while  $C_i$  not absorbed do  
    if conflict then  
      learn()  
      restart()  
    else if unit then propagate()  
    else assign a literal in  $C_i$  to false  
  restart()
```

- ▶ Optimal variable choices
- ▶ Clauses not thrown away
- ▶ Frequent restarts
- ▶ Standard learning

CDCL equivalent to Resolution: Assumptions

```
for  $C_i \in \pi$  do  
  while  $C_i$  not absorbed do  
    if conflict then  
      learn()  
      restart()  
    else if unit then propagate()  
    else assign a literal in  $C_i$  to false  
  restart()
```

- ▶ Optimal variable choices
- ▶ Clauses not thrown away
- ▶ Frequent restarts
- ▶ Standard learning

CDCL equivalent to Resolution: Assumptions

```
for  $C_i \in \pi$  do  
  while  $C_i$  not absorbed do  
    if conflict then  
      learn()  
      restart()  
    else if unit then propagate()  
    else assign a literal in  $C_i$  to false  
  restart()
```

- ▶ Optimal variable choices
- ▶ Clauses not thrown away
- ▶ Frequent restarts
- ▶ Standard learning

CDCL equivalent to Resolution: Assumptions

```
for  $C_i \in \pi$  do  
  while  $C_i$  not absorbed do  
    if conflict then  
      learn()  
      restart()  
    else if unit then propagate()  
    else assign a literal in  $C_i$  to false  
  restart()
```

- ▶ Optimal variable choices
- ▶ Clauses not thrown away
- ▶ Frequent restarts
- ▶ Standard learning

CDCL equivalent to Resolution: Assumptions

```
for  $C_i \in \pi$  do  
  while  $C_i$  not absorbed do  
    if conflict then  
      learn()  
      restart()  
    else if unit then propagate()  
    else assign a literal in  $C_i$  to false  
  restart()
```

- ▶ Optimal variable choices
- ▶ Clauses not thrown away
- ▶ Frequent restarts
- ▶ Standard learning

Assumptions: Branching

Need optimal variable choices.

- ▶ No deterministic algorithm simulates resolution unless FPT hierarchy collapses.
[Alekhovich, Razborov '01]
- ▶ No deterministic algorithm simulates resolution unless $P = NP$.
[Atserias, Müller '19]

Assumptions: Branching

Need optimal variable choices.

- ▶ No deterministic algorithm simulates resolution unless FPT hierarchy collapses.
[Alekhovich, Razborov '01]
- ▶ No deterministic algorithm simulates resolution unless $P = NP$.
[Atserias, Müller '19]
- ▶ CDCL with any static order exponentially worse than resolution.
[Mull, Pang, Razborov '19]
- ▶ CDCL with VSIDS and similar heuristics exponentially worse than resolution.
[V '20]

Simulation Overhead

- ▶ Given formula F and resolution proof of length L , CDCL can reproduce proof in $O(n^4 L)$ steps.

[Pipatsrisawat, Darwiche '09]

[Atserias, Fichte, Thurley '09]

Simulation Overhead

- ▶ Given formula F and resolution proof of length L , CDCL can reproduce proof in $O(n^4 L)$ steps.

[Pipatsrisawat, Darwiche '09]

[Atserias, Fichte, Thurley '09]

- ▶ $O(n^3 L)$

[Beyersdorff, Böhm '21]

Simulation Overhead

- ▶ Given formula F and resolution proof of length L , CDCL can reproduce proof in $O(n^4 L)$ steps.

- ▶ $O(n^3 L)$

- ▶ Theory: Polynomial 😊

- ▶ Practice: But my solver runs in linear time 😞

[Pipatsrisawat, Darwiche '09]

[Atserias, Fichte, Thurley '09]

[Beyersdorff, Böhm '21]

Simulation Overhead

- ▶ Given formula F and resolution proof of length L , CDCL can reproduce proof in $O(n^4 L)$ steps.

[Pipatsrisawat, Darwiche '09]

[Atserias, Fichte, Thurley '09]

- ▶ $O(n^3 L)$

[Beyersdorff, Böhm '21]

- ▶ Theory: Polynomial 😊
- ▶ Practice: But my solver runs in linear time 😞

- ▶ Can we simulate resolution with less overhead?
- ▶ If not, why?

Simulation Overhead

Need linear overhead.

- ▶ Exist formulas with $O(n)$ resolution proofs that require $\Omega(n^2)$ steps in CDCL.

[Fleming, Ganesh, Kolokolova, Li, V]

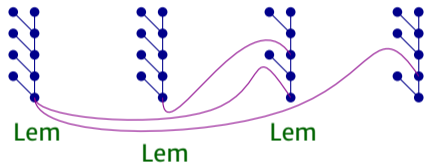
Simulation Overhead

Need linear overhead.

- ▶ Exist formulas with $O(n)$ resolution proofs that require $\Omega(n^2)$ steps in CDCL.
[Fleming, Ganesh, Kolokolova, Li, V]
- ▶ Clauses learned by CDCL have syntactical restrictions
- ▶ Define restricted resolution
- ▶ Prove separation between restricted and general resolution

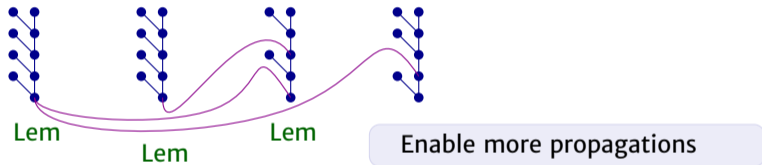
Formalizing CDCL

- ▶ Every resolution proof can be decomposed into a sequence of **input resolution derivations**.
- ▶ The final clause of each derivation is called a **lemma**, and can be **used in future derivations**.



Formalizing CDCL

- ▶ Every resolution proof can be decomposed into a sequence of **input resolution derivations**.
- ▶ The final clause of each derivation is called a **lemma**, and can be **used in future derivations**.

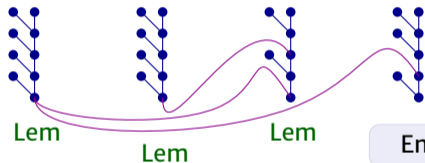


- ▶ Natural restriction: all lemmas must be 1-empowering

Formalizing CDCL

- ▶ Every resolution proof can be decomposed into a sequence of **input resolution derivations**.
- ▶ The final clause of each derivation is called a **lemma**, and can be **used in future derivations**.

A 1-empowering clause contains a merge in its derivation



Enable more propagations

- ▶ Natural restriction: all lemmas must be 1-empowering
- ▶ Finer restriction: all lemmas must be merges

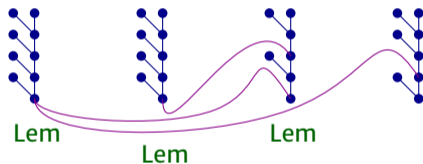
Premises share a literal:
$$\frac{x \vee y \vee z \quad x \vee \bar{z}}{x \vee y}$$

Merge Resolution

Building on [Andrews '68]

Definition

- ▶ Sequence of input resolution derivations
- ▶ Lemmas (reusable clauses) are merges



Properties

- ▶ CDCL produces merge resolution proofs.
- ▶ Merge resolution simulates resolution with $O(n)$ overhead.
- ▶ Exist formulas with $O(n)$ resolution proofs that require $\Omega(n^2)$ merge resolution proofs.

Future: CDCL vs Resolution

Overhead

- ▶ One n explained, n^2 remaining.
- ▶ Are merge resolution proofs easier to simulate by CDCL?
- ▶ Can we improve learning to avoid overhead?

Future: CDCL vs Resolution

Overhead

- ▶ One n explained, n^2 remaining.
- ▶ Are merge resolution proofs easier to simulate by CDCL?
- ▶ Can we improve learning to avoid overhead?

Assumptions

- ▶ Branching
- ▶ Memory
- ▶ Restarts

Future: SAT vs Proof Complexity

Beyond Resolution

- ▶ Preprocessing
- ▶ Parity and pseudoBoolean constraints
- ▶ Symmetry breaking

Future: SAT vs Proof Complexity

Beyond Resolution

- ▶ Preprocessing
- ▶ Parity and pseudoBoolean constraints
- ▶ Symmetry breaking

Beyond Proofs?

- ▶ Satisfiable formulas
- ▶ When is CDCL efficient?

Take Home

- ▶ CDCL needs linear overhead to simulate resolution.

Open Problems

- ▶ Improve or explain remaining overhead.
- ▶ Assumptions needed for simulation.
- ▶ Proof systems beyond resolution.
- ▶ ...

Thanks!